

LSA-S10HM

Shaft type, 100 mm wide
High-thrust type, multi-slider



■ Model Name **LSA-S10HM-I-200-□-T2-□-□**
 Series — Type — Encoder type — Applicable drive output — Stroke — Applicable controller — Cable length — Options

I: Incremental specification 200 : 105:105mm 200W }
 T2 : N: None S: 3m M: 5m Refer to the options table below.
 SCON SSEL XSEL-P/-Q X□□:

* Refer to P. 13 for details on each item comprising the model name. 1815:1815mm

Model Specifications

Model	Encoder type	Applicable drive output (per slider)	Stroke Specified in 90-mm steps (mm)	Speed (Note 1) (mm/sec)	Payload (Note 2)		Rated thrust (N)	Maximum thrust (N)	Maximum acceleration (G) (Note 2)
					Horizontal (kg)	Vertical (kg)			
LSA-S10HM-I-200-□-T2-□-□	I: Incremental	200	105-1815	2500	20	-	80	320	3

* In the above model names, □ indicates the stroke, □ indicates the cable length, and □ indicates the options.

Options

Name	Model	Reference page	Remarks
Cable track installation direction	CT5	→P14	Sideway specification
Cable track for user wiring, type S	US1/US5	→P14	Standard specification/sideway specification
Cable track for user wiring, type M	UM1/UM5	→P14	Standard specification/sideway specification

(Note) To change the cable track position to the opposite side, install the actuator by rotating it 180 degrees horizontally because the actuator is bilaterally symmetrical.

Common Specifications

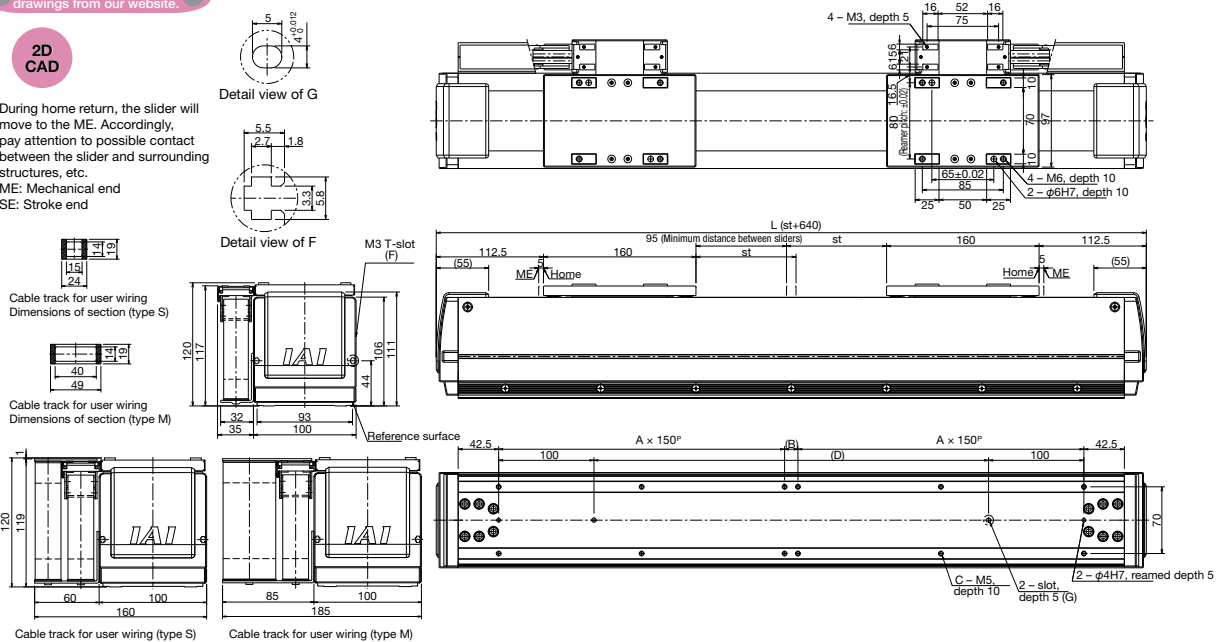
Drive method	Linear servo motor
Positioning repeatability	±0.005mm
Guide	Built-in linear guide
Permissible load moment	Ma: 57.4N • m Mb: 81.9 • m Mc: 60.8N • m
Overhang load length	300 mm or less in Ma direction / 300 mm or less in Mb/Mc directions
Base	Material: Aluminum with white alumite treatment
Applicable controller	T2: SCON, SSEL, XSEL-P/Q
Cable length (Note 3)	N: No Cable S: 3m M: 5m X□□: Specified length
Ambient operating temperature	0 to 40°C, 85% RH or below (non-condensing)

Dimensions

You can download CAD drawings from our website.

2D CAD

*1 During home return, the slider will move to the ME. Accordingly, pay attention to possible contact between the slider and surrounding structures, etc.
 ME: Mechanical end
 SE: Stroke end



Stroke	105	195	285	375	465	555	645	735	825	915	1005	1095	1185	1275	1365	1455	1545	1635	1725	1815
L	745	835	925	1015	1105	1195	1285	1375	1465	1555	1645	1735	1825	1915	2005	2095	2185	2275	2365	2455
A	2	2	2	2	3	3	3	4	4	4	5	5	5	5	6	6	6	7	7	7
B	14	104	194	284	74	164	254	44	134	224	14	104	194	284	74	164	254	44	134	224
C	12	12	12	12	16	16	16	20	20	20	24	24	24	24	28	28	28	32	32	32
D	414	504	594	684	774	864	954	1044	1134	1224	1314	1404	1494	1584	1674	1764	1854	1944	2034	2124
Weight(kg)	15.6	16.4	17.3	18.1	18.9	19.8	20.6	21.4	22.3	23.1	23.9	24.8	25.6	26.4	27.3	28.1	28.9	29.8	30.6	31.4

Applicable Controller Specifications

Applicable controller	Maximum controlled axes	Operating method	Power-supply voltage	Reference page
XSEL	6 axes	Program	Single-phase/ three-phase AC 200 V	→P53
SSEL	2 axes	Program/positioner	Single-phase AC100/200V	→P52
SCON	1 axis	Pulse train/positioner	Single-phase AC100/200V	→P51



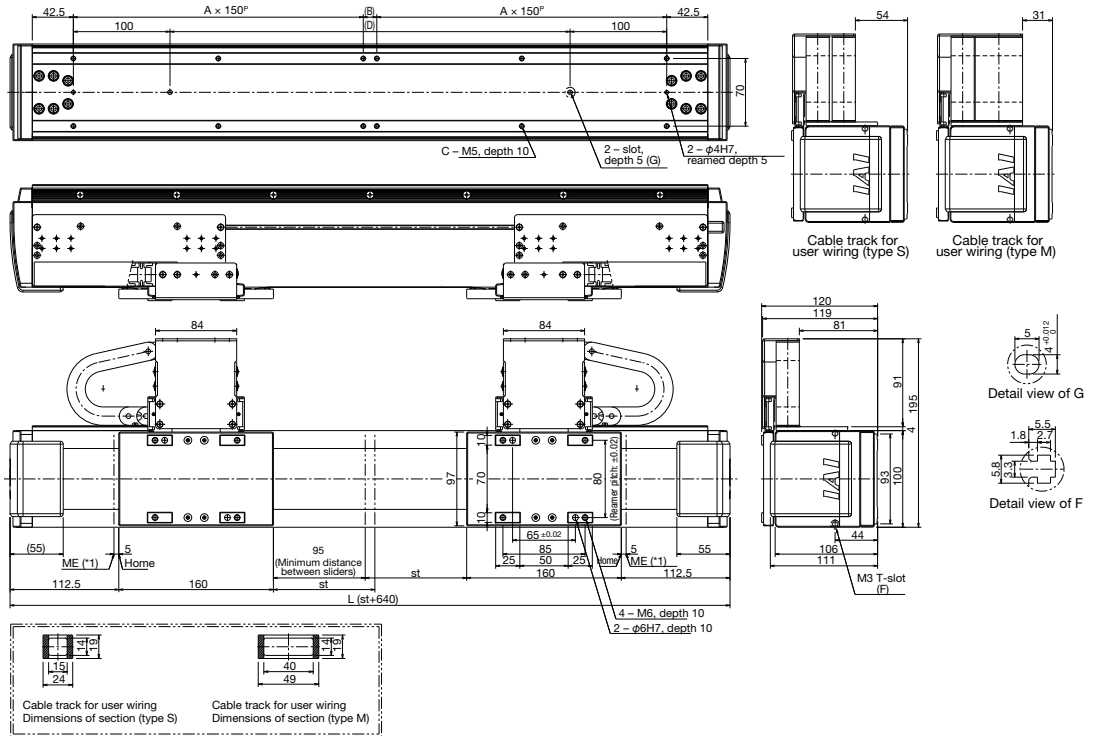
(Note 1) The maximum speed may not be attained if the stroke is short.
 (Note 2) The maximum acceleration varies depending on the operating conditions.
 (Note 3) The maximum cable length is 20 m for the SCON/SSEL and 30 m for the XSEL. Specify a desired length in units of meters. (Example: X08 = 8 m)

Dimensions – Sideway Specification

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Shaft type

Small type

Flat type

Medium type

Large type