

Model/Specification

		Motor	out Lead Stroke						Acceleration (Note 1)			Payload capacity (Note 1 & 2)			
Model	Encoder Type	Encoder Output			I (mm/s)	Horizontal (G) Vertical (G)		Horizontal (kg)		Vertical (kg)		Rated Thrust (N)			
	(W)	(W)				Rated Maximum	Rated	Maximum	Rated Acceleration	Maximum Acceleration	Rated Acceleration	Maximum Acceleration	(,		
NS-MZMS-@-200-20-@-T2-@-AQ-@-RT	Absolute Incremental	200	20	500~800	1000	Vertical Only	0.3	0.5	Vertica	l Only	6	3	170.9		

*In the model above, ①indicates the type of encoder, ②indicates the stroke, ③indicates the cable length, and ④indicates the option.

Option

Name	Model Reference page		Note		
AQ Seal	AQ	→P5	Standard Equipment		
Brake (*)	В	→P5	Standard Equipment		
Installation Direction of Standard Cable Track	CT1~CT4	→P5	Enter CT1 for standard installation		
Guide with Ball-Retaining Mechanism	RT	→P6	Standard Equipment		

(*) A brake box is attached for powering the brake.

(For details, see page 21)

Common specifications

Driving Method	Ball Thread, Diameter φ16 mm, Equivalent to Rolled C5			
Repeated Positioning Accuracy	+/- 0.01 mm			
Backlash	0.02 mm or less			
Guide	Integrated to Base			
Dynamic Allowable Moment (Note 3)	Ma: 69.6N·m, Mb: 99.0N·m, Mc: 81.3N·m			
Overhung load length	Ma Direction: 600mm or less; Mb and Mc Direction: 600mm or less			
Base	Material: Aluminium, White Alumite Treatment			
Cable Length (Note 4)	4) N: No cable; S: 3 m; M: 5 m; X□□: Length specified			
Ambient Temperature	bient Temperature 0~40 degrees Celsius, 85% RH or less (No condensation)			

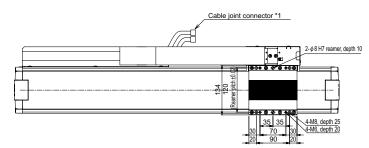
Dimensional drawing

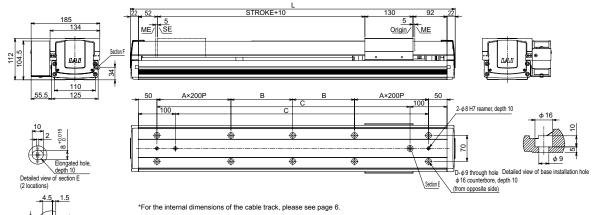




*1 Connects motor cables and encoder cables. For details on cables, please see page 22.

SE: Stroke End ME: Mechanical End





Detailed view of section F (T-slot in base)

Stroke	500	600	700	800	
L	828	928	1028	1128	
Α	1	1	1	1	
В	142	192	242	292 934	
С	634	734	834		
D	10	10	10	10	
Mass (kg)	13.5	14.8	16.0	17.2	

Applicable Controller Specifications

Applicable Controller	Max. Number of Axes Controlled	Compatible Encoder Type	Operation Method	Power/ Voltage						
X-SEL-P/Q	6 axis		Programs	Three-Phase/ Single-Phase 200VAC						
SSEL	2 axis	Absolute/ Incremental	Programs	Single- Phase						
SCON	1 axis		Positioner Pulse Train Control							



(Note 1) For the relationship between acceleration and payload capacity, see page 4. (Note 2) The values shown are payload capacities during operation at maximum speed. (Note 3) For a 10,000-km running life.

(Note 4) The maximum cable length is 30 m. Please specify length in meters. (E.g., X08 = 8 m)