

ROBO Cylinder Waterproof Type KCP2

New RCP2 slider lineup Eagerly awaited waterproof type!

First in the industry (IAI study) Fully conforming to IEC IP67!

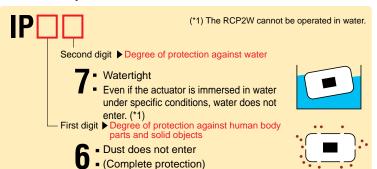
Able to withstand strong/repeated splashes or washing processes!



Features

An **IP67**-rated structure provides strong protection a gainst water.

The RCP2W fully conforms to IEC IP67.



• Magnetic coupling structure (patent pending)

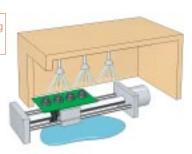
Thrust is transmitted via magnetic attraction force to achieve complete sealing around the ball screw.

Optional cover type

You can select the cover type that protects guides and other sliding parts.

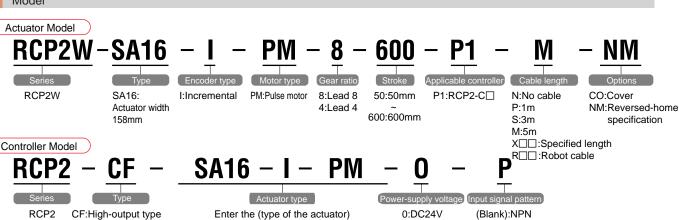
Examples of Use

Parts cleaning equipment





Model



with built-in drivesource cutoff relay - (encoder type) - (motor type)

:PNP

* Leave this space blank unless you require the PNP specification.

RCP2W-SA16 ROBO Cylinder Waterproof Type, Actuator Width 158mm, Pulse Mor Actuator Width 158mm, Pulse Motor

Type Slider (158mm wide)

Stroke 50~600mm

Load capacity 35kg (horizontal)

Model specification items RCP2W-SA16-

PM - 8 - 600 -

Series Type Encoder type Motor Stroke Applicable controller Cable length Options

Models/Specifications

The maximum speed of the RCP2 Series varies depending on the weight of the load installed on the slider (rod). Refer to the graph on the facing page for the relationship of speed and load capacity.

Model	Franks Turn	Motor output	Lead	Stroke 50mm increments (mm)	Speed (mm/s)	Load capacity (Note1)	
Model	Encoder Type	(W)	(mm)			Horizontal (kg)	Vertical (kg)
RCP2W-SA16-I-PM-8- ①-P1- ② - ③	Incremental	tal Pulse motor	8	50 ~ 600	5 ~ 180	25 ~ 1	. Horizontal only
RCP2W-SA16-I-PM-4- ① -P1- ② - ③	morementar		4		1 ~ 133	35 ~ 3	

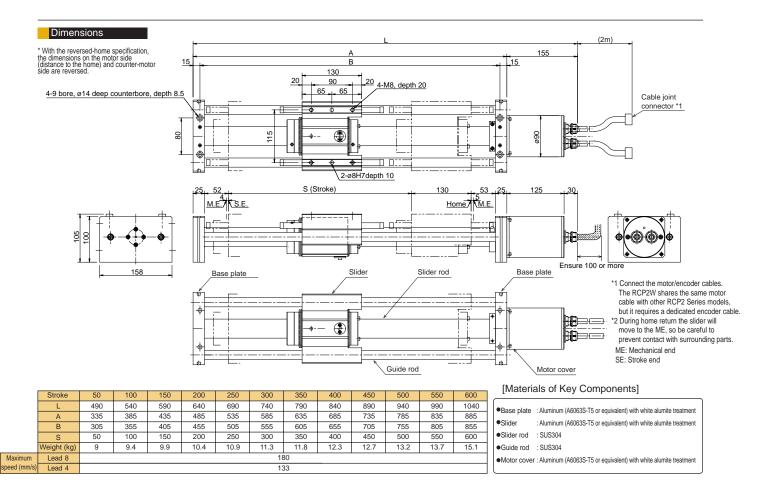
* In the above model names, Dindicates the stroke, 2 the cable length, and 3 the applicable option(s).

Options

Name	Code	Page	
Cover type	СО	→P2	
Reversed-home specification	NM	-	

Common Specifications

Drive system	Ball screw ø12mm, rolled C10		
Positioning repeatability	±0.08mm		
Backlash	0.1mm or less		
Guide	ø20 non-lubricated, direct-coupled sliding guide		
Static allowable load moment (Note 2)	20.0N • m		
Overhung load length (Note 3)	Ma direction: 200mm or less		
Base	Material: Aluminum with white alumite treatment		
Cable length (Note 4)	N: No cable, P: 1m, S: 3m, M: 5m,		
	X□□: Length specification, R□□: Robot cable		
Ambient operating temperature/humidity	0~40°C, 85% RH or less (non-condensing)		



Applicable Controller Specifications

Applicable controller	Maximum number of controlled axes	Compatible encoder type	Operating method	Power supply voltage	Page
RCP2-CF-SA16	1 axis	Incremental	Positioner	DC24V	Back cover



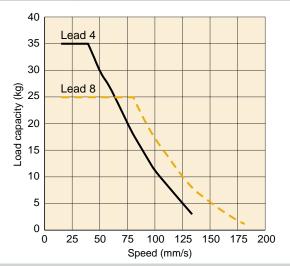
- (Note 1) The load capacity is based on operation at an acceleration of 0.2 G.
- (Note 2) The allowable load moment when the actuator is stationary. (Note 3) The actuator cannot accommodate overhung loads in the Mb or Mc direction. (Refer to "Notes on Use" on the facing page.)

(Note 4) The maximum cable length is 18 m. Specify a desired length in meters. (Example: X08 = 8 m)

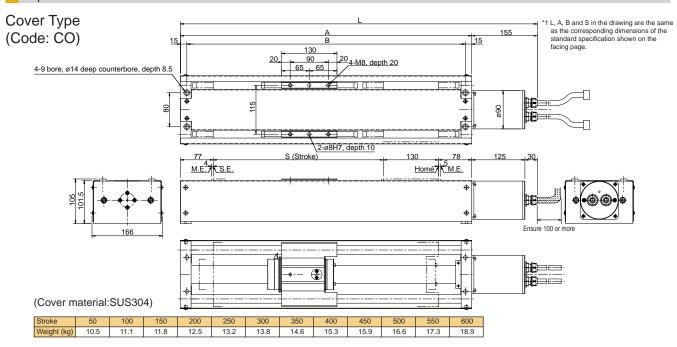
Correlation Diagram of Speed and Load Capacity

The specification data shown to the right is based on operation at an acceleration of 0.2 G with the payload uniformly distributed over the slider.

If the actuator receives any moment load, different values will apply because the effect of slide resistance must be considered.

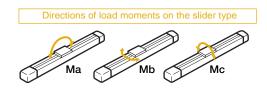


Option



Notes on Use

- This actuator cannot be used in vertical applications. It cannot perform push operation, either.
- Keep the duty (%) <operating time / (operating time + stopped time) x 100)> at 50% or below.
- Operate the actuator in conditions where it does not receive any moment load in the Mb or Mc direction.
 If any implement is to be attached to the slider, install the implement so that its center of gravity stays within the slider dimension and its height is kept within 200 mm from the top surface of the slider.



- This actuator is IP67-rated. However, the user must heed the following precautions:
 - The cable leading from the actuator (actuator cable) is 2 m long.

The connector at the end of the cable is not waterproof, so lay the cable in such a way that its end does not come in contact with water.

- The actuator cannot be operated in water.
- If the actuator is to be used in an environment where it will be exposed to splashed liquids other than water, consult IAI beforehand.
- The actuator cannot be used in an environment where air contains scattered or suspended dust including magnetic particles.
- The actuator cannot be used in an environment where air contains scattered or suspended abrasive particles or dust.
- The ball screw and slider are coupled via magnetic attraction force and will therefore separate if an excessive force is applied. To prevent their accidental decoupling, the actuator has a built-in torque limiter. Should the ball screw and slider be displaced due to impact, etc., they will return to their original positions once home return is performed.
- ullet The encoder cable is different from the one used with the standard RCP2 models. (The motor cable is the same.)

Controller

RCP2-CF-SA16

RCP2

with built-in drive-

source cutoff relay

CF:High-output type

SA16-I-PM

- (encoder type) - (motor type)

Enter the (type of the actuator)

0:DC24V

(Blank):NPN :PNP

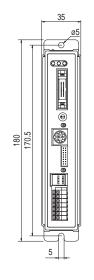


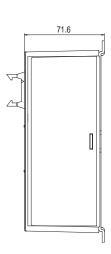
Specification Table

Item	Specification
Controller series/type	RCP2-CF-SA16
Connected actuator	RCP2-SA16
Input power supply	DC24V±10%
Power-supply capacity	6A max. (peak rush current: 8A)
Number of controlled axes	1 axis
Control method	Field-weakening vector control (patent pending)
Positioning command	Position number specification
Position numbers	Standard 16 points, maximum 64 points
Backup memory	Position number data and parameters are saved in non-volatile memory. Serial EEPROM rewritable up to 100,000 times.
PIO	10 dedicated input points / 10 dedicated output points; selectable from 5 patterns.
LED indicators	RDY (green), RUN (green), ALM (red)
I/F power supply	External power supply 24V±10% / 0.3A; insulated
Communication	RS485, 1 channel (terminated externally)
Encoder interface	Incremental interface conforming to EIA RS-422A/423A
Forced release of electromagnetic brake	Toggle switch on front panel of enclosure
Cable length	Motor/encoder cables: 18m max.
Cable long.	PIO cable: 5m max.
Withstand voltage	DC500V 10MΩ
Vibration resistance	10~57Hz in XYZ directions / Single amplitude 0.035mm (continuous), 0.075mm (intermittent)
Ambient operating temperature	0~40°C
Ambient operating humidity	85% RH or less (non-condensing)
Operating ambience	Free from corrosive gases
Protection class	IP20
Weight	300g
Accessory	PIO flat cable (2m)

External Dimensions

Unit:mm





Options/Spare Parts

Item	Model
Teaching pendant	RCA-T
Teaching pendant (deadman specification)	RCA-TD
Simple teaching pendant	RCA-E
Data setting unit	RCA-P
PC software	RCB-101-MW
Motor cable	CB-RCP2-MA □□□
Encoder cable	CB-RFA-PA □□□
Encoder robot cable	CB-RFA-PA□□□-RB



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^{*} The standard motor cable is a robot cable.
* The encoder cable is different from the one used with the standard RCP2 models.