

RCP6(S)-RRA6R

Battery-less
AbsoluteMotor
Unit
TypeSide-mounted
MotorBody Width
58*
mm24v
Stepper
MotorModel
Specification
Items

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controller/I/O Type	Cable Length	Options
RCP6: Separate Controller RCP6S: Built-in Controller	RRA6R	WA: Battery-less Absolute	42P: Stepper Motor 42□□ Size	20: 20mm 12: 12mm 6: 6mm 3: 3mm	65: 65mm 415: 415mm (50mm increments)	[RCP6] P3: PCON MCON MSEL [RCP6S] SE: SIO Type	N : None P : 1m S : 3m M : 5m X□□ : Specified Length R□□ : Robot Cable	Please refer to the options table below. *Please make sure to specify either ML or MR when ordering the side- mounted motor type.

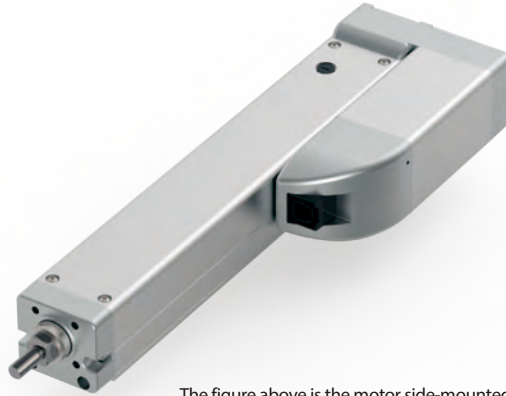
* RCP6 does not include a controller. RCP6S includes a built-in controller.

* Please refer to P.11 for more information about the model specification items.

Radial Load OK



*Depending on the model, there may be some limitations to using the vertical, side, and ceiling mount positions. Please contact IAI for more information regarding mounting positions.



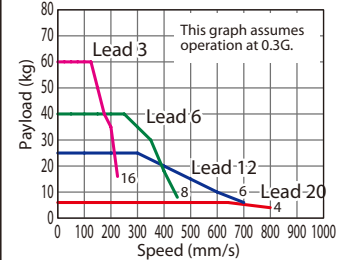
The figure above is the motor side-mounted to the left (ML).



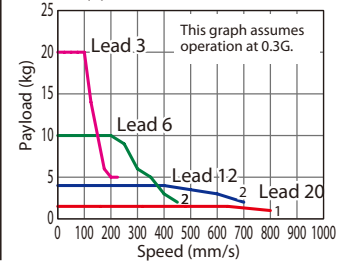
- (1) The maximum acceleration/deceleration is 1G for horizontal, and 0.5G for vertical use.
- (2) The actuator specification displays the payload's maximum value, but it will vary depending on the acceleration and speed. Please refer to the "Selection Guidelines" (RCP6 Tables of Payload by Speed/Acceleration) on P.115 for more details.
- (3) The radial cylinder is equipped with a built-in guide. Please refer to the graphs shown in P.127 and after for the allowable load mass.
- (4) When performing push-motion operation, please confirm the push force of each model by checking the "Correlation diagram of push force and current limit" on P.113.
- (5) Depending on the ambient operational temperature, duty control is necessary for the RCP6S (built-in controller type) with lead 3/6. Please refer to P.130 for more information.

Correlation Diagrams of Speed and Payload

High-output enabled with
PCON/MCON/MSEL connected.
RCP6(S)-RRA6R Horizontal mount



RCP6(S)-RRA6R Vertical mount



Actuator Specifications

Lead and Payload

(Note 1) The payload assumes that there is an external guide.

Model Number	Lead (mm)	Connected Controller	Max. Payload		Stroke (mm)
			Horizontal (kg)	Vertical (kg)	
RCP6(S)-RRA6R-WA-42P-20-①-②-③-④	20	High-output Enabled	6	1.5	65~415 (The increment of stroke is 50mm)
RCP6(S)-RRA6R-WA-42P-12-①-②-③-④	12	High-output Enabled	25	4	
RCP6(S)-RRA6R-WA-42P-6-①-②-③-④	6	High-output Enabled	40	10	
RCP6(S)-RRA6R-WA-42P-3-①-②-③-④	3	High-output Enabled	60	20	

Legend: ① Stroke ② Applicable controller/I/O type ③ Cable length ④ Options

Stroke and Max. Speed

(Unit: mm/s)

Lead (mm)	Connected Controller	65~365 (Every 50mm)	415 (mm)
20	High-output Enabled	800	
12	High-output Enabled	700	
6	High-output Enabled	450	
3	High-output Enabled	225	220

① Stroke

Stroke (mm)	RCP6	RCP6S	Stroke (mm)	RCP6	RCP6S
65	○	○	265	○	○
115	○	○	315	○	○
165	○	○	365	○	○
215	○	○	415	○	○

④ Options

Name	Option Code	Reference Page
Brake	B	See P.105
Cable exit direction (Outside)	CJO	See P.105
Flange	FL	See P.106
Tip adapter (Flange)	FFA	See P.105
Tip adapter (Internal thread)	NFA	See P.109
Tip adapter (Keyway)	KFA	See P.108
Motor side-mounted to the left	ML	See P.109
Motor side-mounted to the right	MR	See P.109
Knuckle joint*	NJ	See P.110
Non-motor end specification	NM	See P.110
Clevis bracket*	QR	See P.111

* The clevis (QR) and knuckle joint (NJ) are sold as a set.

The assembly is to be performed by the customer.

When selecting multiple options, please list them in alphabetical order. (e.g. B-CJB-NM)

③ Cable Length

Cable Type	Cable Code	RCP6	RCP6S
Standard	P (1m)	○	○
	S (3m)	○	○
	M (5m)	○	○
Specified Length	X06 (6m) ~X10 (10m)	○	○
	X11 (11m) ~X15 (15m)	○	○
	X16 (16m) ~X20 (20m)	○	○
	R01 (1m) ~R03 (3m)	○	○
Robot Cable	R04 (4m) ~R05 (5m)	○	○
	R06 (6m) ~R10 (10m)	○	○
	R11 (11m) ~R15 (15m)	○	○
	R16 (16m) ~R20 (20m)	○	○
		○	○

* Please refer to P.144 for more information regarding the maintenance cables.

Actuator Specifications

Item	Description
Drive system	Ball screw φ10mm, rolled C10
Positioning repeatability	±0.01mm
Lost motion	0.1mm or less
Rod	φ25mm Aluminum
Rod non-rotation precision*	0 deg.
Allowable load and torque on rod tip	See P. 127
Rod tip overhang distance	100mm
Ambient operating temp. & humidity	0~40°C, 85% RH or less (Non-condensing)

* Rod's angular displacement in rotational direction with no load applied to the rod.

