



#### Summary Air cylinder equipment **ROBO Cylinder equipment** 1 line: 1,918 pcs/day 1 line: 2,647 pcs/day (38% improve Improvement of production efficiency 3 lines: 5,754 pcs/day 2 lines: 5,294 pcs/day =1,403,976 pcs/year (244 days) =1,291,736 pcs/year (244 days) Number of production lines required 3 lines 2 lines 10 types 25 types $+ \alpha$ Number of product types supported (Requires 3 lines to support 25 types) (1 line supports 25 types or more) Cost of equipment \$50,000 \$55,000 Electric power consumption (a)/system 142.51 kwh/year 429.32 kwh/year Step 3: Air compressor power consumption (b)/syster 1,113.15 kwh/year 0 kwh/year Total power consumption (a+b)/system 1,255.67 kwh/year 429.32 kwh/year inspection Step 3 Total power consumption 1,255.67 kwh x 3 lines = 3,767.0 kwh/year429.32 kwh x 2 lines = 858.6 kwh/year machine Step 3 Total power cost (\$0.17/kwh) \$565/year \$129/year 858.6 kwh/1,291,736 pcs = 0.6647 wh Step 3 Power consumption/piece 3,767.0 kwh/1,403,976 pcs = 2.683 whElectric power consumption 75% decreased

#### Production capability:

Air-cylinder equipment x 3 lines is equivalent to ROBO-cylinder equipment x 2 lines



<ul><li>Cost save</li></ul>	d in 3 years after switching to ROBO	DBO-cylinder equipment at Step 3  ② ROBO cylinder equipment	
	① Air-cylinder equipment	② ROBO cylinder equipment	
Equipment	\$50,000 x 3 lines = \$150,000	\$55,000 x 2 lines = \$110,000	

		① Air-cylinder equipment	② ROBO cylinder equipment	Difference (2 - 1)
	oment ost	\$50,000 x 3 lines = \$150,000	\$55,000 x 2 lines = \$110,000	-\$40,000
Labo	r cost	\$65,000 x 3 operators x 3 years = \$585,000	\$65,000 x 2 operators x 3 years = \$390,000	-\$195,000
Electi	ric bill	\$565 x 3 years = \$1,695	\$129 x 3 years = \$387	-\$1,308
Total		\$736,700	\$500,400	-\$236,300

Exchange rate: ¥100 = \$1, Dollar amounts rounded to the nearest \$100

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# **Improvement of Production Efficiency**

A case study that reduced the running costs by \$236,300\* over 3 years by changing to electric actuators

#### Environment surrounding customers

Supporting multi-variety, variable-volume production Improvement of production efficiency is urgently needed



Multiple varieties, varying volumes (Reduction of labor cost)

Issues of production facilities

Improvement of production efficiency

Energy-saving

\*Exchange rate: ¥100 = \$1

Improvement is needed to solve these issues. There are largely three causes.



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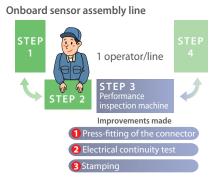
### **Overview of Improved System** (System Using Air Cylinders) **Onboard sensor performance tester**

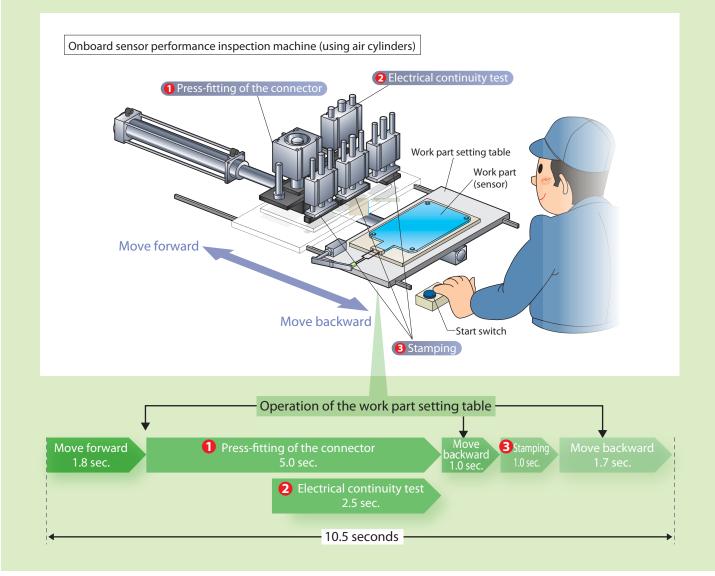
Overview of system The system we worked on is a simple semi-automatic system that assembles onboard sensors and conducts an electrical continuity test on sensor assemblies. The operator sets the work part and presses the start switch, then the work part setting table moves toward the back of the system to perform assembly (press-fitting of the connector) and inspect the assembled work part, after which the table returns to the forward position.

System specifications ● Number of air cylinders = 8 units

- Product types supported = 10 types (25 types can be supported with 3 lines.)
- Setup hours = 10 hours/year
- Cycle time = 10.5 seconds

Positioning of the system in the line



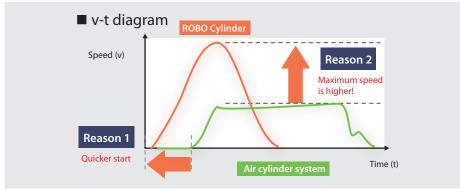


## **Significant Improvement of Production Efficiency through Motorization**

**Improvement** 

**Cycle time reduction for** "work part setting table" operation

With the air cylinder system, the "work part setting table" could not be operated faster because it would have increased the shock upon stopping. With the ROBO Cylinder system, on the other hand, the maximum speed can be increased because the actuator stops without generating shock. In addition, the ROBO Cylinder system starts quicker than the air cylinder system, which enabled significant reduction of the cycle time.

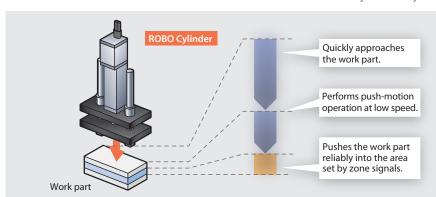


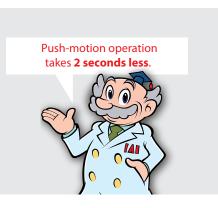
"Work part setting table" operation takes 1.8 seconds less.

Improvement

**Cycle time reduction for** "connector press-fitting" operation

With the air cylinder system, an automatic switch was used to determine whether the work part had been pressed to the specified position, which made the operation unstable and required 4 seconds for the press-fitting action to ensure quality. With the ROBO Cylinder system, on the other hand, push-motion operation can be performed using the zone function and consequently the press-fitting time was successfully reduced by 2 seconds.

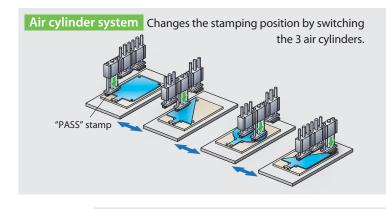




Improvement

**Supporting more product types** 

With the air cylinder system, multiple product types (10 types) were supported by switching the three air cylinders at the stamping location of the work part inspection "PASS" stamp. By motorizing the system, 25 product types are now supported. With the motorization of the "connector press-fitting" and "electrical continuity test," these steps can now support 25 product types, as well. (The time spent on setup went down from 150 seconds per day to 0 seconds.)



**ROBO Cylinder** the work part setting table

Setup time = **0 seconds** Number of product types supported = **25 types**