

# NS-MXMXS

Single-Axis Robot Medium Nut Rotation Type Main Unit Width 125mm 200W  
Horizontal Type With Mid-Support Single Slider



Model **NS — MXMXS —**  **200** —  —  — **T2** —  — **AQ** —  — **RT**

Series Type Encoder Type Motor Type Lead Stroke Applicable controller Cable Length Option  
 A: Absolute Motor Type 200: 200W 30: 30mm 1600: 1,600mm T2: SCON N: No  
 I: Incremental 20: 20mm 2200: 2,200mm SSEL S: 3m  
 XSEL-P/Q M: 5m  
 X□□: Length Specified  
 See the options table below

## Model/Specification

Model	Encoder Type	Motor Output (W)	Lead (mm)	Stroke (mm)	Speed (mm/s)	Acceleration (Note 1)				Payload capacity (Note 1 & 2)				Rated Thrust (N)
						Horizontal (G)		Vertical (G)		Horizontal (kg)		Vertical (kg)		
						Rated	Maximum	Rated	Maximum	Rated Acceleration	Maximum Acceleration	Rated Acceleration	Maximum Acceleration	
NS-MXMXS- <input type="checkbox"/> -200-30- <input type="checkbox"/> -T2- <input type="checkbox"/> -AQ- <input type="checkbox"/> -RT	Absolute	200	30	1600-2200	1800	0.3	Horizontal Only	25	Horizontal Only	113.9				
													Incremental	20

\*In the model above,  indicates the type of encoder,  indicates the stroke,  indicates the cable length, and  indicates the option.

## Option

Name	Model	Reference page	Note
AQ Seal	AQ	→P5	Standard Equipment
Installation Direction of Standard Cable Track	CT1~CT4	→P5	Enter CT1 for standard installation
Guide with Ball-Retaining Mechanism	RT	→P6	Standard Equipment

## Common specifications

Driving Method	Ball Thread, Diameter $\phi 16$ mm, Equivalent to Rolled C5
Repeated Positioning Accuracy	+/- 0.01 mm
Backlash	0.02 mm or less
Guide	Integrated to Base
Dynamic Allowable Moment (Note 3)	Ma: 69.6N·m, Mb: 99.0N·m, Mc: 161.7N·m
Overhung load length	Ma Direction: 600mm or less; Mb and Mc Direction: 600mm or less
Base	Material: Aluminium, White Alumite Treatment
Cable Length (Note 4)	N: No cable; S: 3 m; M: 5 m; X□□: Length specified
Ambient Temperature	0~40 degrees Celsius, 85% RH or less (No condensation)

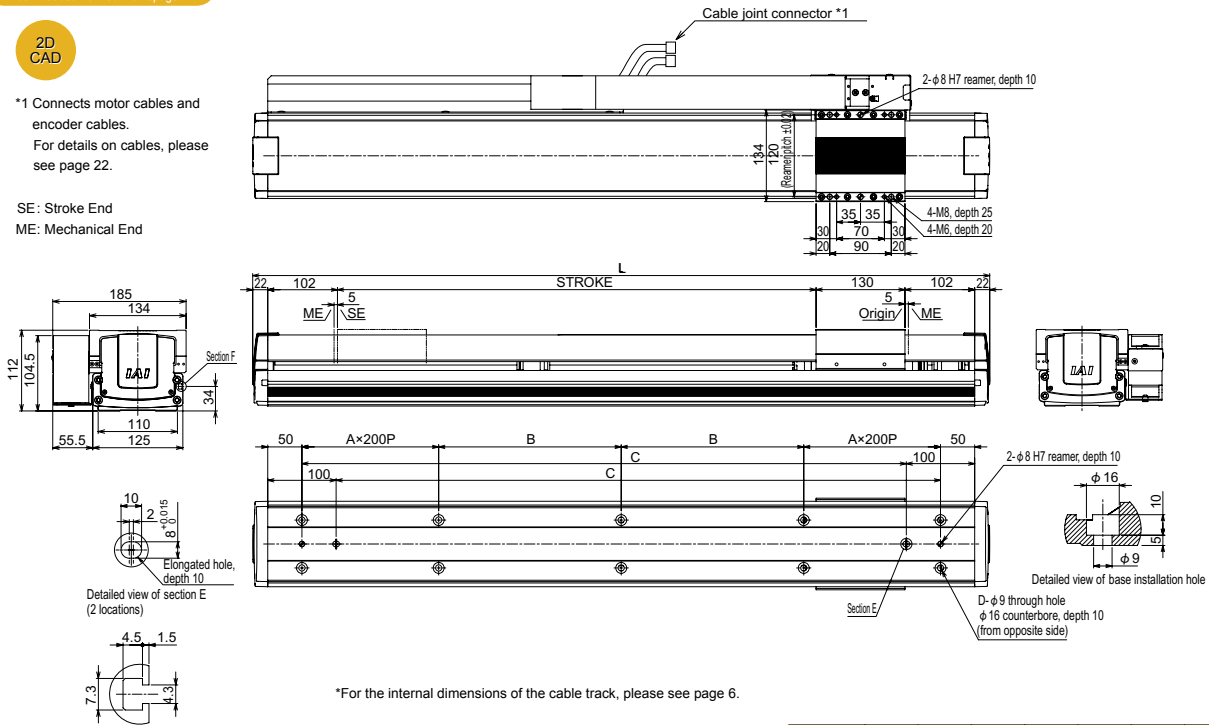
## Dimensional drawing

The CAD drawings can be downloaded from our homepage.

2D CAD

\*1 Connects motor cables and encoder cables.  
For details on cables, please see page 22.

SE: Stroke End  
ME: Mechanical End



Detailed view of section F (T-slot in base)

Note: Due to their structure, models with a mid-support cannot be positioned horizontally on their side or vertically.

Stroke	1600	1700	1800	1900	2000	2100	2200
L	1978	2078	2178	2278	2378	2478	2578
A	3	4	4	4	4	5	5
B	317	167	217	267	317	167	217
C	1784	1884	1984	2084	2184	2284	2384
D	18	22	22	22	22	26	26
Mass (kg)	26.2	27.5	28.7	29.9	31.2	32.4	33.6

## Applicable Controller Specifications

Applicable Controller	Max. Number of Axes Controlled	Compatible Encoder Type	Operation Method	Power/Voltage
X-SEL-P/Q	6 axis	Absolute/ Incremental	Programs Positioner Pulse Train Control	Three-Phase/ Single-Phase 200VAC
SSEL	2 axis			Single-Phase
SCON	1 axis			100/200VAC



Note

(Note 1) The maximum acceleration is 0.3 G.  
 (Note 2) The values shown are payload capacities during operation at maximum speed.  
 (Note 3) For a 10,000-km running life.  
 (Note 4) The maximum cable length is 30 m. Please specify length in meters. (E.g., X08 = 8 m)  
 (Note 5) When an axis with a long stroke (1,300 mm or more) is used hanging from the ceiling, the cover of the body may hang down and contact the slider. Therefore, in cases of such use, please contact our sales representative in advance.