

Model/Specification

Model	Encoder Type Motor Output (W)	Motor				Acceleration (Note 1)			Payload capacity (Note 1 & 2)				
		Output	Lead (mm)	Stroke (mm)	(mm/s)	Horizontal (G) Vertical (G)		Horizontal (kg) Vert		Vertica	al (kg)	Rated Thrust (N)	
		(W)				Rated Maximum	Rated	Maximum	Rated Acceleration	Maximum Acceleration	Rated Acceleration	Maximum Acceleration	(-1)
NS-LZMS	Absolute Incremental	400	20	500~1000	1000	Vertical Only	0.3	0.8	Vertica	al Only	16	6.0	340.1

^{*}In the model above, ①indicates the type of encoder, ②indicates the stroke, ③indicates the cable length, and ④indicates the option.

Option

Model	Reference page	Note
AQ	→P5	Standard Equipment
В	→P5	Standard Equipment
С	→P5	
CT1~CT4	→P5	Enter CT1 for standard installation
ET1~ET4	→P5	
L	→P6	
RT	→P6	Standard Equipment
	AQ B C CT1~CT4 ET1~ET4 L	AQ →P5 B →P5 C →P5 CT1-CT4 →P5 ET1-ET4 →P6

^(*) A brake box is attached for powering the brake. (For details, see page 21)

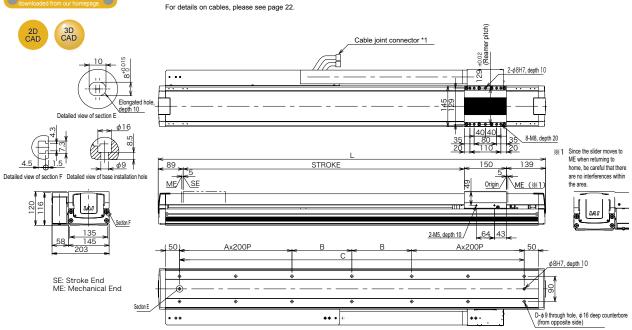
Common specifications

Driving Method	Ball Thread, Diameter φ20 mm, Equivalent to Rolled C5				
Repeated Positioning Accuracy	±0.01mm				
Backlash	0.02 mm or less				
Guide	Integrated to Base				
Dynamic Allowable Moment (Note 3)	Ma: 104.9N·m; Mb: 149.9N·m; Mc: 248.9N·m				
Overhung load length	Ma Direction: 750 mm or less; Mb and Mc Direction: 750 mm or less				
Brake	Non-excitation electromagnetic brakes are installed as standard equipment				
Base	Material: Aluminium, White Alumite Treatment				
Cable Length (Note 4)	N: No cable; S: 3 m; M: 5 m; X□□: Length specified				
Ambient Temperature	0~40 degrees Celsius, 85% RH or less (No condensation)				

Dimensional drawing



*1 Connects motor cables and encoder cables



*For the internal dimensions of the cable track, please see page 6.

Stroke	500	600	700	800	900	1000
L	878	978	1078	1178	1278	1378
Α	1	1	1	2	2	2
В	163	213	263	113	163	213
С	726	826	926	1026	1126	1226
D	10	10	10	14	14	14
Mass (kg)	19.9	21.4	22.9	24.4	25.9	27.4

Applicable Controller Specifications

Applicable Controller	Max. Number of Axes Controlled	Compatible Encoder Type	Operation Method	Power/ Voltage	
X-SEL-P/Q	6 axis		Programs	Three-Phase/ Single-Phase 200VAC	
SSEL	2 axis	Absolute/ Incremental	Programs	Single- Phase	
SCON	1 axis		Positioner Pulse Train Control		



(Note 1) For the relationship between acceleration and payload capacity, see page 4.

(Note 2) The values shown are payload capacities during operation at maximum speed.

(Note 3) For a 10,000-km running life.

(Note 4) The maximum cable length is 30 m. Please specify length in meters. (E.g., X08 = 8 m)