

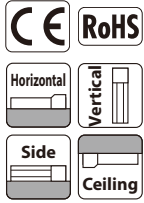
RCP6(S)-WSA14C

±10µm Standard
±5µm High-precision Optional
Simple Dust-proof
Battery-less Absolute
Motor Unit Type
Coupled Motor
Body Width 140mm
24v Stepper Motor

Model Specification Items

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controller/I/O Type	Cable Length	Options
RCP6: Separate Controller RCP6S: Built-in Controller	WSA14C	WA	56P	24: 24mm 16: 16mm 8: 8mm 4: 4mm	50: 50mm 800: 800mm (50mm increments)	[RCP6] P3: PCON MCON MSEL [RCP6S] SE: SIO Type	N : None P : 1m S : 3m M : 5m X□□ : Specified Length R□□ : Robot Cable	Please refer to the options table below.

* RCP6 does not include a controller. RCP6S includes a built-in controller.
* Please refer to P.10 for more information about the model specification items.



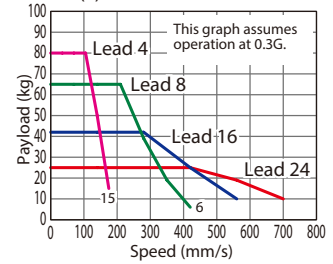
* Depending on the model, there may be some limitations to using the vertical, side, and ceiling mount positions. Please contact IAI for more information regarding mounting positions.



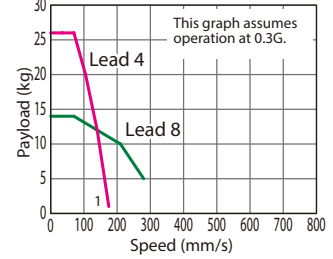
- POINT Selection Notes**
- (1) The maximum acceleration/deceleration is 1G for horizontal, and 0.5G for vertical use.
 - (2) The actuator specification displays the payload's maximum value, but it will vary depending on the acceleration and speed. Please refer to the "Selection Guidelines" (RCP6 Tables of Payload by Speed/Acceleration) on P.115 for more details.
 - (3) When performing push-motion operation, please confirm the push force of each model by checking the "Correlation diagram of push force and current limit" on P.113.
 - (4) Depending on the ambient operational temperature, duty control is necessary for the RCP6S (built-in controller type) with lead 4/8/16. Please refer to P.130 for more information.

Correlation Diagrams of Speed and Payload

High-output enabled with PCON/MCON/MSEL connected.
RCP6(S)-WSA14C Horizontal mount



RCP6(S)-WSA14C Vertical mount



Actuator Specifications

Lead and Payload

Model Number	Lead (mm)	Connected Controller	Max. Payload		Stroke (mm)
			Horizontal (kg)	Vertical (kg)	
RCP6(S)-WSA14C-WA-56P-24-①-②-③-④	24	High-output Enabled	25	-	50~800 (The increment of stroke is 50mm)
RCP6(S)-WSA14C-WA-56P-16-①-②-③-④	16	High-output Enabled	50	-	
RCP6(S)-WSA14C-WA-56P-8-①-②-③-④	8	High-output Enabled	65	14	
RCP6(S)-WSA14C-WA-56P-4-①-②-③-④	4	High-output Enabled	80	26	

Legend: ① Stroke ② Applicable controller/I/O type ③ Cable length ④ Options

Stroke and Max. Speed

(Unit: mm/s)

Lead (mm)	Connected Controller	50~500 (Every 50mm)	550 (mm)	600 (mm)	650 (mm)	700 (mm)	750 (mm)	800 (mm)
24	High-output Enabled	700						665
16	High-output Enabled	560			550	490	440	
8	High-output Enabled	420 <350>	400 <350>	350	305	270	240	215
4	High-output Enabled	210 <175>	200 <175>	170	150	135	120	105

Values in brackets < > are for vertical use.

① Stroke

Stroke (mm)	RCP6	RCP6S	Stroke (mm)	RCP6	RCP6S
50	○	○	450	○	○
100	○	○	500	○	○
150	○	○	550	○	○
200	○	○	600	○	○
250	○	○	650	○	○
300	○	○	700	○	○
350	○	○	750	○	○
400	○	○	800	○	○

④ Options

Name	Option Code	Reference Page
Brake	B	See P.105
Cable exit direction (Top)	CJT	See P.105
Cable exit direction (Right)	CJR	See P.105
Cable exit direction (Left)	CJL	See P.105
Cable exit direction (Bottom)	CJB	See P.105
High-precision specification *	HPR	See P.108
Non-motor end specification	NM	See P.110

* Positioning repeatability is ±5µm for high-precision specification (HPR).

High-precision specification option cannot be selected for lead 16, 24.

When selecting multiple options, please list them in alphabetical order. (e.g. B-CJB-NM)

③ Cable Length

Cable Type	Cable Code	RCP6	RCP6S
Standard	P (1m)	○	○
	S (3m)	○	○
	M (5m)	○	○
Specified Length	X06 (6m) ~X10 (10m)	○	○
	X11 (11m) ~X15 (15m)	○	○
	X16 (16m) ~X20 (20m)	○	○
	R01 (1m) ~R03 (3m)	○	○
Robot Cable	R04 (4m) ~R05 (5m)	○	○
	R06 (6m) ~R10 (10m)	○	○
	R11 (11m) ~R15 (15m)	○	○
	R16 (16m) ~R20 (20m)	○	○

* Please refer to P.144 for more information regarding the maintenance cables.

Actuator Specifications

Item	Description
Drive system	Ball screw φ12mm, rolled C10
Positioning repeatability (*1)	±0.01mm [±0.005mm]
Lost motion	0.1mm or less
Base	Material: Aluminum with white alumite treatment
Static allowable moment	Ma: 462N·m, Mb: 462N·m, Mc: 1,170N·m
Dynamic allowable moment (*2)	Ma: 122N·m, Mb: 122N·m, Mc: 308N·m
Ambient operating temp. & humidity	0~40°C, 85% RH or less (Non-condensing)

* Reference for overhang load length: Ma: 550mm or less, Mb, Mc: 550mm or less

(*1) Values in [] are for high-precision (for lead 4/8) specification.

(*2) Assumes a standard rated life of 5,000km. The service life will vary depending on operation and installation conditions.

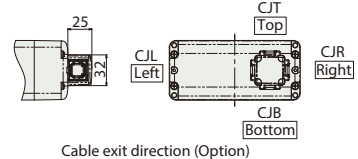
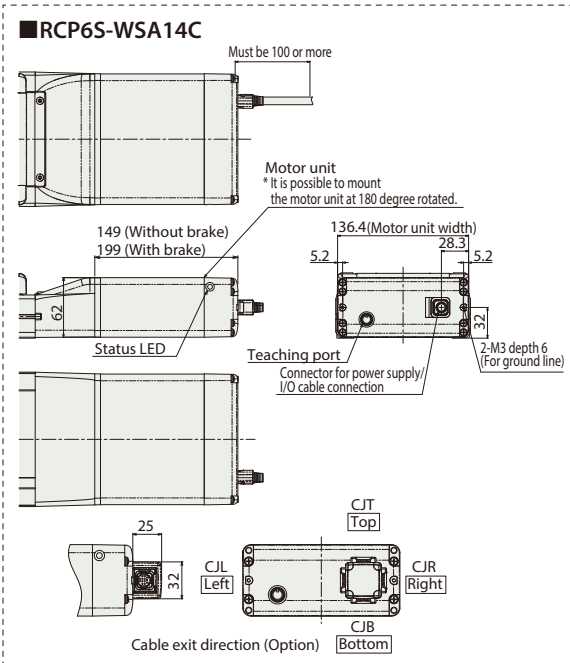
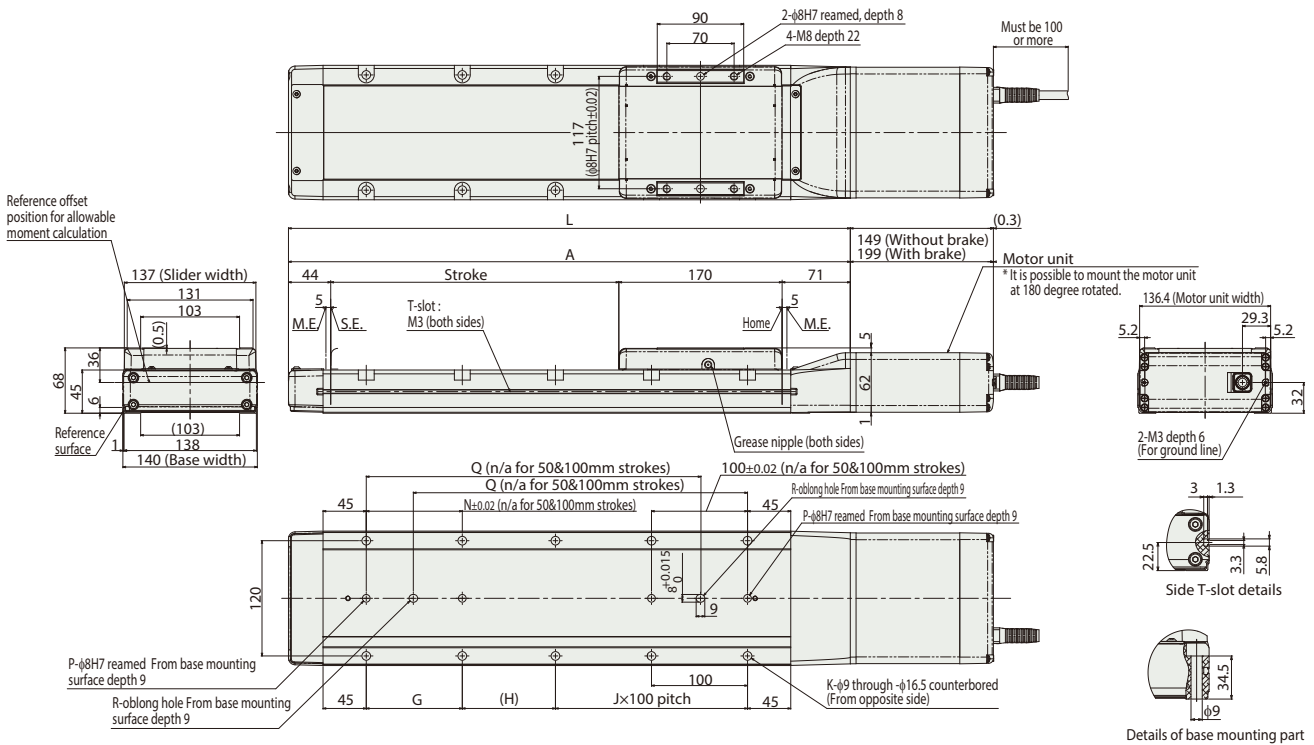
Please refer to our website for more information regarding the directions of the allowable moment and overhang load length.

Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.com



*1 When the slider is returning to its home position, please be careful of interference from surrounding objects, as it will travel until it reaches the M.E.
M.E: Mechanical end S.E: Stroke end



■ Dimensions and Mass by Stroke

Stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	
L	RCP6	w/o brake	484	534	584	634	684	734	784	834	884	934	984	1,034	1,084	1,134	1,184
		w/ brake	534	584	634	684	734	784	834	884	934	984	1,034	1,084	1,134	1,184	1,234
	RCP6S	w/o brake	484	534	584	634	684	734	784	834	884	934	984	1,034	1,084	1,134	1,184
		w/ brake	534	584	634	684	734	784	834	884	934	984	1,034	1,084	1,134	1,184	1,234
A	335	385	435	485	535	585	635	685	735	785	835	885	935	985	1,035	1,085	
G	-	-	100	100	100	100	100	100	100	100	100	100	100	100	100	100	
H	147	197	47	97	47	97	47	97	47	97	47	97	47	97	47	97	
J	0	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7	
K	4	4	8	8	10	10	12	12	14	14	16	16	18	18	20	20	
N	-	-	100	100	100	100	100	100	100	100	100	100	100	100	100	100	
P	1	1	2	2	2	2	2	2	2	2	2	2	2	2	2	2	
Q	-	-	198	248	298	348	398	448	498	548	598	648	698	748	798	848	
R	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	
Mass (kg)	RCP6	w/o brake	6.6	7.0	7.5	8.0	8.5	8.9	9.4	9.9	10.4	10.9	11.3	11.8	12.3	12.8	13.2
		w/ brake	7.0	7.5	8.0	8.5	8.9	9.4	9.9	10.4	10.9	11.3	11.8	12.3	12.8	13.2	13.7
	RCP6S	w/o brake	6.6	7.1	7.6	8.0	8.5	9.0	9.5	9.9	10.4	10.9	11.4	11.9	12.3	12.8	13.3
		w/ brake	7.1	7.6	8.0	8.5	9.0	9.5	9.9	10.4	10.9	11.4	11.8	12.3	12.8	13.3	13.8

② Applicable Controllers

The RCP6 series actuators can be operated by the controllers indicated below. Please select the type depending on your intended use. * Please refer to P.147 for more information about the built-in controller of RCP6S series.

Name	External view	Max. number of controlled axes	Input power	Control method				Maximum number of positioning points	Reference page
				Positioner	Pulse train	Program	Network *Option		
PCON-CB/CGB		1	DC24V	● *Option	● *Option	-	 Note: The type of compatible networks will vary depending on the controller. Please refer to reference page for more information.	512 (768 for network spec.)	Please see P.131
MCON-C/CG		4		This model is network-compatible only.					
MSEL-PC/PG		4	Single-phase 100~230VAC	-	-	●		30,000	Please see the MSEL-PC/PG catalog.

* Please select "high-output specification" as an option for the MCON. With the MCON, operation is possible only when the high-output specification is selected.