

NS-MXMM

Single-Axis Robot Medium Nut Rotation Type Main Unit Width 125mm 200W
Horizontal Type Multi-Slider

Model: **NS** - **MXMM** - - **200** - - - **T2** - - **AQ** - **CT1** - **RT**

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable controller	Cable Length	Option
A: Absolute I: Incremental	200: 200W	30: 30mm 20: 20mm	300: 300mm 1500: 1,500mm	T2: SCON SSEL XSEL-P/Q	N: No S: 3m M: 5m X□: Length Specified			See the options table below



Model/Specification

Model	Encoder Type	Motor Output (W)	Lead (mm)	Stroke (mm)	Speed (mm/s)	Acceleration (Note 1)				Payload capacity (Note 1 & 2)				Rated Thrust (N)
						Horizontal (G)		Vertical (G)		Horizontal (kg)		Vertical (kg)		
						Rated	Maximum	Rated	Maximum	Rated	Maximum	Rated	Maximum	
NS-MXMM- -200-30- -T2- -AQ- -RT	Absolute	200	30	300~1500	1800	0.3	1.0	Horizontal Only		25	0.5	Horizontal Only		113.9
NS-MXMM- -200-20- -T2- -AQ- -RT	Incremental		20		1200	0.3	0.8			40	2.5			170.9

*In the model above, indicates the type of encoder, indicates the stroke, indicates the cable length, and indicates the option.

Option

Name	Model	Reference page	Note
AQ Seal	AQ	→P5	Standard Equipment
Installation Direction of Standard Cable Track	CT1	→P5	CT1 for standard
Guide with Ball-Retaining Mechanism	RT	→P6	Standard Equipment

Common specifications

Driving Method	Ball Thread, Diameter φ16 mm, Equivalent to Rolled C5
Repeated Positioning Accuracy	+/- 0.01 mm
Backlash	0.02 mm or less
Guide	Integrated to Base
Dynamic Allowable Moment (Note 3)	Ma: 69.6N·m, Mb: 99.0N·m, Mc: 161.7N·m
Overhung load length	Ma Direction: 600mm or less; Mb and Mc Direction: 600mm or less
Base	Material: Aluminium, White Alumite Treatment
Cable Length (Note 4)	N: No cable; S: 3 m; M: 5 m; X□: Length specified
Ambient Temperature	0~40 degrees Celsius, 85% RH or less (No condensation)

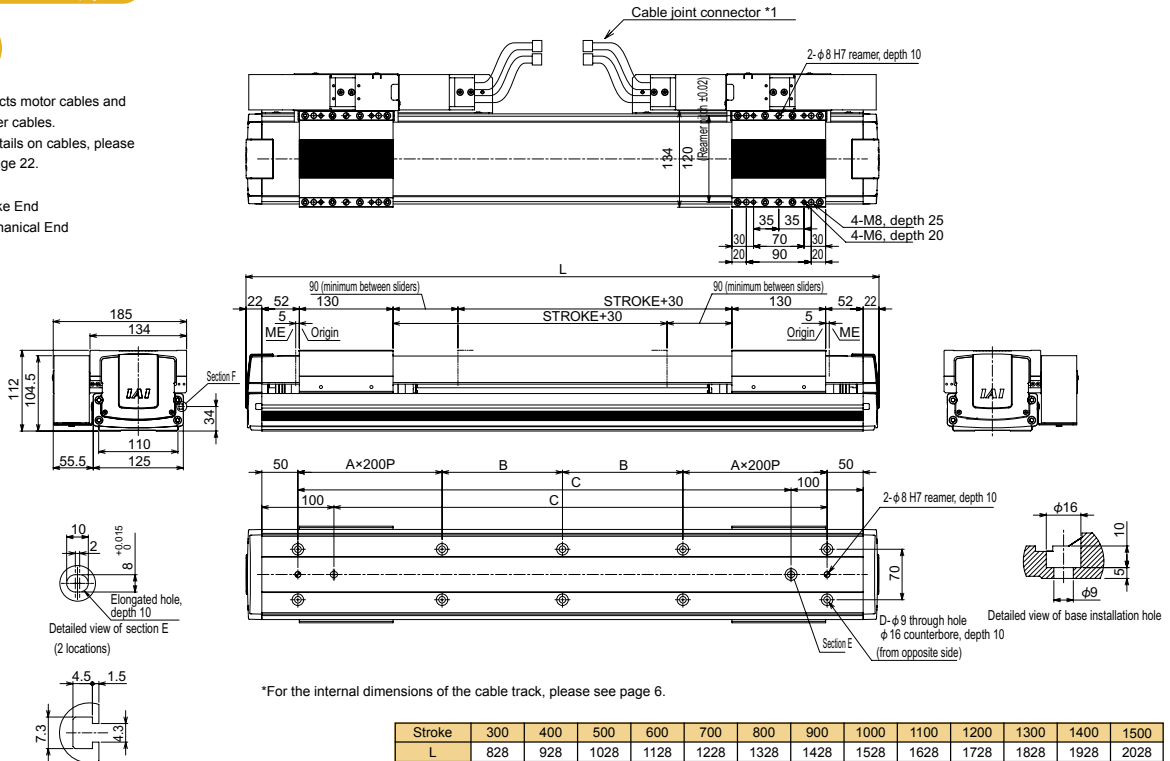
Dimensional drawing

The CAD drawings can be downloaded from our homepage.

2D CAD

*1 Connects motor cables and encoder cables.
For details on cables, please see page 22.

SE: Stroke End
ME: Mechanical End



Stroke	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500
L	828	928	1028	1128	1228	1328	1428	1528	1628	1728	1828	1928	2028
A	1	1	1	1	2	2	2	2	3	3	3	3	4
B	142	192	242	292	142	192	242	292	142	192	242	292	142
C	634	734	834	934	1034	1134	1234	1334	1434	1534	1634	1734	1834
D	10	10	10	10	14	14	14	14	18	18	18	18	22
Mass (kg)	15.6	16.8	18	19.2	20.5	21.7	22.9	24.2	25.4	26.6	27.9	29.1	30.3

Applicable Controller Specifications

Applicable Controller	Max. Number of Axes Controlled	Compatible Encoder Type	Operation Method	Power/Voltage
X-SEL-P/Q	6 axis	Absolute/ Incremental	Programs	Three-Phase/ Single-Phase 200VAC
SSEL	2 axis		Positioner Pulse Train Control	Single-Phase 100/200VAC
SCON	1 axis			

Note: A two-axis controller is required to operate the multi-slider.
Two controllers are required for SCON.
(Please note that SCON does not have a collision prevention mechanism)



Note

(Note 1) For the relationship between acceleration and payload capacity, see page 4.
(Note 2) The values shown are payload capacities during operation at maximum speed.
(Note 3) For a 10,000-km running life.
(Note 4) The maximum cable length is 30 m. Please specify length in meters.
(E.g., X08 = 8 m)
(Note 5) When an axis with a long stroke (1,300 mm or more) is used hanging from the ceiling, the cover of the body may hang down and contact the slider. Therefore, in cases of such use, please contact our sales representative in advance.