

RCS2-RA4C

Robo Cylinder, Rod Type, ø37mm Diameter, 200V Servo Motor, Coupled

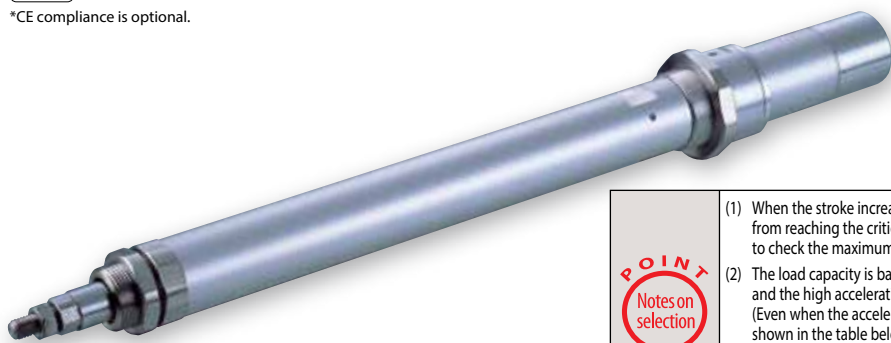
Model Specification Items	RCS2 — RA4C	—	Encoder type	—	Motor type	—	Lead	—	Stroke	—	Applicable controller	—	Cable length	—	Options
	Series — Type		I: Incremental A: Absolute		20:20W Servo motor 30:30W Servo motor		12: 12mm 6: 6mm 3: 3mm		50: 50mm 300: 300mm (50mm pitch increments)		T1: XSEL-J/K T2: SCON MSCON SSEL XSEL-P/Q XSEL-R/S		N: None P: 1m S: 3m M: 5m X□□: Custom Length R□□: Robot Cable		See options below.

* See page Pre-47 for details on the model descriptions.



*CE compliance is optional.

For High Acceleration/Deceleration (*1)



(*1) Except all 20W models and 30W 3mm lead models

Technical References Appendix P.5



- (1) When the stroke increases, the maximum speed will drop to prevent the ball screw from reaching the critical rotational speed. Use the actuator specification table below to check the maximum speed at the stroke you desire.
- (2) The load capacity is based on operation of the standard model at 0.3G (0.2G for 3mm-lead), and the high acceleration/deceleration model at 1G (excluding the 3mm-lead model). (Even when the acceleration/deceleration is dropped, the maximum load capacity values shown in the table below are the upper limits.)
- (3) The values for the horizontal load capacity assume the use of an external guide, so that there is no external force from any direction other than the forward/backward direction of the rod.
- (4) See page A-71 for details on push motion.

Actuator Specifications

Leads and Payloads

Model number	Motor output (W)	Lead (mm)	Max. Load Capacity		Rated thrust (N)	Stroke (mm)
			Horizontal (kg)	Vertical (kg)		
RCS2-RA4C-①-20-12-②-③-④-⑤	20	12	3.0	1.0	18.9	50~300 (every 50mm)
RCS2-RA4C-①-20-6-②-③-④-⑤		6	6.0	2.0	37.7	
RCS2-RA4C-①-20-3-②-③-④-⑤		3	12.0	4.0	75.4	
RCS2-RA4C-①-30-12-②-③-④-⑤	30	12	4.0	1.5	28.3	
RCS2-RA4C-①-30-6-②-③-④-⑤		6	9.0	3.0	56.6	
RCS2-RA4C-①-30-3-②-③-④-⑤		3	18.0	6.5	113.1	

Stroke and Maximum Speed

Lead	Stroke	50~300 (every 50mm)
		12
6		300
3		150

(Unit: mm/s)

Code explanation ① Encoder ② Stroke ③ Applicable controller ④ Cable length ⑤ Options *See page A-71 for details on push motion.

① Encoder Type/② Stroke

② Stroke (mm)	Standard price			
	① Encoder Type			
	Incremental		Absolute	
	Motor Output (W)		Motor Output (W)	
	20W	30W	20W	30W
50	—	—	—	—
100	—	—	—	—
150	—	—	—	—
200	—	—	—	—
250	—	—	—	—
300	—	—	—	—

⑤ Options

Name	Option code	See page	Standard price
Brake	B	→ A-42	—
CE compliance	CE	→ A-42	—
Foot bracket	FT	→ A-49	—
Flange bracket (front)	FL	→ A-45	—
Flange bracket (back)	FLR	→ A-47	—
High-acceleration/deceleration (*1)	HA	→ A-50	—
Home sensor (*2)	HS	→ A-50	—
Knuckle joint	NJ	→ A-53	—
Non-motor end specification	NM	→ A-52	—
Trunnion bracket (front)	TRF	→ A-57	—
Trunnion bracket (back)	TRR	→ A-58	—

(*1) The high-acceleration/deceleration option is not available for all 20W models and 30W model with 3mm lead.
(*2) The home sensor (HS) cannot be used on the non-motor end models.

④ Cable Length

Type	Cable symbol	Standard Price
Standard	P (1m)	—
	S (3m)	—
	M (5m)	—
Special length	X06 (6m) ~ X10 (10m)	—
	X11 (11m) ~ X15 (15m)	—
	X16 (16m) ~ X20 (20m)	—
Robot Cable	R01 (1m) ~ R03 (3m)	—
	R04 (4m) ~ R05 (5m)	—
	R06 (6m) ~ R10 (10m)	—
	R11 (11m) ~ R15 (15m)	—
	R16 (16m) ~ R20 (20m)	—

* See page A-59 for cables for maintenance.

Actuator Specifications

Item	Description
Drive System	Ball screw, ø10mm, rolled C10
Positioning Repeatability	±0.02mm
Lost Motion	0.1mm or less
Base	Material: Aluminum, white alumite treated
Rod diameter	ø20mm
Non-rotating accuracy of rod	±1.0 deg
Ambient operating temperature, humidity	0 to 40°C, 85% RH or less (Non-condensing)

Dimensional Drawings

CAD drawings can be downloaded from the website.

www.intelligentactuator.com

For Special Orders

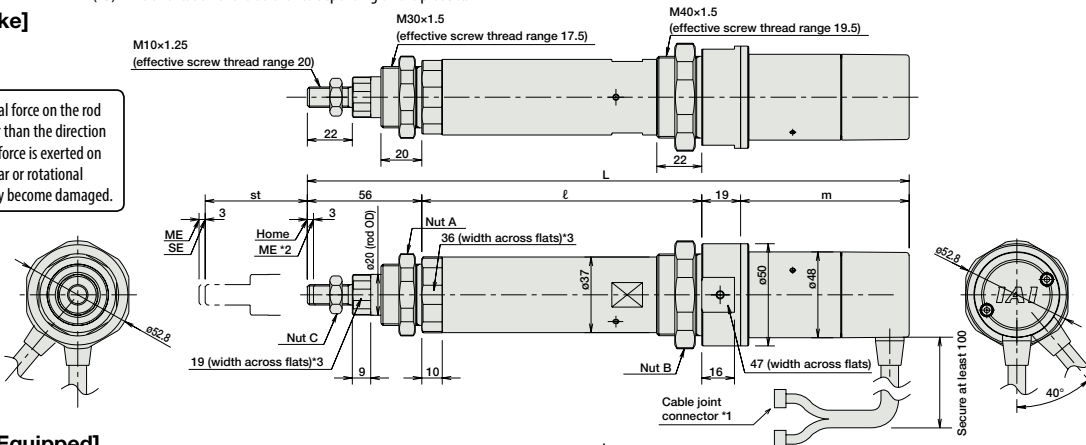
Appendix P.15



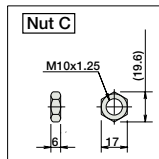
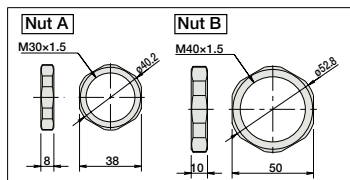
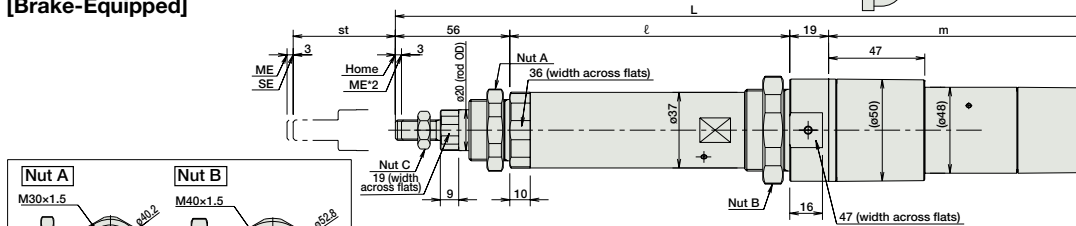
- (*1) Connect the motor and encoder cables here. See page A-59 for details on cables.
- (*2) After homing, the slider moves to the ME, therefore, please watch for any interference with surrounding objects.
ME: Mechanical end SE: Stroke end
- (*3) The orientation of the bolt varies depending on the product.

[No Brake]

Note:
Do not apply any external force on the rod from any direction other than the direction of the rod's motion. If a force is exerted on the rod in a perpendicular or rotational direction, the detent may become damaged.



[Brake-Equipped]



■ Dimensions and Weight by Stroke

RCS2-RA4C (without brake)

Stroke	50	100	150	200	250	300	
L	20W	292.5	342.5	392.5	442.5	492.5	542.5
	30W	307.5	357.5	407.5	457.5	507.5	557.5
l		137	187	237	287	337	487
m	20W	80.5					
	30W	95.5					
Weight (kg)		1.1	1.2	1.4	1.5	1.7	1.8

RCS2-RA4C (with brake)

Stroke	50	100	150	200	250	300	
L	20W	335.5	385.5	435.5	485.5	535.5	585.5
	30W	350.5	400.5	450.5	500.5	550.5	600.5
l		137	187	237	287	337	487
m	20W	123.5					
	30W	138.5					
Weight (kg)		1.3	1.5	1.6	1.7	1.9	2.0

③ Applicable Controllers

RCS2-series actuators can be operated with the following controllers. Select an appropriate controller type according to your application.

Name	External view	Model number	Features	Maximum number of positioning points	Input power	Power supply capacity	Standard price	Reference page
Positioner mode		SCON-CA-20①-NP-2-② SCON-CA-30D①-NP-2-②	Up to 512 positioning points are supported.	512 points	Single-phase 100VAC Single-phase 200VAC 3-phase 200VAC (XSEL-P/Q/R/S ONLY)	126 VA max. *Power supply capacity will vary depending on the controller, so please refer to the instruction manual for details.	—	→ P643
Solenoid valve mode			Actuators can be operated through the same control used for solenoid valves.	7 points				
Field network type			Movement by numerical specification is supported.	768 points				
Pulse-train input control type			Dedicated pulse-train input type	(—)				
Positioner multi-axis, network type		MSCON-C-1-20①-V-0-② MSCON-C-1-30D①-V-0-②	Up to 6 axes can be operated. Movement by numerical specification is supported.	256 points			—	→ P655
Program control type, 1 to 2 axes		SSEL-CS-1-20①-NP-2-② SSEL-CS-1-30D①-NP-2-②	Program operation is supported. Up to 2 axes can be operated.	20,000 points			—	→ P685
Program control type, 1 to 8 axes		XSEL-③-1-20①-N1-EEE-2-④ XSEL-③-1-30D①-N1-EEE-2-④	Program operation is supported. Up to 8 axes can be operated.	Varies depending on the number of axes connected			—	→ P695

* This is for the single-axis MSCON, SSEL, and XSEL.

* ① indicates the power-supply voltage type (1: 100V / 2: Single-phase 200V).

* ② indicates the power-supply voltage type (1: 100V / 2: Single-phase 200V / 3: Three-phase 200V).

* ③ indicates the encoder type (I: Incremental / A: Absolute).

* ④ indicates the XSEL type (J / K / P / Q / R / S).

* ⑤ indicates field network specification symbol.

Slider Type

Mini

Standard

Controllers Integrated

Rod Type

Mini

Standard

Controllers Integrated

Table/ Arm/ Flat Type

Mini

Standard

Gripper/ Rotary Type

Linear Servo Type

Clean-room Type

Splash-Proof Type

Pulse Motor

Servo Motor (24V)

Servo Motor (200V)

Linear Servo Motor