

RCA2-TA4R

Robo Cylinder, Mini Table Type, Motor Unit Coupled Type, Actuator Width 40mm, 24V Servo Motor, Ball Screw Specification

Model Specification Items	RCA2 — TA4R — I — 10 — <input type="checkbox"/> — <input type="checkbox"/> — <input type="checkbox"/> — <input type="checkbox"/> — <input type="checkbox"/>
Series — Type	Encoder type — Motor type — Lead — Stroke — Applicable controller — Cable length — Options
	I: Incremental 10: 10W Servo motor * The Simple absolute encoder is also considered type "I". 6: 6mm 20: 20mm 4: 4mm 2: 2mm 100: 100mm (10mm pitch increments) A1: ACON ASEL A3: AMEC ASEP MSEP N: None P: 1m S: 3m M: 5m X□□: Custom Length See options below. * Be sure to specify which side the motor is to be mounted (ML/MR)
* See page Pre-47 for details on the model descriptions.	



Power-saving



Photo above shows the specification with TA3R motor side-mounted to the left (ML).

Technical References Appendix P.5



- (1) The payload is the value when the actuator is operated at an acceleration of 0.3 G (or 0.2G in the case of 2mm-lead and vertical usage). The upper limit for acceleration is 0.3G (or 0.2G in case of 2mm-lead and vertical usage).
- (3) See page A-71 for details on push motion.

Actuator Specifications

Leads and Payloads

Model number	Motor output (W)	Feed Screw	Lead (mm)	Max. Load Capacity		Rated thrust (N)	Positioning repeatability (mm)	Stroke (mm)
				Horizontal (kg)	Vertical (kg)			
RCA2-TA4R-I-10-6-①-②-③-④	10	Ball screw	6	1	0.5	28	±0.02	20~100 (every 10mm)
RCA2-TA4R-I-10-4-①-②-③-④			4	2	1	43		
RCA2-TA4R-I-10-2-①-②-③-④			2	3	1.5	85		

Stroke and Maximum Speed

Lead	Stroke	
	20~100 (every 10mm)	20~100 (every 10mm)
Ball screw	6	300
	4	200
	2	100

Code explanation ① Stroke ② Applicable Controller ③ Cable length ④ Options *See page A-71 for details on push motion. (Unit: mm/s)

① Stroke

① Stroke (mm)	Standard price
20	—
30	—
40	—
50	—
60	—
70	—
80	—
90	—
100	—

③ Cable Length

Type	Cable symbol	Standard price
Standard (Robot Cables)	P (1m)	—
	S (3m)	—
	M (5m)	—
Special length	X06 (6m) ~ X10 (10m)	—
	X11 (11m) ~ X15 (15m)	—
	X16 (16m) ~ X20 (20m)	—

*The standard cable for the RCA2 is the robot cable.
* See page A-59 for cables for maintenance.

④ Options

Name	Option code	See page	Standard price
Brake	B	→ A-42	—
Cable exit direction (top)	CJT	→ A-42	—
Cable exit direction (outside)	CJO	→ A-42	—
Cable exit direction (bottom)	CJB	→ A-42	—
Power-saving specification	LA	→ A-52	—
Side-mounted motor to the left (standard)	ML	→ A-52	—
Side-mounted motor to the right	MR	→ A-52	—
Non-motor end specification	NM	→ A-52	—

Actuator Specifications

Item	Description
Drive System	Ball screw, ø6mm, rolled C10
Lost Motion	0.1mm or less
Base	Material: Aluminum, white alumite treated
Allowable dynamic moment (*)	Ma: 4.2 N·m, Mb: 6 N·m, Mc: 8.2 N·m
Ambient operating temperature, humidity	0 to 40°C, 85% RH or less (Non-condensing)

(*) Based on 5,000km of traveling life

Directions of allowable load moments



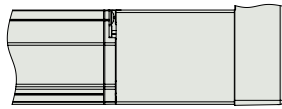
Dimensional Drawings

CAD drawings can be downloaded from the website. www.intelligentactuator.com

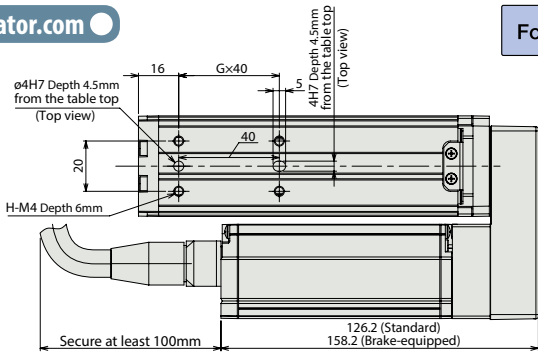
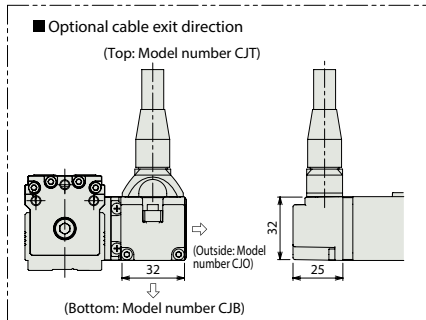
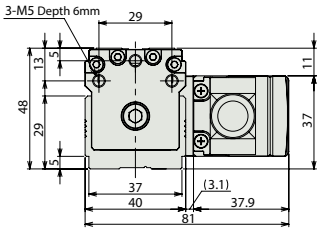
For Special Orders Appendix P.15



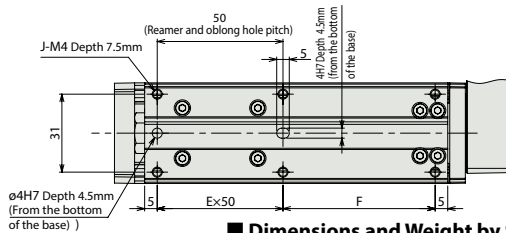
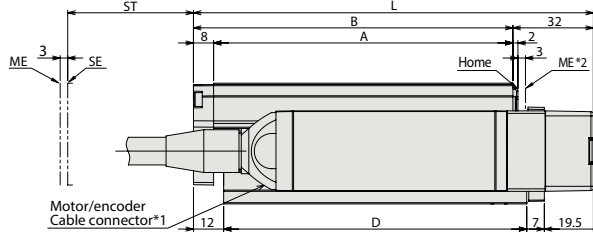
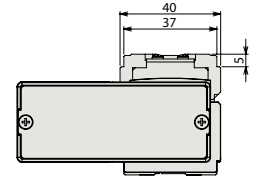
* The diagram below shows a left-mounted motor model.



With the brake:
(see drawing on the right for dimensions)



The offset reference position of the moment is the same as TA4C (P336).



ST : Stroke
ME : Mechanical end
SE : Stroke end

* Brake-equipped models are heavier by 0.2kg.

Dimensions and Weight by Stroke

Stroke	20	30	40	50	60	70	80	90	100
L	129	139	149	159	169	179	189	199	209
A	89	99	109	119	129	139	149	159	169
B	97	107	117	127	137	147	157	167	177
D	90.5	100.5	110.5	120.5	130.5	140.5	150.5	160.5	170.5
E	1	1	1	1	2	2	2	2	2
F	30.5	40.5	50.5	60.5	20.5	30.5	40.5	50.5	60.5
G	1	1	1	1	2	2	2	2	2
H	4	4	4	4	6	6	6	6	6
J	6	6	6	6	8	8	8	8	8
Weight (kg)	0.8	0.9	0.9	0.9	1.0	1.0	1.0	1.1	1.1

(*1) Connect the motor-encoder integrated cable here. See page A-59 for details on cables.
(*2) After homing, the slider moves to the ME, therefore, please watch for any interference with surrounding objects.

Applicable Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application. * ACON-CY also can be used.

Name	External view	Model number	Features	Maximum number of positioning points	Input power	Power-supply capacity	Standard price	Reference page
Solenoid Valve Type		AMEC-C-10I①-②-2-1	Easy-to-use controller, even for beginners	3 points	AC100V	2.4A rated	—	→ P537
		ASEP-C-10I①-②-2-0	Simple controller operable with the same signal as a solenoid valve					→ P547
Solenoid valve multi-axis type PIO specification		MSEP-C-③④⑤⑥⑦⑧⑨⑩-②-0	Positioner type based on PIO control, allowing up to 8 axes to be connected	256 points	DC24V	(Standard) 1.3A rated 4.4A max.	—	→ P563
Solenoid valve multi-axis type Network specification		MSEP-C-③④⑤⑥⑦⑧⑨⑩-V-0-0	Field network-ready positioner type, allowing up to 8 axes to be connected					→ P631
Positioner type		ACON-C-10I①-②-2-0	Positioning is possible for up to 512 points	512 points	DC24V	(Power-saving) 1.3A rated 2.5A max.	—	—
Safety-Compliant Positioner Type		ACON-CG-10I①-④-2-0						
Pulse Train Input Type (Differential Line Driver)		ACON-PL-10I①-②-2-0	Pulse train input type with differential line driver support	(-)	DC24V	(Power-saving) 1.3A rated 2.5A max.	—	→ P631
Pulse Train Input Type (Open Collector)		ACON-PO-10I①-②-2-0	Pulse train input type with open collector support					
Serial Communication Type		ACON-SE-10I①-N-0-0	Dedicated Serial Communication	64 points	DC24V	(Power-saving) 1.3A rated 2.5A max.	—	—
Program Control Type		ASEL-CS-1-10I①-②-2-0	Programmed operation is possible. Can operate up to 2 axes	1,500 points	DC24V	(Power-saving) 1.3A rated 2.5A max.	—	→ P675

* This is for the single-axis ASEL. * Enter the code "LA" in ① when the power-saving specification is specified. * ① indicates I/O type (NP/PN). * ③④⑤⑥⑦⑧⑨⑩ indicates number of axes (1 to 8). * V indicates field network specification symbol.

Slider Type

Mini

Standard

Controllers Integrated

Rod Type

Mini

Standard

Controllers Integrated

Table/Arm/Flat Type

Mini

Standard

Gripper/Rotary Type

Linear Servo Type

Clean-room Type

Splash-Proof Type

Pulse Motor

Servo Motor (24V)

Servo Motor (200V)

Linear Servo Motor