

Electronic Cam oller Option Function

XSEL-P/Q Controller Option

ELECTRONIC PAM



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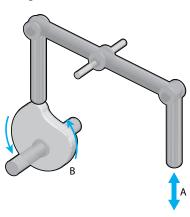
The controller recreates the movements of mechanical cams!

A cam mechanisms is used in situations where a given operation should be performed in conjunction with another operation in a production facility.

If a cam mechanism is used, however, the cam itself must be redesigned from scratch when the stroke or pattern is to be changed, which makes the adjustment process time-consuming and cumbersome. An electronic cam function solves this problem.

Example of Cam Mechanism

To change the vertical travel (A) or operation pattern, the cam (B) must be given additional machining or redesigned.



What Is Electronic Cam?

An electronic cam controls the slave axis in synchronization with the master axis, using pulse trains, according to a pre-defined electronic cam table.

Features of Electronic Cam

Shorter system cycle time

Since the position relationships of operating axes can be specified in a cam table, the stopping time of each axis can be minimized and consequently the cycle time can be reduced significantly.

C Easy adjustment when changing the operation pattern

Unlike with a mechanical cam, no parts must be machined when changing the operation pattern. All you need is to change the data of the electronic cam table, and you will be able to change the positions and timings.

Since the position relationships of the master axis do not change due to speed, timings can be adjusted at a sufficiently low speed, which makes adjustments very easy.

Up to 16 axes can be controlled

Eight slave axes can be operated with one pulse-train board installed in the XSEL controller. Up to two pulse-train boards can be installed, which means that up to 16 axes can be controlled.

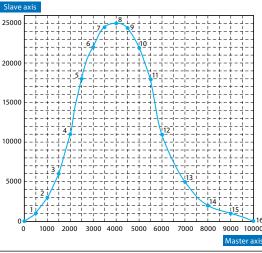
Example of Electronic Cam Table

The electronic cam table is a data table used for specifying the positions of slave axes that move in conjunction with the movements of the master axis. The horizontal axis represents the phase of the master axis, while the vertical axis represents the displacement of the slave axis.

When values are entered in the electronic cam table, points appear on the graph area of the electronic cam table and a curved line linking all these points gives an operating curve of the slave axis.

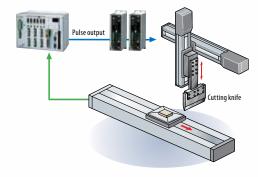
No.	Master axis phase	Slave axis phase
0	0	. 0
1	500	1000
2	1000	3000
3	1500	6000
4	2000	11000
5	2500	18000
6	3000	22000
7	3500	24500
8	4000	25000
9	4500	24500
10	5000	22000
11	5500	18000
12	6000	11000
13	7000	5000
14	8000	2000
15	9000	1000
16	10000	0





Example of Use of Electronic Cam

By designating a single-axis robot as the master axis and moving a cutting knife up and down in conjunction with the movements of this single-axis robot, the work part can be cut without stopping the work part.



<Note> The above table and graph are provided for illustration purposes only and may differ from the actual table and graph shown on the software screen.

Other Useful Functions

1. Electronic shaft function

2. Positioner function

that the ratio of the travels of master and slave axes can be changed accordingly. Just like in any normal positioning operation, the actuator can be operated by setting position data. Movement by linear interpolation is also supported in addition to PTP operation. Up to 512 position points can be set, where the maximum number of position points changes depending on the number of connected axes.

3. Input pulse counter function

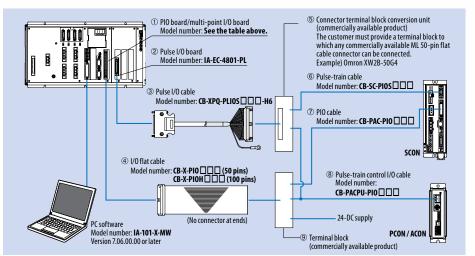
Pulses input from the pulse input channel are counted by the SEL program. It is also possible to use input pulses as the master axis of the electronic cam.

All slave axes move in the same manner as the master axis moves. A gear ratio can be set for master/slave-axis movements, which means

The following equipment will be required when an electronic cam is used.

Applicable controllers: XSEL-P/Q

Name	Master axis phase	Slave axis phase				
 N1: IA-103-X-32 N2: IA-103-X-16 N3: IA-IO-3204-NP P1: IA-103-X-32-P P2: IA-103-X-16-P P3: IA-IO-3204-PN 		Specify a desired code from among "N1," "N2," "N3," "P1", "P2" and "P3" in the standard or expansion I/O field of the controller model number.				
② Pulse I/O board	IA-EC-4801-PL	Enter the code "MC" in the expansion I/O field of the controller model number. If nine or more controllers are connected, two pulse I/O boards are required.				
③ Pulse I/O cable	CB-XPQ-PLIOS	This cable comes with the pulse I/O board.				
④ I/O flat cable	CB-X-PIODD(for 50 pins) CB-X-PIOHDD(for multi-point I/Os)	This cable comes with the controller or multi-point I/O board.				
⑤ Connecter terminal block conversion unit	—	Purchase a terminal block to which any commercially available ML 50-pin flat cable connector can be connected. (Example: Omron XW2B-50G4)				
6 SCON pulse-train cable	CB-SC-PIOS	Specify the model number shown to the left when ordering this cable.				
⑦ SCON PIO cable	CB-PAC-PIO	This cable comes with the SCON controller.				
8 Pulse-train control I/O cable		This cable comes with the PCON/ACON controller.				
③ Terminal block		Use a commercially available terminal block.				



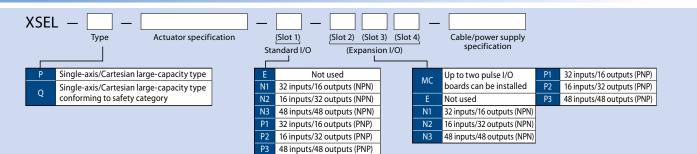
One pulse I/O board has eight pulse output channels and two pulse input channels.

Up to two pulse I/O board can be installed in one controller, meaning that up to 16 ROBO Cylinder controllers of pulse I/O type can be connected.

If a NOBO Cylinder controller is connected, PIO connection is required in addition to pulse I/O connection. Use the table below to check the number of signals required by each controller and add a PIO board according to the number of controllers to be operated.

	Number of I/Os required per controlle						
	Input	Output					
SCON controller	5 points	3 points					
PCON/ACON controller	4 points	3 points					

Model number



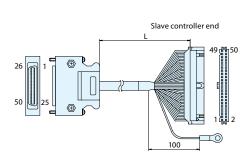
Specifications

ltem	Description	Remarks
Applicable controller	XSEL-P/Q	
PC software	Version 7.06.00.00 or later	
I/O I/F	Pulse I/Os by 2 input channels and 8 output channels (1 board)	
Number of installed boards	Up to 2 boards	Installed in expansion I/O slots.
Number of controlled axes	Up to 16 axes (when 2 pulse I/O boards are used)	
Connection pulse-train driver	SCON, ACON-PL, PCON-PL	Only differential drivers are supported.
Synchronous control function	Synchronous electronic cam (master axis specification), single electronic cam (time specification), electronic shaft	
Positioning function	Servo ON/OFF, home return, PTP movement (absolute/relative), movement by linear interpolation (absolute/relative), movement by direct numerical specification (absolute/relative)	
Input pulse counter function	Clear pulse counter, get pulse count	Max. 500 Kpps
Other functions	Jog/Incremental move (only via a tool), axis movement stop, pause, cancel, soft limit, command position teaching	

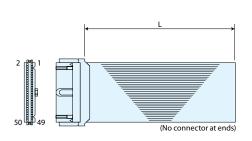
Cable

• Pulse I/O cable

Model number: CB-XPQ-PLIOS - H6 * III indicates the cable length (L). A desired length of up to 5 m can be specified in meters. Example: 020 = 2 m



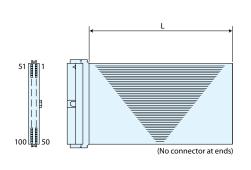
Pin No.	Wire color	Signal	Channel No.	Function	Pin No.	Wire color	Signal	Channel No.	Function	
1	Blue	0A+		Pulse output phase A+	27	Gray/White 2	1A+		Pulse output phase A+	
2	Orange	0A-	0	Pulse output phase A-	28	Red/White 2	1A-	1	Pulse output phase A-	
3	Green	0B+		Pulse output phase B+	29	Black/White 2	1B+	'	Pulse output phase B+	
4	Brown	0B-		Pulse output phase B-	30	Yellow/Black 2	1B-		Pulse output phase B-	
5	Gray	2A+		Pulse output phase A+	31	Pink/Black 2	3A+		Pulse output phase A+	
6	Red	2A-	2	Pulse output phase A-	32	Purple/White 2	3A-	3	Pulse output phase A-	
7	Black	2B+	-	Pulse output phase B+	33	White/Blue 2	3B+		Pulse output phase B+	
8	Yellow	2B-		Pulse output phase B-	34	Blue/Black 1	3B-		Pulse output phase B-	
9	Pink	4A+		Pulse output phase A+	35	Orange/Black 1	5A+		Pulse output phase A+	
10	Purple	4A-	4	Pulse output phase A-	36	Green/Black 1	5A-	5	Pulse output phase A-	
11	White	4B+	-	Pulse output phase B+	37	Brown/Black 1	5B+		Pulse output phase B+	
12	Blue/Red 1	4B-		Pulse output phase B-	38	Gray/Black 1	5B-		Pulse output phase B-	
13	Orange/White 1	6A+	6	Pulse output phase A+	39	Red/Black 1	7A+		Pulse output phase A+	
14	Green/White 1	6A-		6	Pulse output phase A-	40	Yellow/Red 1	7A-	7	Pulse output phase A-
15	Brown/White 1	6B+			Pulse output phase B+	41	Pink/Red 1	7B+	, í	Pulse output phase B+
16	Gray/White 1	6B-		Pulse output phase B-	42	Purple/Black 1	7B-		Pulse output phase B-	
17	Red/White 1	INA+0		Pulse input phase A+	43	White/Black 1	INA+1		Pulse input phase A+	
18	Black/White 1	INA-0		Pulse input phase A-	44	Blue/Black 2	INA-1]	Pulse input phase A-	
19	Yellow/Black 1	INB+0		Pulse input phase B+	45	Orange/Black 2	INB+1]	Pulse input phase B+	
20	Pink/Black 1	INB-0	0	Pulse input phase B-	46	Green/Black 2	INB-1	1	Pulse input phase B-	
21	Purple/White 1	INZ+0		Do not connect anything to this signal.	47	Brown/Black 2	INZ+1] '	Do not connect anything to this signal.	
22	White/Blue 1	INZ-0		Do not connect anything to this signal.	48	Gray/Black 2	INZ-1]	Do not connect anything to this signal.	
23	Blue/Red 2	E5V_0		Encoder power output (5 VDC): 100 mA max.	49	Red/Black 2	E5V_1]	Encoder power output (5 VDC): 100 mA max.	
24	Orange/White 2	E0V_0		Encoder power ground	50	Yellow/Red 2	E0V_1		Encoder power ground	
25	Green/White 2	RSV_COM1	-	Do not connect anything to this signal.	Conn	ect a crimpled ro	und termin	al to the shield		
26	Brown/White 2	RSV_COM2	-	Do not connect anything to this signal.						



			ard I/O	Expa	nsion I/O			Standard	11/0	Expansion I/O	
Pin No.	Wire color	When I/O code N1/P1 is selected	When I/O code N2/P2 is selected	When I/O code N1/P1 is selected	When I/O code N2/P2 is selected	Pin No.	Wire color	When I/O code N1/P1 is selected	When I/O code N2/P2 is selected	When I/O code N1/P1 is selected	When I/O code N2/P2 is selected
1	Brown 1	24 V, externally	24 V, externally	24 V, externally	24 V, externally	26	Blue 3				
		supplied	supplied	supplied	supplied	27	Purple 3				
2	Red 1	Program start					Gray 3				
3	Orange 1					29	White 3	General-		General-	
4	Yellow 1					30	Black 3	purpose input		purpose input	
5	Green 1	General-purpose	General-purpose			31	Brown 4				
6	Blue 1	input	input		32 Red 4 33 Orange 4 34 Yellow 4 Alarm output						
7	Purple 1										
8	Gray 1										
9	White 1	Program specification (PRG No. 1)		purpose input	35	Green 4	Ready output			General-	
10	Black 1	Program specification (PRG No. 2)			36	Blue 4	Emergency stop output				
11	Brown 2	Program specification (PRG No. 4)			37	Purple 4		General-			
12	Red 2	Program specification (PRG No. 8)				38	Gray 4		purpose output	General-purpose	purpose output
13	Orange 2	Program specific		General-	input 40 41		White 4	-			
14	Yellow 2	Program specific		purpose input			Black 4				
15	Green 2	Program specific	ation (PRG No. 40)				Brown 5				
16	Blue 2		General-purpose			42	Red 5	General- purpose output		output	
17	Purple 2		input			43	Orange 5				
18	Gray 2		Alarm output			44	Yellow 5				
19	White 2		Ready output			45	Green 5				
20	Black 2	General-purpose	Emergency stop output		General-purpose	46	Blue 5				
21	Brown 3	input	General-purpose		output	47	Purple 5				
22	Red 3					48	Gray 5				
23	Orange 3		output			49	White 5				
24 25	Yellow 3 Green 3					50	Black 5	0 V, externally supplied	0 V, externally supplied	0 V, externally supplied	0 V, externally supplied

I/O flat cable (100-pin specification for multi-point I/O board)

Model number: CB-X-PIOH T * D indicates the cable length (L). A desired length of up to 10 m can be specified in meters. Example: 020 = 2 m



Pin No.	Standard I/O	Expansion I/O	Pin No.	Standard I/O	Expansion I/O	Pin No.	Standard I/O	Expansion I/O	Pin No.	Standard I/O	Expansion I/O	
1	24 V, externally			24 V, externally	51	Alarm output		76				
'	supplied	supplied		supplied	supplied	52	Ready output		77	7		
2	Program start		27 53 Emergen	Emergency stop output		78						
3			28			54			79			
4			29			55			80			
5	General-purpose input		30			56			81			
6	General-purpose input		31			57			82		1	
7			32			58			83			
8			33			59			84			
9	Program specification		34		60			85				
10	Program specification		35	36 37 38 General- purpose input General-	61			86				
11	Program specification				62		General-	87	General-	General-		
12	Program specification	tion General- 38 General- 0 tion purpose input 39 purpose input pur				63	General-	purpose output	88	purpose output	purpose output	
13	Program specification						purpose output		89	89 90 91		
14	Program specification		39			65	purpose output		90			
15	Program specification		40			66			91			
16				67		92]					
17			42			68			93			
18			43			69			94			
19			44			70			95			
20	General-purpose input		45			71			96			
21	General-purpose input		46	46 47		72			97			
22			47			73			98			
23			48			74			99			
24 25				49 50			75	0 V, externally supplied	0 V, externally supplied	100	0 V, externally supplied	0 V, externally supplied

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