

Program Controller  
for ROBO Cylinder  
RCP5/RCP4/RCP3/RCP2

# MSEL-PC/PG

Powerful & Multifunctional



# Introducing the ROBO Cylinder 4-axis Program Controller MSEL with High-output Driver (PowerCON)



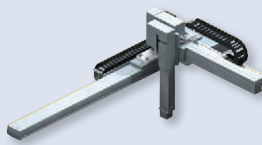
## 1 Control Maximum of 4 Axes Available with Pulse Motor Mounted ROBO Cylinder

Actuators with pulse motor in the past were able to control only up to two axes at maximum with one program controller. By using MSEL, four axes will be available for control. It is also available for interpolation operation, which enhances the ways of use.

### Example of Combinations

3-axis Cartesian (Pulse Motor)

RCP5



+



Available to Connect 4 Axes at Maximum

## 2 Available to Connect ROBO Cylinders RCP5 and RCP4

By applying to PowerCON, it is now possible to perform interpolation operation with ROBO Cylinders RCP5 and RCP4, which are applicable for high-output driver, but were not feasible with the program controller PSEL in the past.



## 3 Greatly Enhanced Programing Feature

The feature has been greatly upgraded with four times as many programs and twenty times as many positions compared to our products (PSEL) in the past.

	Conventional product PSEL		New product MSEL
Number of programs	64	4 times	255
Number of program steps	2,000	5 times	9,999
Number of multi-tasking programs	8	2 times	16
Number of positions	1,500	20 times	30,000 <sup>(*1)</sup>

(\*1) Note that the number of points available for backup in system memory is 10,000 points.

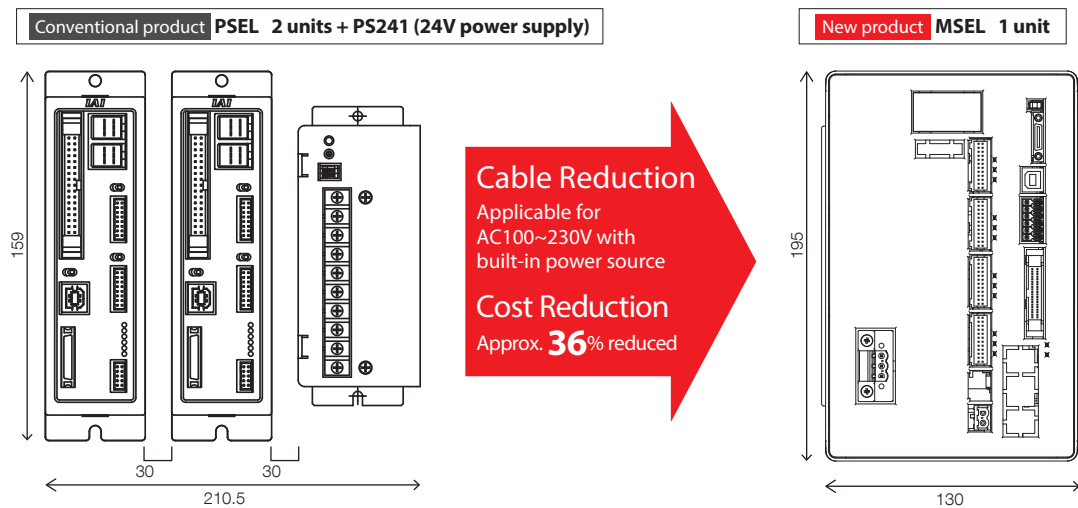
## 4 Equipped with Expansion I/O Slot

In addition to the standard IO (IN 16 points / OUT 16 points), one slot is available as the expansion I/O slot. The expansion I/O is available to select from PIO (IN 16 points / OUT 16 points) and four types of field network.

	Conventional product PSEL	New product MSEL
Max. I/O Input and Output Points	<b>24/8</b> Not applicable for expansion	<b>32/32</b> When expansion slot used
Field Network	<b>3 types</b> (CC-Link, DeviceNet, PROFIBUS-DP)	<b>4 types</b> (CC-Link, DeviceNet, PROFIBUS-DP, EtherNet/IP)
Other External Connections	<b>RS232C: 1ch</b>	<b>RS232C: 1ch</b>

## 5 Cable and Cost Reduction

### In 4-Axis Controlling of Actuator



## 6 Safety Category Applicable Type Introduced in Lineup (Applicable for Category 3)

MSEL-PG is applicable for Safety Category 3.

(To apply with Safety Category, it is necessary that the user establish a safety circuit out of the controller.)


## 7 Applicable for Various Models

It is now compatible with pulse motor type ROBO Cylinders RCP5 / RCP4 / RCP3 / RCP2.



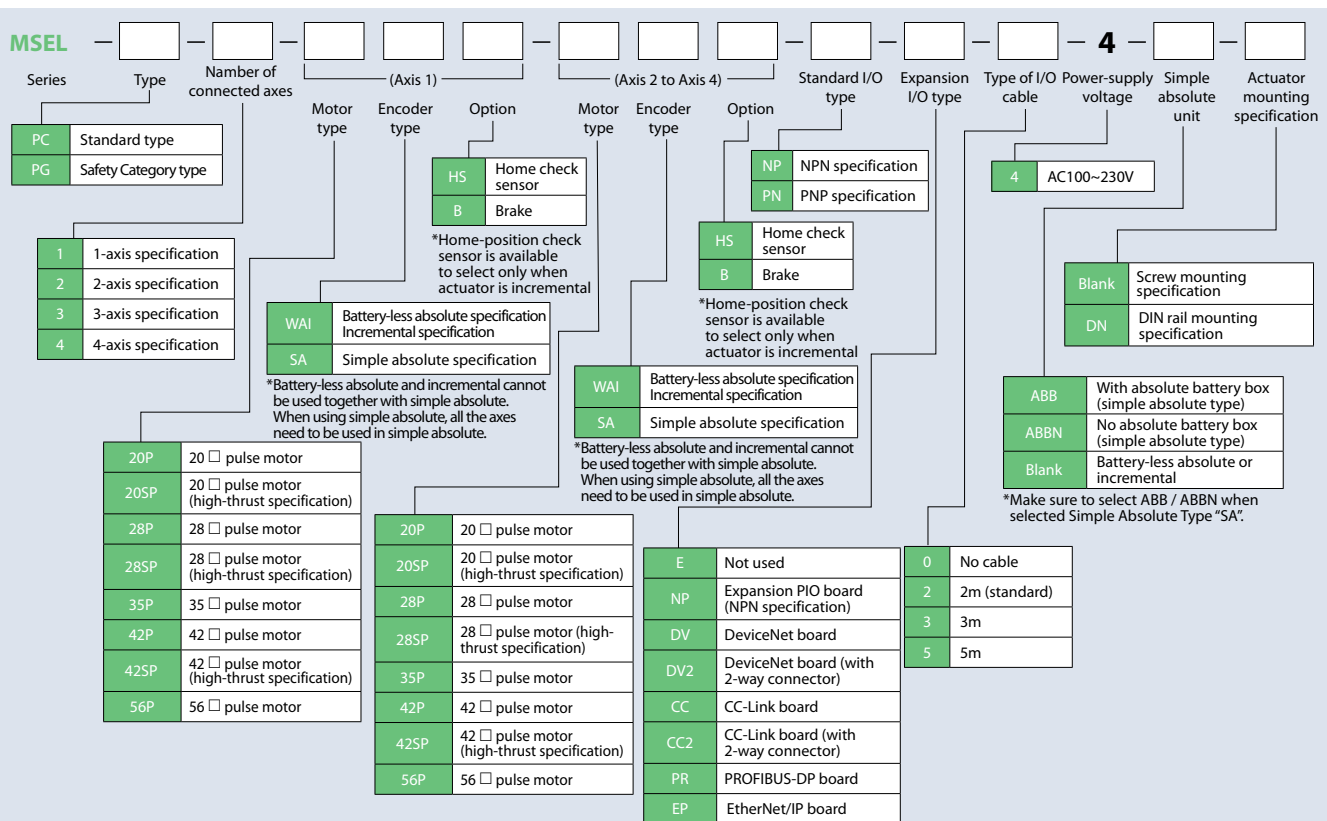
## Model List

It is a program controller available for operation of RCP5 / RCP4 / RCP3 / RCP2 series actuator. It is applicable to various types of controls with one unit.

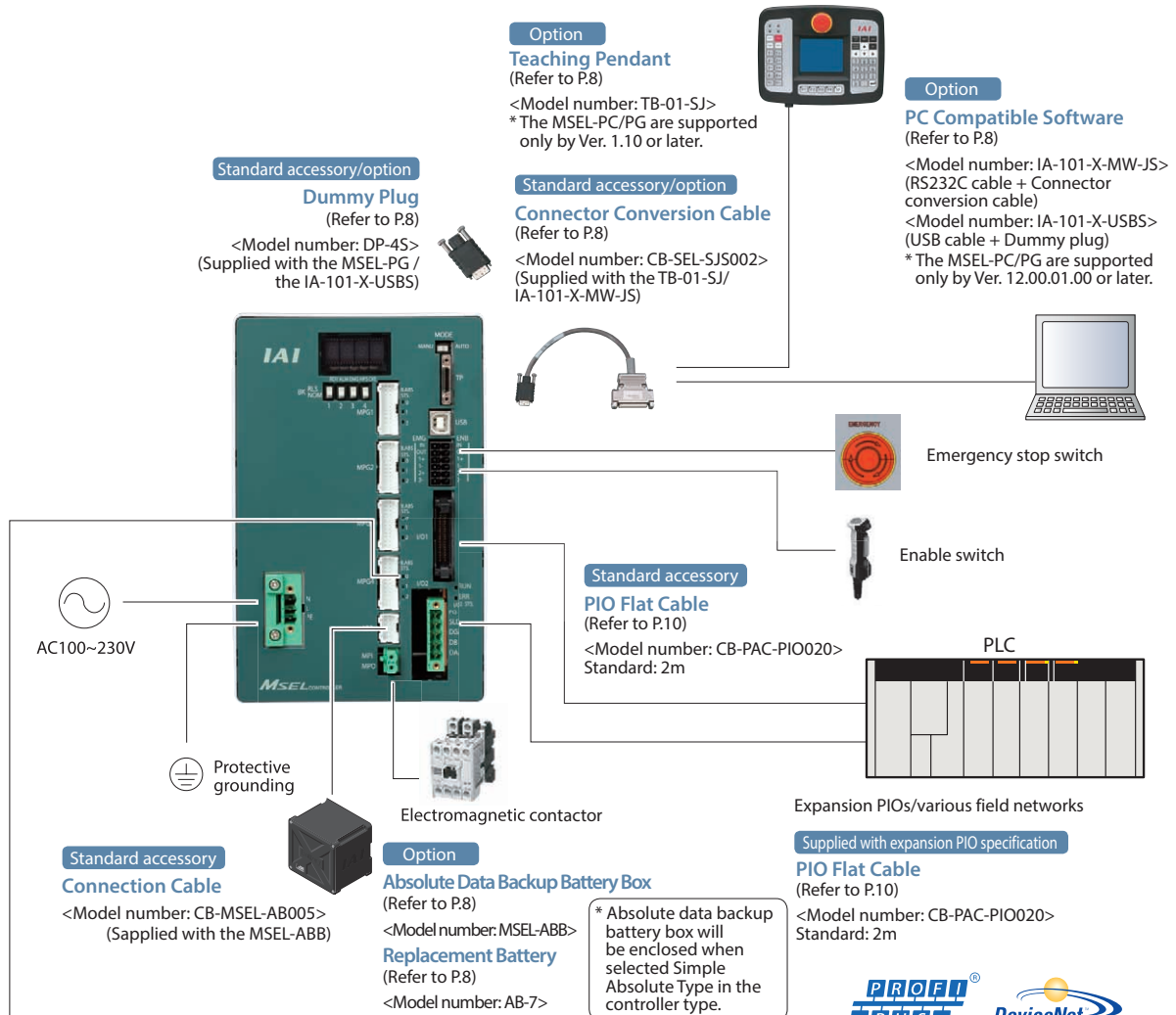
Type name			PC	PG
Name			Standard type	Safety Category type
External view				
Maximum number of controlled axes			4	
Number of positions			30,000	
Power supply			Single-phase AC100~230V	
Safety category			B	3 <sup>*1</sup>
Standard price	Battery-less absolute Incremental	1 axis	—	
		2 axes	—	
		3 axes	—	
		4 axes	—	
	Simple absolute	1 axis	—	
		2 axes	—	
		3 axes	—	
		4 axes	—	

\*1: Meeting this Safety Category requires the customer to install a safety circuit externally to the controller.

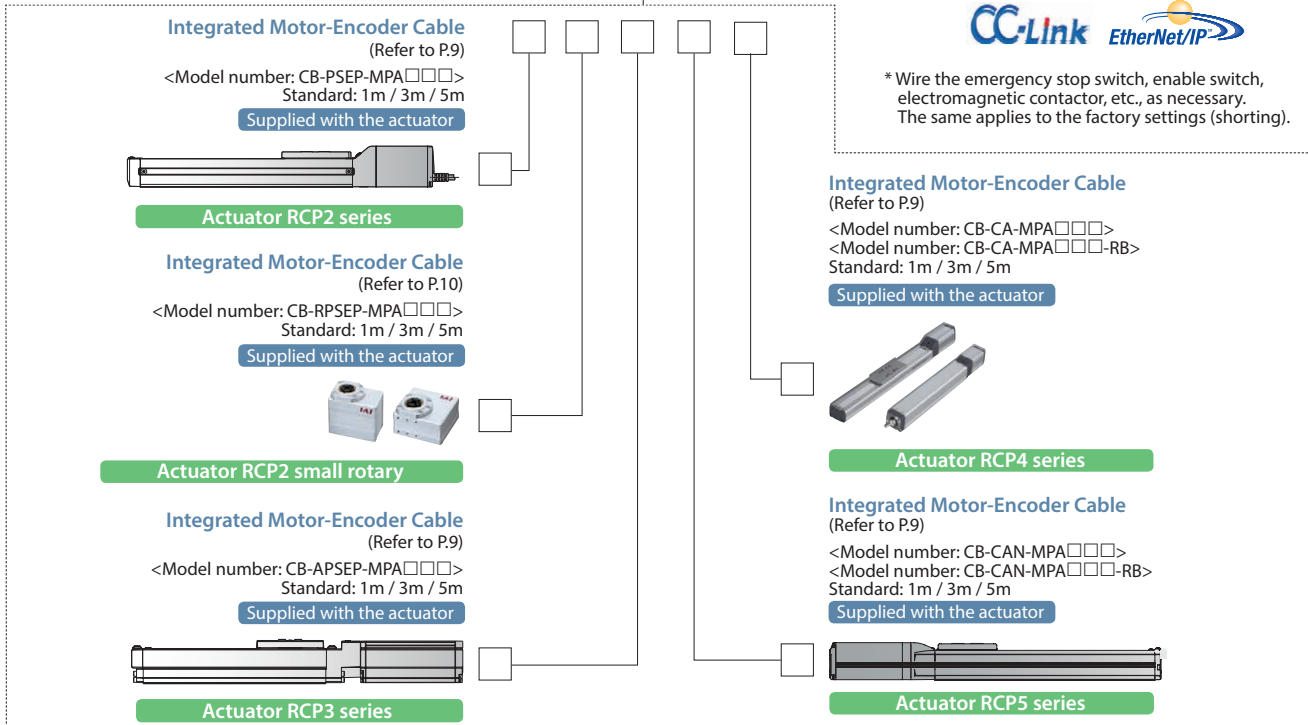
## Model



# System Configuration



## <Connectable Actuators>



**Basic Controller Specifications**

Specification item			Contents
Power-supply input voltage			Single-phase AC100~230V ±10%
Power-supply current			2.9A typ. (AC100V), 1.4A typ. (AC200V), 1.2A typ. (AC230V)
Power-supply frequency range			50/60Hz ±5%
Motor type			Pulse motor (servo control)
Supported encoder			Incremental encoder / Battery-less absolute encoder
Data storage device			FlashROM/FRAM
Number of program steps			9,999
Number of positions			30,000
Number of programs			255
Number of multitasks			16
Operation mode	Serial communications		○
	Program		○
SIO interface	Communication method		RS232 (asynchronous communications)
	Baud rate		9.6, 19.2, 38.4, 57.6, 76.8, 115.2kbps
	Live wire connection	TP port	×
		USB	○
Standard PIO interface	Input specification	Number of input points	16 points
		Input voltage	DC24V ±10%
		Input current	7mA/circuit
		ON voltage	Min.DC16V
		OFF voltage	Max.DC5V
		Leak current	Allowable leak current: 1mA max.
		Insulation method	Photocoupler insulation
	Output specification	Number of output points	16 points
		Load voltage	DC24V ±10%
		Maximum current	100mA/point, 400mA/8 points (Note 1)
		Saturated voltage	Max.3V
		Leak current	Max.0.1mA
Insulation method		Photocoupler insulation	
Compliant expansion I/O interface			Expansion PIO NPN specification (16IN/16OUT)
			CC-Link (remote device station)
			DeviceNet
			PROFIBUS-DP
			EtherNet/IP
Calendar/clock function	Retention time		Approx. 10 days
	Charge time		Approx. 100 hours (fully charged) * Data can be retained even when the batteries are not fully charged.
Protective functions			Overcurrent, abnormal temperature, fan speed low monitoring, encoder disconnection, etc.
Operating temperature range			0~40°C
Operating humidity range			85% RH max. (non-condensing, non-freezing)
Installation	Installation direction		Installed vertically (exhaust side up)
	Installation method		Mounted with screws or using a DIN rail
Rush current			15A typ. (AC100V ), 30A typ. (AC200V): 5ms max. (Ambient temperature 25°C/No cycling of the power)
Air cooling method			Forced air cooling
External dimensions			Width 130mm x Height 195mm x Depth 125mm
Mass			Approx. 1,400g

Note 1: The total load current shall be 400mA for every eight points from standard I/O No. 316. (The maximum current per point shall be 100mA.)



## PIO Signal Chart

Pin Layouts for Standard PIO Connector/Expansion PIO Connector

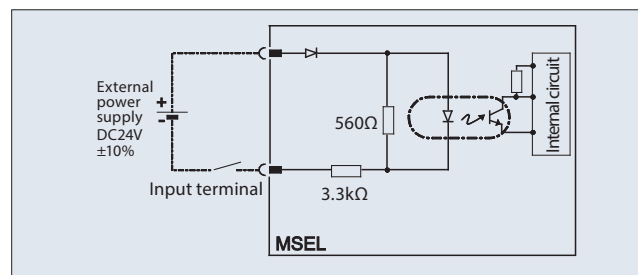
Pin No.	Category	Assignment	Pin No.	Category	Assignment
1A	24V	P24	1B	Output	OUT0
2A	24V	P24	2B		OUT1
3A	—	—	3B		OUT2
4A	—	—	4B		OUT3
5A	Input	IN0	5B		OUT4
6A		IN1	6B		OUT5
7A		IN2	7B		OUT6
8A		IN3	8B		OUT7
9A		IN4	9B		OUT8
10A		IN5	10B		OUT9
11A		IN6	11B		OUT10
12A		IN7	12B		OUT11
13A		IN8	13B		OUT12
14A		IN9	14B		OUT13
15A		IN10	15B		OUT14
16A		IN11	16B		OUT15
17A		IN12	17B	—	—
18A		IN13	18B	—	—
19A		IN14	19B	0V	N
20A		IN15	20B	0V	N

## Internal Circuits for Standard I/Os (NPN Specifications)

**[Input section]** External input specifications (NPN specifications)

Item	Specifications
Input voltage	DC24V $\pm 10\%$
Input current	7mA/circuit
On/Off voltage	On voltage...Min. DC16.0V, Off voltage...Max. DC5.0V
Insulation method	Photocoupler insulation

\* The port numbers in the circuit diagram below represent the factory-set port numbers.  
\* When the input is off, the allowable leak current is 1mA max.

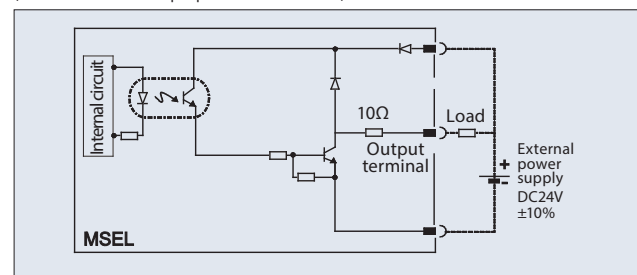


\* For the standard I/Os (PNP specifications), refer to the operation manual.

**[Output section]** External output specifications (NPN specifications)

Item	Specifications	
Load voltage	DC24V $\pm 10\%$	Uses TD62084 (or equivalent).
Maximum load current	100mA/point, 400mA/8 points (Note)	
Leak current	Max. 0.1mA/point	
Insulation method	Photocoupler insulation	

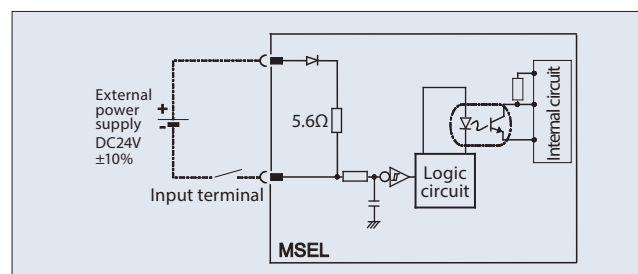
\* The port numbers in the circuit diagram below represent the factory-set port numbers.  
Note: The total load current shall be 400 mA for every eight points from standard I/O No. 316. (The maximum current per point shall be 100mA.)



## Internal Circuits for Expansion I/Os (NPN Specifications)

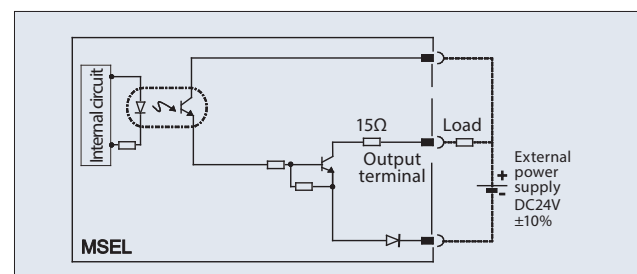
**[Input section]** External input specifications

Item	Specifications
Number of input points	16 points
Input voltage	DC24V $\pm 10\%$
Input current	4mA/circuit
On/Off voltage	On voltage...Min. DC18V (3.5mA) Off voltage...Max. DC6V (1mA)
Insulation method	Photocoupler insulation

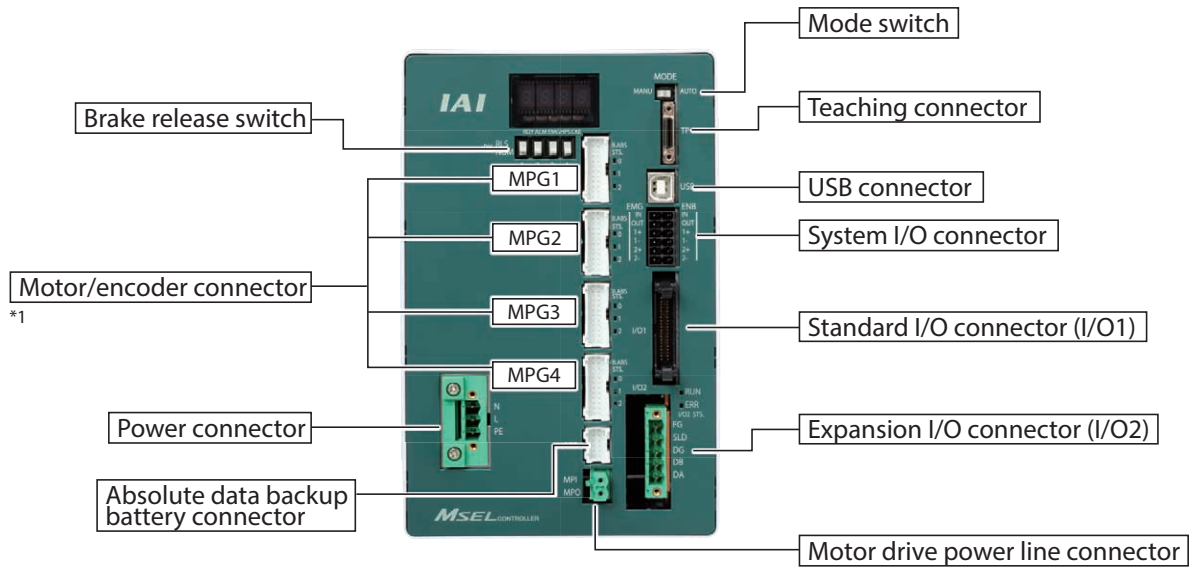


**[Output section]** External output specifications

Item	Specifications
Number of output points	16 points
Rated load current	DC24V $\pm 10\%$
Maximum current	50mA/circuit
Insulation method	Photocoupler insulation



## Name of Each Part

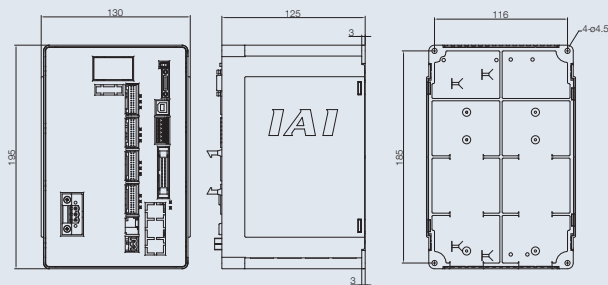


\*1: Do not connect a wrong motor to the MPG1, MPG2, MPG3 or MPG4 connector. It may cause malfunction or failure.

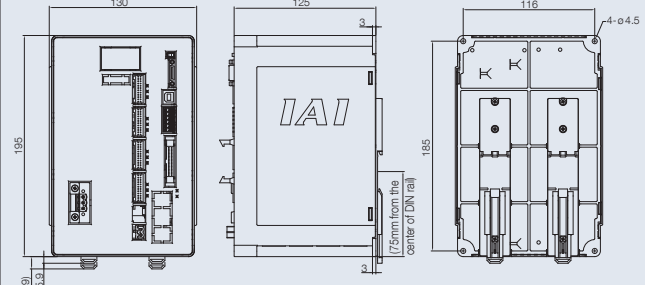
## External Dimensions

### Controller

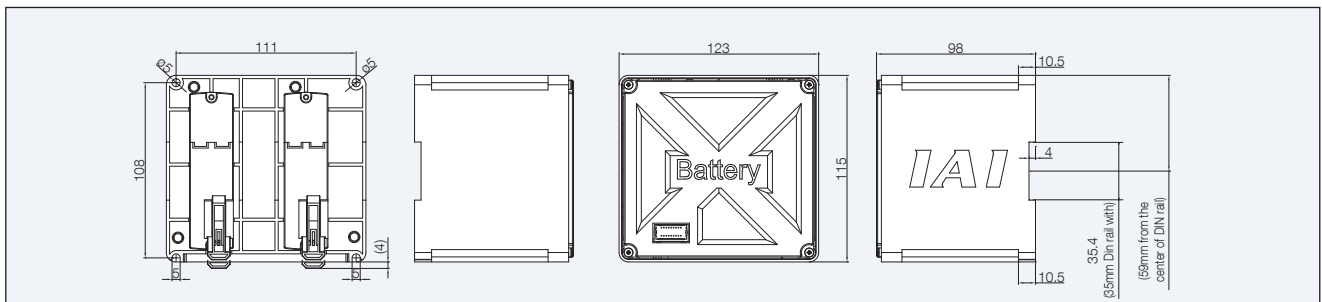
#### Screw mounting specification



#### DIN rail mounting specification



### Absolute Data Backup Battery Box





## Options

### Teaching Pendant

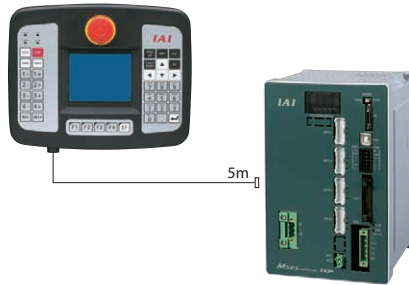
#### Features

A teaching device offering program/position input, trial operation and monitoring functions.

#### Model number **TB-01-SJ**

\* This model is the standard specification with connector conversion cable. If you are interested in the deadman switch specification, specify the model number of the applicable teaching pendant (TB-01D-N/TB-01DR-N) and that of the cable (CB-TB1-X050-JS).

#### Configuration



The MSEL-PC/PG are supported by Ver. 1.10 or later.

### Dummy Plug

#### Features

This plug is required for the safety category specification (MSEL-PG) and when the MSEL is operated using a USB cable. (The MSEL-PG type and PC compatible software IA-101-X-USBS come with this dummy plug.)

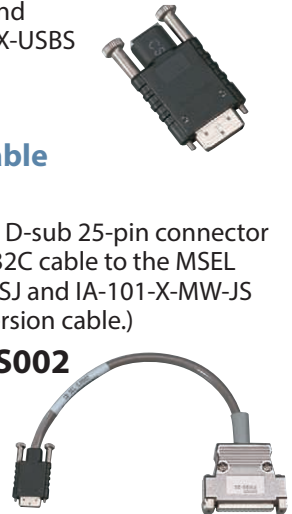
#### Model number **DP-4S**

### Connector Conversion Cable

#### Features

This cable is used to convert the D-sub 25-pin connector of the teaching pendant or RS232C cable to the MSEL teaching connector. (The TB-01-SJ and IA-101-X-MW-JS come with this connector conversion cable.)

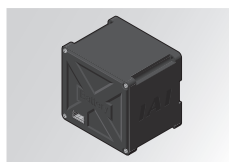
#### Model number **CB-SEL-SJS002**



### Absolute Data Backup Battery Box

#### Features

If the absolute position encoder specification is selected with code ABB, the absolute data backup battery box is included with the controller. However, if the battery box is ordered as a separate unit, it does not include the battery but just the box itself. If the battery is needed, please purchase it separately. (Model: AB-7).



#### Model number **MSEL-ABB** (Batteries not included)

#### Exterior dimensions See P.7

\* A cable (Model CB-MSEL-AB005) that connects the absolute data backup battery box to the MSEL is included with the box.

### Replacement Battery

#### Features

The replacement battery for the absolute data backup battery box.

#### Model number **AB-7**



\* Same quantity of absolute battery units is required as the number of axes.

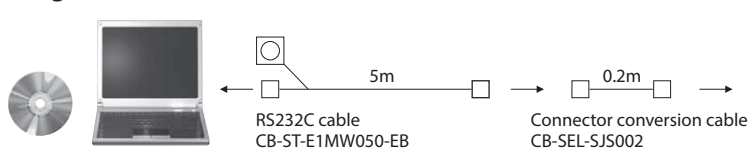
### PC Compatible Software (Windows Only)

#### Features

The startup support software provides program/position input, test operation and monitoring functions, among others. With its enhanced functions required for debugging, this software helps shorten the startup time.

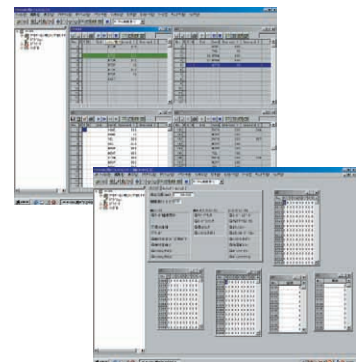
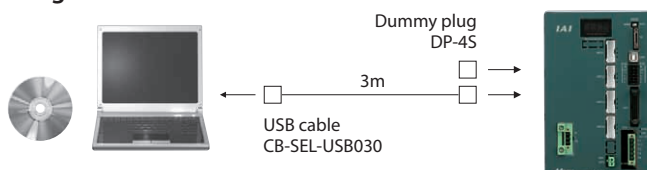
#### Model number **IA-101-X-MW-JS** (RS232C cable + Connector conversion cable)

#### Configuration



#### Model number **IA-101-X-USBS** (USB cable + Dummy plug)

#### Configuration

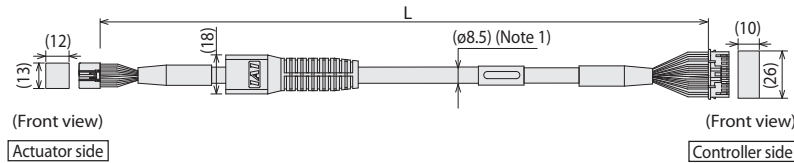


The MSEL-PC/PG are supported by Ver. 12.00.01.00 or later.

The CB-ST-E1MW050-EB cannot be used when "Building an enable system that uses a system I/O connector and external power supply" or "Building a redundant safety circuit." (The CB-ST-A1MW050-EB must be used instead.)

Model number	<b>CB-CAN-MPA</b> □□□	Integrated Motor-Encoder Cable	for RCP4-SA3/RA3/RCP5/RCD
	<b>CB-CAN-MPA</b> □□□-RB	Integrated Motor-Encoder Robot Cable	

\* Please indicate cable length (L) in □□□, maximum 20m. e.g.) 080 = 8m



Minimum bending radius 5m or less length R = 68mm or more (Dynamic bending condition)  
Longer than 5m R = 73mm or more (Dynamic bending condition)

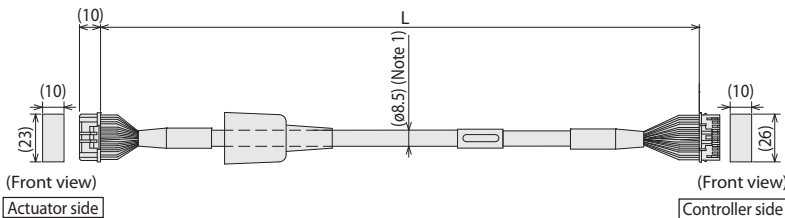
\* The robot cable is designed for flex-resistance: Please use the robot cable if the cable has to be installed through a cable track.

(Note 1) If the cable is 5m or longer, ø9.1 cable diameter applies for a non-robot cable and ø10 for a robot cable.

Pin No.	Signal name	Pin No.	Signal name
3	øA/U	1	øA/U
5	VMM/V	2	VMM/V
10	ø A/W	3	ø A/W
9	øB/-	4	øB/-
4	VMM/-	5	VMM/-
15	ø B/-	6	ø B/-
8	LS+/BK+	7	LS+/BK+
14	LS-/BK-	5	LS-/BK-
12	-/A+	11	-/A+
17	-/A-	12	-/A-
1	A+/B+	13	A+/B+
6	A-/B-	14	A-/B-
11	B+/Z+	15	B+/Z+
16	B-/Z-	16	B-/Z-
20	BK+/LS+	9	BK+/LS+
2	BK-/LS-	10	BK-/LS-
21	LS GND	17	LS GND
7	VPS	19	VPS
15	VCC	15	VCC
13	GND	20	GND
19	BAT+	22	BAT+
22	BAT+	23	BAT+
23	FG	24	FG

Model number	<b>CB-CA-MPA</b> □□□	Integrated Motor-Encoder Cable	for RCP4 (Excluding the RCP4-SA3/RA3)
	<b>CB-CA-MPA</b> □□□-RB	Integrated Motor-Encoder Robot Cable	

\* Please indicate cable length (L) in □□□, maximum 20m. e.g.) 080 = 8m



Minimum bending radius 5m or less length R = 68mm or more (Dynamic bending condition)  
Longer than 5m R = 73mm or more (Dynamic bending condition)

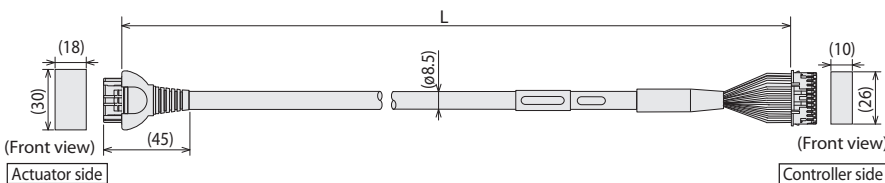
\* The robot cable is designed for flex-resistance: Please use the robot cable if the cable has to be installed through a cable track.

(Note 1) If the cable is 5m or longer, ø9.1 cable diameter applies for a non-robot cable and ø10 for a robot cable.

Pin No.	Signal name	Pin No.	Signal name
A1	øA/U	1	øA/U
B1	VMM/V	2	VMM/V
A2	ø A/W	5	ø A/W
B2	øB/-	4	øB/-
A3	VMM/-	6	VMM/-
B3	ø B/-	7	ø B/-
A4	LS+/BK+	8	LS+/BK+
B4	LS-/BK-	11	-/A+
A6	-/A+	12	-/A-
B6	-/A-	13	A+/B+
A7	A+/B+	14	A-/B-
B7	A-/B-	15	B+/Z+
A8	B+/Z+	16	B-/Z-
B8	B-/Z-	9	BK+/LS+
A5	BK+/LS+	10	BK-/LS-
B5	BK-/LS-	20	LS GND
A9	LS GND	17	VCC
B9	VPS	19	GND
A10	VCC	21	—
B10	GND	22	—
A11	—	23	—
B11	FG	24	FG

Model number	<b>CB-APSEP-MPA</b> □□□-LC	Integrated Motor-Encoder Cable	for RCP3/RCA2 and others
	<b>CB-APSEP-MPA</b> □□□	Integrated Motor-Encoder Robot Cable	

\* Please indicate cable length (L) in □□□, maximum 20m. e.g.) 080 = 8m



Minimum bending radius R = 68mm or more (Dynamic bending condition)

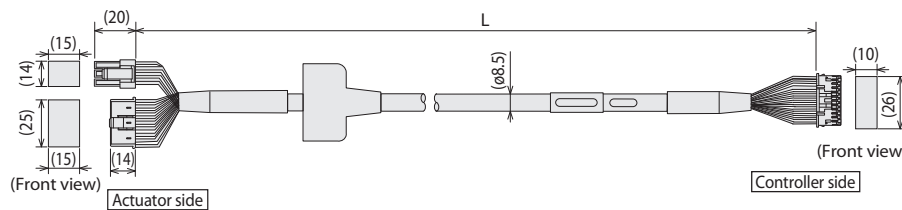
\* The robot cable is designed for flex-resistance: Please use the robot cable if the cable has to be installed through a cable track.

Actuator side		Controller side	
Pin No.			Pin No.
A1	(PCON) (ACON)		1
B1	(øA) (U)		2
A2	(VMM) (V)		3
B2	(øA) (W)		5
A3	(øB) (-)		4
B3	(VMM) (-)		6
A4	(øB) (-)		7
B4	(LS+) (BK+)		8
A6	(LS-) (BK-)		11
B6	(-) (A+)		12
A7	(-) (A-)		13
B7	(A+) (B+)		14
A8	(A-) (B-)		15
B8	(B+) (Z+)		16
A5	(B-) (Z-)		9
B5	(BK+) (LS+)		10
A9	(BK-) (LS-)		20
B9	(GNDLS) (GNDLS)		18
A10	(VPS) (VPS)		17
B10	(VCC) (VCC)		19
A11	(GND) (GND)		21
B11	NC		24
	Shield (FG) (FG)		22
	NC		23
			25

**Model number** **CB-PSEP-MPA**□□□ **Integrated Motor-Encoder Robot Cable** **for RCP2**

\* Only robot cable is available for this model

\* Please indicate cable length (L) in □□□, maximum 20m. e.g.) 080 = 8m

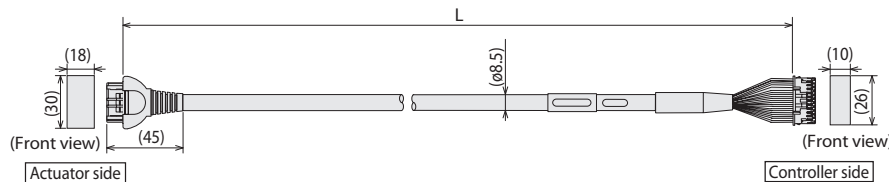


Actuator side Pin No.		Controller side Pin No.
1	[aA]	1
2	[VMM]	2
3	[aB]	3
4	[VMM]	4
5	[aA]	5
6	[aB]	6
7	[BK+]	7
8	[BK-]	10
9	NC	11
10	NC	12
11	[LS+]	7
12	[LS-]	8
13	[A+]	13
14	[A-]	14
15	[B+]	15
16	[B-]	16
17	[VCC]	17
18	[VPS]	18
19	[GND]	19
20	[Spare]	20
21	NC	21
22	NC	22
23	NC	23
24	Shield [FG]	24

**Model number** **CB-RPSEP-MPA**□□□ **Integrated Motor-Encoder Robot Cable** **for RCP2-RTBS/RTBSL/RTCS/RTCSL**

\* Only robot cable is available for this model

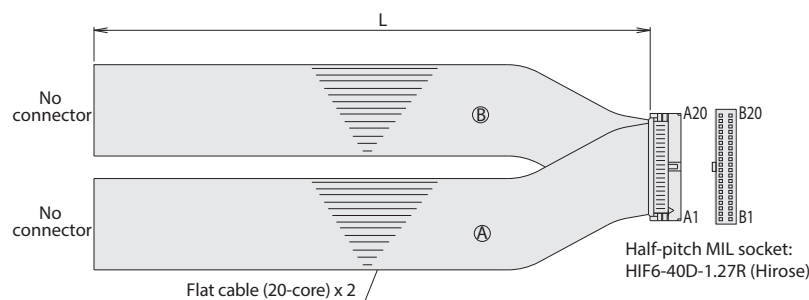
\* Please indicate cable length (L) in □□□, maximum 20m. e.g.) 080 = 8m



Actuator side Pin No.		Controller side Pin No.
A1	[aA]	1
B1	[VMM]	2
A2	[aA]	5
B2	[aB]	3
A3	[VMM]	4
B3	[aB]	6
A6	[LS+]	7
B6	[LS-]	8
A7	[A+]	13
B7	[A-]	14
A8	[B+]	15
B8	[B-]	16
A4	NC	—
B4	NC	9
A5	[BK+]	10
B5	[BK-]	11
A9	[GNDLS]	20
B9	[VCC]	18
A10	[VCC]	17
B10	[GND]	19
A11	NC	21
B11	NC	22
	Shield [FG] (FG)	23

**Model number** **CB-PAC-PIO**□□□ **PIO Flat Cable** **for MSEL/PCON-CA/MSEP-LC**

\* Please indicate cable length (L) in □□□, maximum 10m. e.g.) 080 = 8m



No.	Signal name	Cable color	Wiring	No.	Signal name	Cable color	Wiring
A1	24V	Brown-1	Flat cable (A) (crimped) AWG28	B1	OUT0	Brown-3	Flat cable (B) (crimped) AWG28
A2	24V	Red-1		B2	OUT1	Red-3	
A3	—	Orange-1		B3	OUT2	Orange-3	
A4	—	Yellow-1		B4	OUT3	Yellow-3	
A5	IN0	Green-1		B5	OUT4	Green-3	
A6	IN1	Blue-1		B6	OUT5	Blue-3	
A7	IN2	Purple-1		B7	OUT6	Purple-3	
A8	IN3	Gray-1		B8	OUT7	Gray-3	
A9	IN4	White-1		B9	OUT8	White-3	
A10	IN5	Black-1		B10	OUT9	Black-3	
A11	IN6	Brown-2		B11	OUT10	Brown-4	
A12	IN7	Red-2		B12	OUT11	Red-4	
A13	IN8	Orange-2		B13	OUT12	Orange-4	
A14	IN9	Yellow-2		B14	OUT13	Yellow-4	
A15	IN10	Green-2		B15	OUT14	Green-4	
A16	IN11	Blue-2		B16	OUT15	Blue-4	
A17	IN12	Purple-2		B17	—	Purple-4	
A18	IN13	Gray-2		B18	—	Gray-4	
A19	IN14	White-2		B19	0V	White-4	
A20	IN15	Black-2		B20	0V	Black-4	

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The information contained in this product brochure may change without prior notice due to product improvements.

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