\* See page Pre-47 for details on the model descriptions

Model Specification Items RCP2 — SRA4R – Type

35P Encoder type — Motor type I: Incremental 35P: Pulse motor, \*The Simple absolute size 35□

encoder is also

considered type "I".

Lead 5: 5mm 2.5: 2.5mm

Stroke 20: 20mm 200: 200mm

(10mm pitch increments) \* 50mm increments over 100mm

Applicable controller Cable length P1: PCON-PL/PO/SE PSEL P3: PCON-CA PMEC/PSEP

MSEP

N: None P: 1m S: 3m \* See options below.

M:5m X□□:Custom length

Options



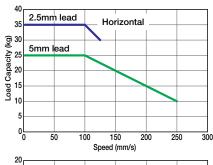
Technical References

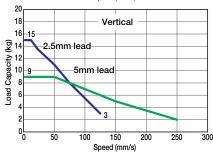
(1) Since the RCP2 series use a pulse motor, the load capacity decreases at high speeds. Check in the Speed vs. Load Capacity graph to see if your desired speed and load capacity are supported.

- (2) The load capacity is based on operation at an acceleration of 0.3G (0.2G is for the 2.5mm-lead model, or when used vertically). This is the upper limit of the acceleration. (3) The horizontal load capacity is based on the use of an external guide. If an external force is exerted on
- the rod from a direction other than the motion of the rod, the detent may become damaged.
- (4) See page A-71 for details on push motion.

### ■ Speed vs. Load Capacity

Due to the characteristics of the pulse motor, the RCP2 series' load capacity decreases at high speeds. In the table below, check if your desired speed and load capacity are supported.





### Actuator Specifications

■ Leads and Payloads (Note 1) Please note that the maximum load capacity decreases as the speed increases. (Note 2) 50mm increments over 100mm. ■ Stroke and Maximum Speed

Model number	Lead	Maximum pa	yload (Note 1)	Max. push	Stroke	
Model number		Horizontal (kg)	Vertical (kg)	force (N)	(mm)	
RCP2-SRA4R-1-35P-5-①-②-③-④	5	~25	~9	112	20 to 200	
RCP2-SRA4R-1-35P-2.5-①-②-③-④	2.5	~35	~15	224	(every 10mm) (Note 2)	

Stroke 5 250

2.5 Legend ① Stroke ② Applicable Controller ③ Cable length ④ Options \*See page A-71 for details on push motion.

(Unit: mm/s)

### ①Stroke (mm) Standard price 25 ~ 50 60 ~ 100 150 200

③Cable Length							
Туре	Cable symbol	Standard price					
Standard type (Robot cable)	<b>P</b> (1m)	_					
	<b>S</b> (3m)	_					
	<b>M</b> (5m)	_					
	<b>X06</b> (6m) ~ <b>X10</b> (10m)	_					
Special length	<b>X11</b> (11m) ~ <b>X15</b> (15m)	_					
	<b>X16</b> (16m) ~ <b>X20</b> (20m)	_					

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- \* The cable is a motor-encoder integrated cable, and is provided as a robot cable.
- \* See page A-59 for cables for maintenance.

# **@Options**

Name	Option code	rage	Standard Frice
Brake	В	→ A-42	_
Flange bracket (front)	FL	→ A-44	_
Flange bracket (rear)	FLR	→ A-46	_
Foot bracket 1 (base mounting)	FT	→ A-48	
Foot bracket 2 (right/left side mounting)	FT2/FT4	→ A-48	_
Non-motor end specification	NM	→ A-52	_

* The brake is available for strokes of 70mm of	or more.

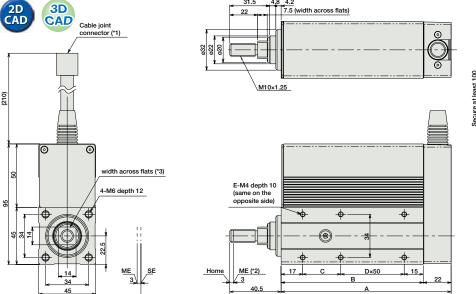
Actuator Specifications	
ltem	Description
Drive method	Ball screw, ø8mm, rolled C10
Positioning repeatability	±0.02mm
Lost motion	0.1mm or less
Rod diameter	ø22mm
Rod non-rotation precision	_
Ambient operating temperature/humidity	0 to 40°C, 85% RH max. (Non-condensing)

Dimensional Drawings

## www.intelligentactuator.com

For Special Orders





Secure at least 100 0 0 4-M6 depth 12 (E 0

\* The exterior dimensions for the brake-equipped model is no different than the standard model. However, 70mm is the minimum stroke of the brake-equipped models. (i.e. The brake is not compatible at 60mm strokes and under.) E-M4 depth 10 φ ф D×50

Dimensions of the Supplied Nut

M10×1.25

ST : Stroke SE : Stroke end ME: Mechanical end

Note: -Do not apply any external force on the rod from any direction other than the direction of the rod's motion. If a force is exerted on the rod in a perpendicular or rotational direction, the detent may become damaged.

(\*1) Connect the motor-encoder integrated cable here. (See page A-59 for details on cables.)

(\*2) During home return, be careful to avoid interference from peripheral objects because the rod moves until the mechanical end.
(\*3) The orientation of the bolt varies depending on the product.

### ■ Dimensions and Weights by Stroke (Add 0.2kg for brake equipped)

Stroke	20	30	40	50	60	70	80	90	100	150	200
L	124.5	134.5	144.5	154.5	164.5	174.5	184.5	194.5	204.5	254.5	304.5
Α	84	94	104	114	124	134	144	154	164	214	264
В	62	72	82	92	102	112	122	132	142	192	242
С	30	40	50	60	70	30	40	50	60	60	60
D	0	0	0	0	0	1	1	1	1	2	3
E	4	4	4	4	4	6	6	6	6	8	10
Weight (kg)	0.83	0.89	0.96	1.02	1.08	1.14	1.21	1.27	1.33	1.64	1.95

### ②Applicable Controllers \*Please contact IAI for latest controllers/information.

Name	External view	Model number	Features	Maximum number of positioning points	Input power	Power-supply capacity	Standard price	Reference page			
Calcari IVI a Tara	100	PMEC-C-35PI-①-2-⑪	MEC-C-35PI-①-2-① Easy-to-use controller, even for beginners		AC100V AC200V	Refer to P541	_	→ P537			
Solenoid Valve Type	1	PSEP-C-35PI-①-2-0	Simple controller operable with the same signal as a solenoid valve	3 points		Refer to P555	_	→ P547			
Solenoid valve multi-axis type PIO specification	lun*	MSEP-C	Positioner type based on PIO control, allowing up to 8 axes to be connected			Refer to	_	→ P563			
Solenoid valve multi-axis type Network specification		MSEP-C	Field network-ready positioner type, allowing up to 8 axes to be connected	256 points		P572					
Positioner type High-output specification	100	PCON-CA-35PI-①-2-0	Equipped with a high-output driver Positioner type based on PIO control	512 points			_				
Pulse-train type High-output specification				1	PCON-CA-35PI-PL□-2-0	Equipped with a high-output driver Pulse-train input type	(—)	DC24V	Refer to P618	_	→ P607
Field network type High-output specification		PCON-CA-35PI-W-0-0	Equipped with a high-output driver Supporting 7 major field networks	768 points	DC24V		_				
Pulse Train Input Type (Differential Line Driver)	C	PCON-PL-35PI-①-2-0	Pulse train input type with differential line driver support	(—)			_	→ P623			
Pulse Train Input Type (Open Collector)		PCON-PO-35PI-①-2-0	Pulse train input type with open collector support	(—)		Refer to P628	_				
Serial Communication Type		PCON-SE-35PI-N-0-0	Dedicated Serial Communication	64 points			_				
Program Control Type		PSEL-CS-1-35PI-①-2-0	Programmed operation is possible. Can operate up to 2 axes	1,500 points		Refer to P671	_	→ P665			

\*This is for the single-axis PSEL. \* ⊕ indicates I/O type (NP/PN). \* ⊕ indicates power supply voltage (1:100V / 2:100~240V). \* ⊕ indicates number of axes (1 to 8). \* ⊕ indicates field network specification symbol. \* □ indicates N (NPN specification) or P (PNP specification) symbol.

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<sup>\*</sup>Please contact IAI for latest controllers/information.