

ISB-LXM-200

Single-axis robot/Large, X-axis, standard slider type/Actuator width: 150mm/200W Straight shape

ISPB-LXM-200

Single-axis robot/Large, X-axis, standard slider type/Actuator width: 150mm/200W Straight shape **High precision specification**



Model Specification Items

Series	LXM	Encoder type	200	Motor type	200: 200W	Lead	40: 40mm 20: 20mm 10: 10mm	Stroke	100: 100mm 1300: 1300mm (in 50mm increments)	Applicable controller	T1: XSEL-J/K T2: SCON SSEL XSEL-P/Q	Cable length	N: None S: 3m M: 5m X□□: Specified length	Options	Refer to the options table below.
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* Refer to P. 10 for the details of items comprising the model number.

Model Number/Specification

Model number	Encoder type	Motor output (W)	Lead (mm)	Stroke in 50mm increments (mm)	Speed (mm/s)	Acceleration (Note 1)				Payload (Note 1)				Rated thrust (N)
						Horizontal (G)		Vertical (G)		Horizontal (kg)		Vertical (kg)**		
						Rated	Maximum	Rated	Maximum	Rated acceleration	Maximum acceleration	Rated acceleration	Maximum acceleration	
ISB[ISPB]-LXM-①-200-40-②-③-④-⑤	Absolute Incremental	200	40	100~1300	1~2400	0.4	1.2	0.4	1.2	15	6	4	1.6	85.5
ISB[ISPB]-LXM-①-200-20-②-③-④-⑤			20		1~1200	0.4	1.2	0.4	1	45	12	10	5	170.9
ISB[ISPB]-LXM-①-200-10-②-③-④-⑤			10		1~600	0.4	0.7	0.4	0.6	90	40	20	14	341.8

*In the above model numbers, ① indicates the encoder type, ② indicates the stroke, ③ indicates the applicable controller, ④ indicates the cable length, and ⑤ indicates the option(s).

**If the guide with ball retention mechanism (RT) is used, the vertical payload decreases by 1.0 kg. (Please also refer to P.9).

Option

Name	Model number	Reference page	Name	Model number	Reference page
Cable exit from the left	A1S	→P11	Home limit switch	L	→P11
Cable exit from the rear left	A1E	→P11	Home limit switch on the opposite side	LL	→P11
Cable exit from the right	A3S	→P11	Master axis specification	LM	→P12
Cable exit from the rear right	A3E	→P11	Master axis specification (sensor on the opposite side)	LLM	→P12
AQ seal (standard feature)	AQ	→P11	Non-motor side specification	NM	→P12
Brake	B	→P11	Guide with ball retention mechanism	RT	→P12
Creep sensor	C	→P11	Slave axis specification	S	→P12
Creep sensor on the opposite side	CL	→P11	High straightness, precision specification	ST	→P13

Common Specifications

Positioning repeatability (Note 2)	±0.01mm [±0.005mm]
Drive method (Note 3)	Ball screw Ø20mm, rolled C10 [equivalent to rolled C5]
Lost Motion (Note 4)	0.05mm [0.02mm] max.
Dynamic allowable load moment (Note 5)	Ma: 104.9N·m Mb: 149.9N·m Mc: 248.9N·m
Overhang load length	Ma direction: 750mm max. Mb, Mc directions: 750mm max.
Dynamic straightness (Note 6)	0.02mm/m max.
Base	Material: Aluminum, with white alumite treatment
Applicable controller	T1: XSEL-J/K T2: XSEL-P/Q, SSEL, SCON
Cable length (Note 7)	N: None, S: 3m, M: 5m, X□□: Specified length
Ambient operating temperature/humidity	0 to 40°C, 85%RH max. (non-condensing)

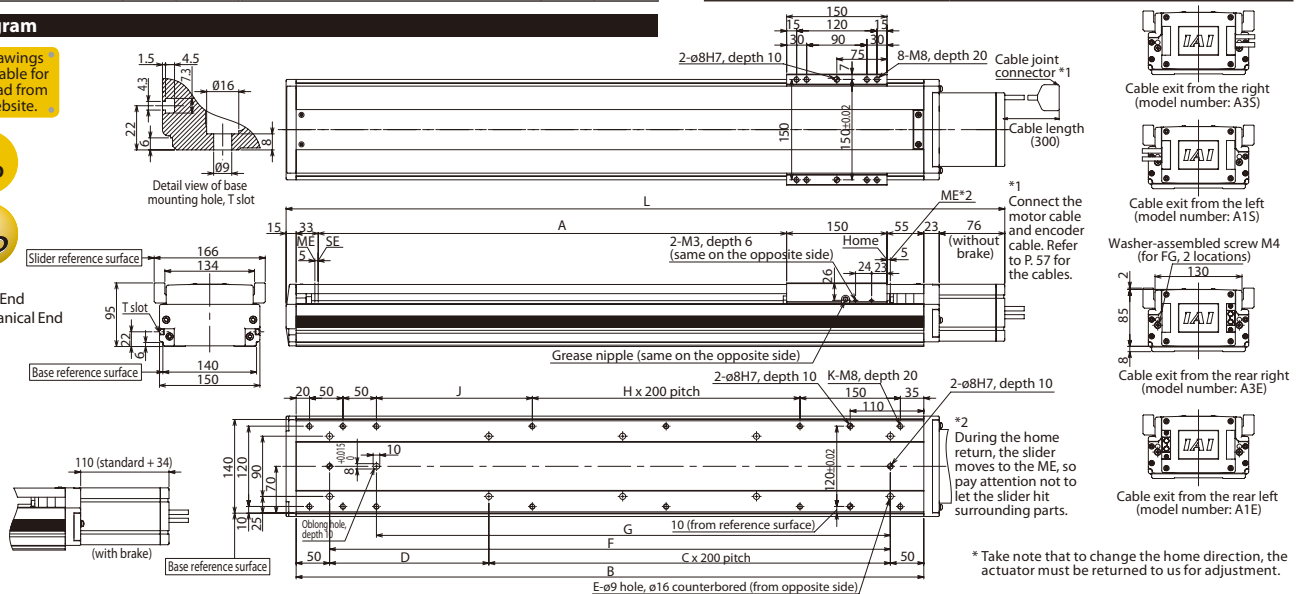
Diagram

CAD drawings are available for download from our website.

2D CAD

3D CAD

SE: Stroke End
ME: Mechanical End



Dimensions, Mass and Maximum Speed by Stroke

Stroke	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	
L	without brake	452	502	552	602	652	702	752	802	852	902	952	1002	1052	1102	1152	1202	1252	1302	1352	1402	1452	1502	1552	1602	1652
	with brake	486	536	586	636	686	736	786	836	886	936	986	1036	1086	1136	1186	1236	1286	1336	1386	1436	1486	1536	1586	1636	1686
A	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	
B	338	388	438	488	538	588	638	688	738	788	838	888	938	988	1038	1088	1138	1188	1238	1288	1338	1388	1438	1488	1538	
C	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6	
D	238	288	338	388	438	488	538	588	638	688	738	788	838	888	938	988	1038	1088	1138	1188	1238	1288	1338	1388	1438	
E	4	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	
F	238	288	338	388	438	488	538	588	638	688	738	788	838	888	938	988	1038	1088	1138	1188	1238	1288	1338	1388	1438	
G	168	218	268	318	368	418	468	518	568	618	668	718	768	818	868	918	968	1018	1068	1118	1168	1218	1268	1318	1368	
H	0	0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	
J	33	83	133	183	233	283	333	383	433	483	533	583	633	683	733	783	833	883	933	983	1033	1083	1133	1183	1233	
K	10	10	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18	18	20	20	20	
Mass (kg)	9.4	10.3	11.1	12.0	12.8	13.7	14.6	15.5	16.3	17.2	18.0	18.9	19.8	20.7	21.5	22.4	23.2	24.1	25.0	25.9	26.7	27.6	28.4	29.3	30.2	
Maximum speed (mm/s)	Lead 40																			1840	1530	1290	1100	880		
	Lead 20																			920	765	645	550	440		
	Lead 10																			460	380	320	270	220		

*If the brake is equipped, the mass increases by 0.6kg. *The maximum speed (mm/s) varies depending on the stroke.

Applicable Controller Specifications

Applicable Controller	Maximum number of controlled axes	Connectable encoder type	Operating method	Power-supply voltage	Reference page
X-SEL-P/Q	6 axes	Absolute/ incremental	Program	Single/three-phase 200 VAC	→P56
X-SEL-J/K	4 axes			Single-phase 100/200 VAC	→P56
SSEL	2 axes			→P56	
SCON	1 axis			Positioner pulse train control	→P56

CAUTION

(Note 1) Refer to P. 9 for the relationship of acceleration and payload. (Notes 2, 3, 4) The values in [] apply to the ISPB series. Other specification values apply commonly to the ISB and ISPB.

(Note 5) When the traveling life is 10,000km.

(Note 6) The value of dynamic straightness is when the high straightness, precision specification (option) is specified.

(Note 7) The maximum cable length is 30m. Specify a desired length in meters. (Example. X08 = 8m)