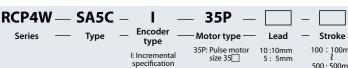
RCP4W-SA5C

ROBO Cylinder Pulse motor

Splash-proof slider type Coupling specification

Actuator width: 55 mm

Model Specification Items



* Also select code "I" for the simple absolute specification.

100 : 100mm 500 : 500mm (Can be set in 50-mm

increments.)

Applicable controller
 controller
 N: None

 P3:PCON/MSEL
 P: 1 m

 P5:RCON/RSEL
 S: 3 m

 M: 5 m
 M: 5 m

Cable length -

- Options Refer to the option list below.

X : Length designation R : Robot cable

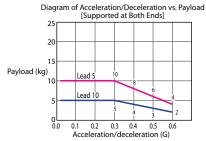


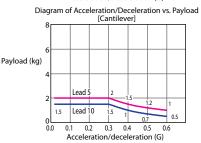
- (1) This actuator is designed exclusively for horizontal installation. It cannot be installed vertically. When hanging the actuator from the ceiling or mounting it on the wall, be sure to do so using an optional dedicated bracket.
- (2) The payload varies depending on the acceleration/deceleration. The upper limit of acceleration/deceleration is 0.6 G.
- (3) The cable joint connector is not splash-proof, so install the connector in a location where it will not come in contact with water.

 (4) Refer to the page at right for the air tube length and air flow rate when implementing air purge.

■ Payload by Acceleration/Deceleration

With the RCP4W series, the payload remains the same even when the speed is raised. However, the payload will drop if the acceleration is raised. Check on the table below.





Actuator Specifications

■ Leads and Payloads

٠.										
	Model number	Lead (mm)	Maximum horizontal payload (kg)		Maximum	Positioning	Stroke			
			Supported on both ends	Cantilever	push force (N)	repeatability (mm)	(mm)			
	RCP4W-SA5C-I-35P-10-①-P3-②-③	10	5	1.5	66.9	+0.02	100 to 500			
	RCP4W-SA5C-I-35P-5-①-P3-②-③	5	10	2	147.9	±0.02	(in 50-mm increments)			

Legend ① Stroke ② Cable length ③ Options

■ Stroke and Maximum Speed

Stroke Lead	100 to 500 (in 50-mm increments)		
10	330		
5	165		

(unit: mm/s)

① Stroke

UStroke	
Stroke (mm)	
100	
150	
200	
250	
300	
350	
400	
450	
500	

③ Options

Name	Option code	See page	
Cable exit from the left side face	A1	→P4	
Cable exit from the right side face	A3	→P4	
Additional alumite coating	AL	→P4	
Designated grease specification	G1/G3/G4	→P4	
Food grade grease (edible grease)	GE	→P4	
Non-motor side specification	NM	→P4	
Ceiling mount (bracket mounted on the left)	HFL	→P4	
Ceiling mount (bracket mounted on the right)	HFR	→P4	
Wall mount sideways on the left	TFL	→P4	
Wall mount sideways on the right	TFR	→P4	

② Cable length

Type	Cable symbol	Standard price
	P(1m)	-
Standard type	S (3m)	-
1	M (5m)	-
	X06(6m) ~ X10 (10m)	-
Special length	X11(11m) ~ X15 (15m)	-
'	X16 (16m) ~ X20 (20m)	-
	R01 (1m) ~ R03 (3m)	-
	R04 (4m) ~ R05 (5m)	-
Robot cable	R06 (6m) ~ R10 (10m)	-
	R11 (11m) ~ R15 (15m)	-
	R16 (16m) ~ R20 (20m)	-

Actuator Specifications

	Item	Description			
Drive system		Ball screw φ8 mm, rolled C10			
Positioning repea	itability	±0.02mm			
Lost motion		0.1 mm or less			
Static allowable	Supported on both ends				
moment	Cantilever	Ma: 2.9 N•m Mb: 4.2 N•m Mc: 6.8 N•m			
Dynamic allowable	Supported on both ends	Ma: 3.4 N•m Mb: 4.9 N•m Mc: 8.0 N•m			
moment (*)	Cantilever	Ma: 1.7 N•m Mb: 2.5 N•m Mc: 4.0 N•m			
Overhang load	Supported on both ends	125mm or less			
length	Cantilever	75 mm or less			
Protective structu		IP65 (with air purge)			
Ambient operating	temperature, humidity	0 to 40°C, 85% RH or less (Non-condensing)			

(*) Based on 5,000 km of traveling life







CAD drawings can be downloaded www.intelligentactuator.com

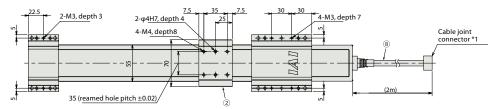


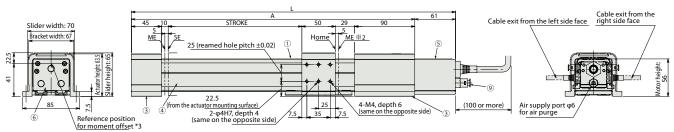
- * See P11 for the dimensional drawing for the ceiling mount specification. See P12 for the dimensional drawing for the wall mount specification.
- *1 Connect the motor and encoder cables.
- *2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.
- *3 Reference position for calculating moments.

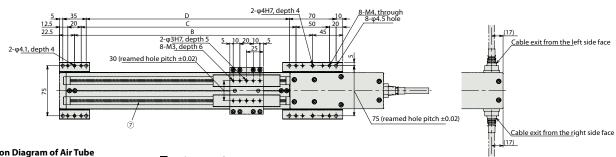
■ Materials of Main Components

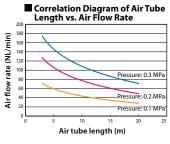
0	Base	Extruded aluminum (A6063)	Surface treatment: Alumite coating
2	Table	Extruded aluminum (A6063)	Surface treatment: Alumite coating (excluding machined areas)
3	Mounting bracket (front/rear)	Extruded aluminum (A6063)	Surface treatment: Alumite coating (excluding machined areas)
4	Side cover	Extruded aluminum (A6063)	Surface treatment: Alumite coating
(5)	Motor cover	Die-cast aluminum (ADC12)	Surface treatment: Alumite coating + Paint
6	Front cover	Die-cast aluminum (ADC12)	Surface treatment: Alumite coating + Paint
0	Seal	Urethane rubber (U)	
8	Actuator cable	Polyvinyl chloride (PVC)	* High flex type cable
9	Air purge joint	Polyphenylene sulfide (PPS)	

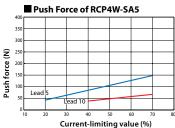
* Alumite coating has been removed in the machined areas of the table ② and mounting bracket ③. To add alumite coating to these areas, specify the "Additional alumite coating (code: AL)" option.











Note on Push-motion Operation

When performing push-motion operation, make sure the reactive moment generated by the push force does not exceed 80% of the dynamic allowable moment (Ma or Mb) specified in the catalog.

In push-motion operation, the travel speed is fixed at 25 mm/s.

- The above correlation diagram assumes an air tube of 6 mm in outer diameter and 4 mm in inner diameter. (A joint of 6 mm in outer diameter is used on the actuator side.)
- Use the correlation diagram as a reference to determine an appropriate pressure and air tube length in such a way that the air flow rate will become 40 NL/min or more (clean dry air).

■ Dimensions and Mass by Stroke

Stroke	100	150	200	250	300	350	400	450	500
L	385	435	485	535	585	635	685	735	785
Α	324	374	424	474	524	574	624	674	724
В	256.5	306.5	356.5	406.5	456.5	506.5	556.5	606.5	656.5
С	221.5	271.5	321.5	371.5	421.5	471.5	521.5	571.5	621.5
D	204	254	304	354	404	454	504	554	604
Mass (kg)	2.8	2.9	3.1	3.2	3.4	3.5	3.7	3.8	4.0

Applicable Controller

* Controller for RCP4W series is PCON, MSEL, RCON or RSEL. Please refer our Controller General Catalog and/or contact IAI.