

NS-MXMS

Single-Axis Robot Medium Nut Rotation Type Main Unit Width 125mm 200W
Horizontal Type Single Slider



■Model **NS** — **MXMS** — — **200** — — — **T2** — — **AQ** — — **RT**

Series Type Encoder Type Motor Type Lead Stroke Applicable controller Cable Length Option
 A: Absolute 200: 200W 30: 30mm 500: 500mm T2: SCON N: No See the options table below
 I: Incremental 20: 20 mm SSEL S: 3m M: 5m
 X□□: Length Specified

Model/Specification

Model	Encoder Type	Motor Output (W)	Lead (mm)	Stroke (mm)	Speed (mm/s)	Acceleration (Note 1)				Payload capacity (Note 1 & 2)				Rated Thrust (N)
						Horizontal (G)		Vertical (G)		Horizontal (kg)		Vertical (kg)		
						Rated	Maximum	Rated	Maximum	Rated	Maximum	Rated	Maximum	
NS-MXMS- <input type="checkbox"/> -200-30- <input type="checkbox"/> -T2- <input type="checkbox"/> -AQ- <input type="checkbox"/> -RT	Absolute	200	30	500~1500	1800	0.3	1.0	Horizontal Only		25	0.5	Horizontal Only		113.9
NS-MXMS- <input type="checkbox"/> -200-20- <input type="checkbox"/> -T2- <input type="checkbox"/> -AQ- <input type="checkbox"/> -RT	Incremental		20		1200	0.3	0.8			40	2.5			170.9

*In the model above, indicates the type of encoder, indicates the stroke, indicates the cable length, and indicates the option.

Option

Name	Model	Reference page	Note
AQ Seal	AQ	→P5	Standard Equipment
Installation Direction of Standard Cable Track	CT1~CT4	→P5	Enter CT1 for standard installation
Guide with Ball-Retaining Mechanism	RT	→P6	Standard Equipment

Common specifications

Driving Method	Ball Thread, Diameter ϕ 16 mm, Equivalent to Rolled C5
Repeated Positioning Accuracy	\pm 0.01 mm
Backlash	0.02 mm or less
Guide	Integrated to Base
Dynamic Allowable Moment (Note 3)	Ma: 69.6N·m, Mb: 99.0N·m, Mc: 161.7N·m
Overhung load length	Ma Direction: 600mm or less; Mb and Mc Direction: 600mm or less
Base	Material: Aluminium, White Alumite Treatment
Cable Length (Note 4)	N: No cable; S: 3 m; M: 5 m; X□□: Length specified
Ambient Temperature	0~40 degrees Celsius, 85% RH or less (No condensation)

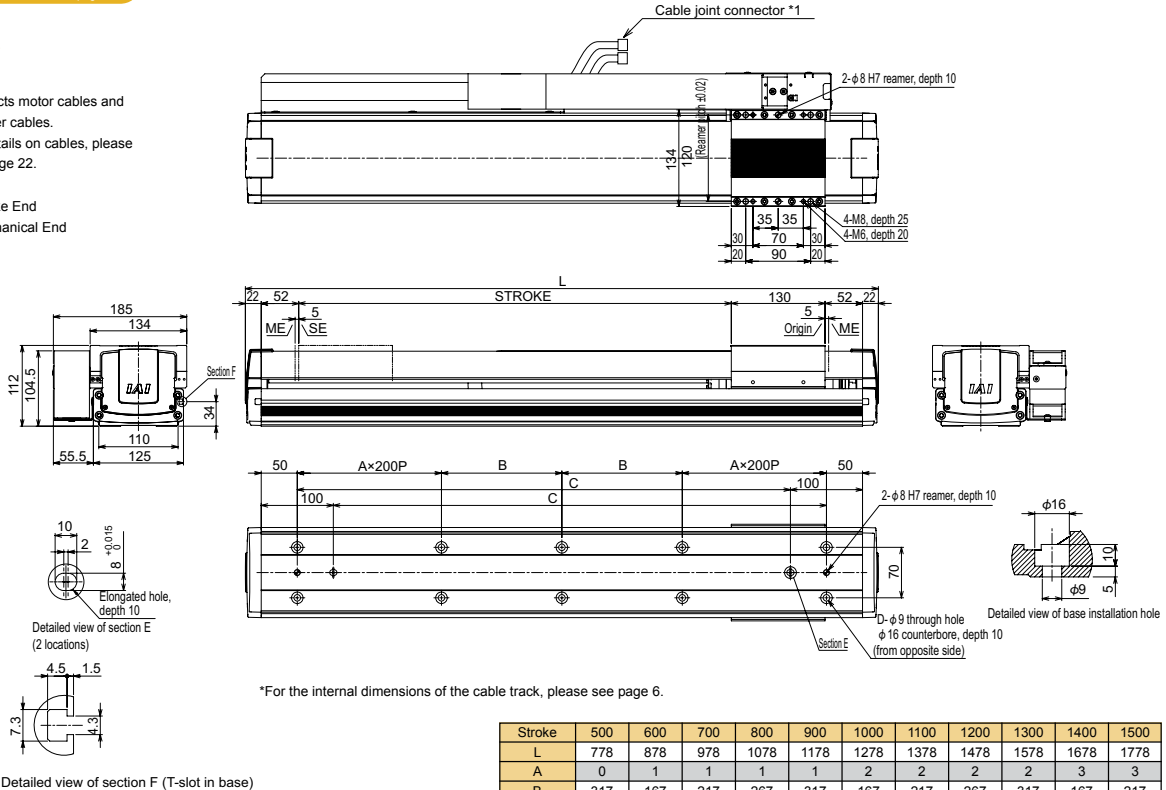
Dimensional drawing

The CAD drawings can be downloaded from our homepage.

2D CAD

*1 Connects motor cables and encoder cables.
For details on cables, please see page 22.

SE: Stroke End
ME: Mechanical End



*For the internal dimensions of the cable track, please see page 6.

Stroke	500	600	700	800	900	1000	1100	1200	1300	1400	1500
L	778	878	978	1078	1178	1278	1378	1478	1578	1678	1778
A	0	1	1	1	1	2	2	2	2	3	3
B	317	167	217	267	317	167	217	267	317	167	217
C	584	684	784	884	984	1084	1184	1284	1384	1484	1584
D	6	10	10	10	10	14	14	14	14	18	18
Mass (kg)	11.9	13.1	14.4	15.6	16.8	18.0	19.3	20.5	21.7	23.0	24.2

Applicable Controller Specifications

Applicable Controller	Max. Number of Axes Controlled	Compatible Encoder Type	Operation Method	Power/Voltage
X-SEL-P/Q	6 axis	Absolute/Incremental	Programs	Three-Phase/Single-Phase 200V AC
SSEL	2 axis		Positioner Pulse Train Control	Single-Phase 100/200VAC
SCON	1 axis			



Note

(Note 1) For the relationship between acceleration and payload capacity, see page 4.
 (Note 2) The values shown are payload capacities during operation at maximum speed.
 (Note 3) For a 10,000-km running life.
 (Note 4) The maximum cable length is 30 m. Please specify length in meters. (E.g., X08 = 8 m)
 (Note 5) When an axis with a long stroke (1,300 mm or more) is used hanging from the ceiling, the cover of the body may hang down and contact the slider. Therefore, in cases of such use, please contact our sales representative in advance.