

EC-RR6

Radial Cylinder Motor Unit Type Coupled Motor Body Width 63 mm 24v Stepper Motor

Model Specification Items

EC Series — **RR6** Type

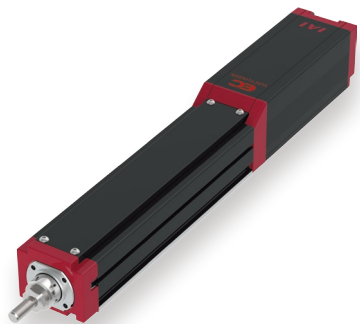
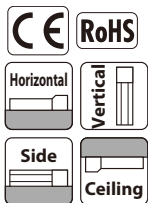
Lead: S: 20mm, H: 12mm, M: 6mm, L: 3mm

Stroke: 65: 65mm, 315: 315mm (Every 50mm)

Cable Length: 0: With terminal block type connector, 1: 1m, 10: 10m

Options: Refer to Options below.

* Please refer to P.16 for more information about the model specification items.



* Depending on the model, there may be some limitations to using the vertical, side, and ceiling mount positions. Please contact IAI for more information regarding mounting positions.

Table of Payload by Speed/Acceleration

| Lead 20 | | | | | | | Lead 12 | | | | | | |
|--------------|------------------|-----|-----|----------|-----|-----|--------------|------------------|-----|-----|----------|-----|-----|
| Orientation | Horizontal | | | Vertical | | | Orientation | Horizontal | | | Vertical | | |
| | Acceleration (G) | | | | | | | Acceleration (G) | | | | | |
| Speed (mm/s) | 0.3 | 0.5 | 0.7 | 1 | 0.3 | 0.5 | Speed (mm/s) | 0.3 | 0.5 | 0.7 | 1 | 0.3 | 0.5 |
| 0 | 6 | 6 | 5 | 5 | 1.5 | 1.5 | 0 | 25 | 18 | 16 | 12 | 4 | 4 |
| 160 | 6 | 6 | 5 | 5 | 1.5 | 1.5 | 100 | 25 | 18 | 16 | 12 | 4 | 4 |
| 320 | 6 | 6 | 5 | 3 | 1.5 | 1.5 | 200 | 25 | 18 | 16 | 10 | 4 | 4 |
| 480 | 6 | 6 | 5 | 3 | 1.5 | 1.5 | 400 | 20 | 14 | 10 | 6 | 4 | 4 |
| 640 | 6 | 4 | 3 | 2 | 1.5 | 1.5 | 500 | 12 | 8 | 6 | 4 | 3.5 | 3 |
| 800 | 4 | 3 | | | 1 | 1 | 700 | 6 | 2 | | | 2 | 1 |

- POINT Selection Notes**
- The maximum acceleration/deceleration is 1G for horizontal, and 0.5G for vertical use.
 - The actuator specifications display the payload's maximum value, but it will vary depending on the acceleration and speed. Please refer to "Table of Payload by Speed/Acceleration" at right for more details.
 - The value of the horizontal payload assumes that there is an external guide.
 - When performing push-motion operation, refer to P.65.
 - Depending on the ambient operating temperature, duty control is necessary. Please refer to P.67 for more information.
 - The radial cylinder is equipped with a built-in guide. For the radial load acting on the rod, refer to P.64.
 - The power capacity can be reduced according to the setting. Please refer to P.63 for the relevant "Table of Payload by Speed/Acceleration."
 - For the relationship between rod deflection and load on rod tip, refer to P.66.

| Lead 6 | | | | | | | Lead 3 | | | | | | |
|--------------|------------------|------|------|----------|-----|-----|--------------|------------------|-----|-----|----------|------|------|
| Orientation | Horizontal | | | Vertical | | | Orientation | Horizontal | | | Vertical | | |
| | Acceleration (G) | | | | | | | Acceleration (G) | | | | | |
| Speed (mm/s) | 0.3 | 0.5 | 0.7 | 1 | 0.3 | 0.5 | Speed (mm/s) | 0.3 | 0.5 | 0.7 | 1 | 0.3 | 0.5 |
| 0 | 40 | 35 | 30 | 25 | 10 | 10 | 0 | 60 | 50 | 45 | 40 | 12.5 | 12.5 |
| 50 | 40 | 35 | 30 | 25 | 10 | 10 | 50 | 60 | 50 | 45 | 40 | 12.5 | 12.5 |
| 100 | 40 | 35 | 30 | 25 | 10 | 10 | 100 | 60 | 50 | 45 | 40 | 12.5 | 12.5 |
| 200 | 40 | 30 | 25 | 20 | 10 | 10 | 125 | 60 | 50 | 40 | 30 | 10 | 10 |
| 250 | 40 | 27.5 | 22.5 | 18 | 9 | 8 | 175 | 40 | 35 | 25 | 20 | 6 | 5 |
| 350 | 30 | 14 | 12 | 10 | 5 | 5 | 200 | 35 | 30 | 20 | 14 | 5 | 4.5 |
| 400 | 18 | 10 | 6 | 5 | 3 | 3 | 225 | 16 | 16 | 10 | 6 | 5 | 4 |
| 450 | 8 | 3 | | | 2 | 1 | | | | | | | |

Actuator Specifications

| Lead and Payload | | | | | Stroke and Max Speed (Unit: mm/s) | | | |
|------------------|-----------|-----------------|---------------|----------------------|-----------------------------------|---------------------|----------|-----|
| Model number | Lead (mm) | Max. payload | | Max. push force (N)* | Lead (mm) | 65~215 (Every 50mm) | | |
| | | Horizontal (kg) | Vertical (kg) | | | 265 (mm) | 315 (mm) | |
| EC-RR6S-①-②-③ | 20 | 6 | 1.5 | 56 | 20 | 800 | | |
| EC-RR6H-①-②-③ | 12 | 25 | 4 | 93 | 12 | 700 | 660 | 480 |
| EC-RR6M-①-②-③ | 6 | 40 | 10 | 185 | 6 | 450 | 325 | 235 |
| EC-RR6L-①-②-③ | 3 | 60 | 12.5 | 370 | 3 | 225 | 160 | 115 |

Legend: ① Stroke ② Cable Length ③ Option *Speed limitation applies to push motion. See the manual or contact IAI.

① Stroke

| ① Stroke (mm) | EC-RR6 | ① Stroke (mm) | EC-RR6 |
|---------------|--------|---------------|--------|
| 65 | ○ | 215 | ○ |
| 115 | ○ | 265 | ○ |
| 165 | ○ | 315 | ○ |

② Cable Length

| Cable code | Cable length |
|------------|---------------------------|
| 0 | No cable (with connector) |
| 1~3 | 1~3m |
| 4~5 | 4~5m |
| 6~10 | 6~10m |

③ Options

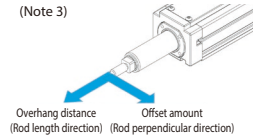
| Name | Option code | Reference page | Name | Option code | Reference page |
|---|-------------|----------------|--|-------------|----------------|
| Brake | B | See P.59 | Non-motor end specification | NM | See P.62 |
| Tip adapter (flange) | FFA | See P.59 | PNP specification | PN | See P.62 |
| Flange (front) | FL | See P.59 | Clevis bracket (Note 1) | QR | See P.62 |
| Foot bracket | FT | See P.60 | Clevis bracket + oscillation receiving bracket | QRPB | See P.62 |
| Tip adapter (internal thread) | NFA | See P.61 | Battery-less Absolute Encoder specification | WA | See P.62 |
| Knuckle joint (Note 1) | NJ | See P.61 | Wireless communication specification | WL | See P.62 |
| Knuckle joint + oscillation receiving bracket | NJPB | See P.61 | | | |

(Note 1) The clevis (QR) and knuckle joint (NJ) are sold as a set. The assembly is to be performed by the customer.

Actuator Specifications

| Item | Description |
|--|--|
| Drive system | Ball screw φ10mm, rolled C10 |
| Positioning repeatability | ±0.05mm |
| Rod | φ25mm Material: Aluminum, hard alumite treatment |
| Rod non-rotation precision (Note 2) | 0 degrees |
| Rod tip static allowable torque | 5.5N·m |
| Rod tip allowable overhang distance (Note 3) | 100mm |
| Rod tip allowable offset amount (Note 3) | 100mm |
| Ambient operating temperature/humidity | 0 to 40°C, 85% RH or less (Non-condensing) |

(Note 2) Rod rotating direction displacement angle with no load. (Note 3)

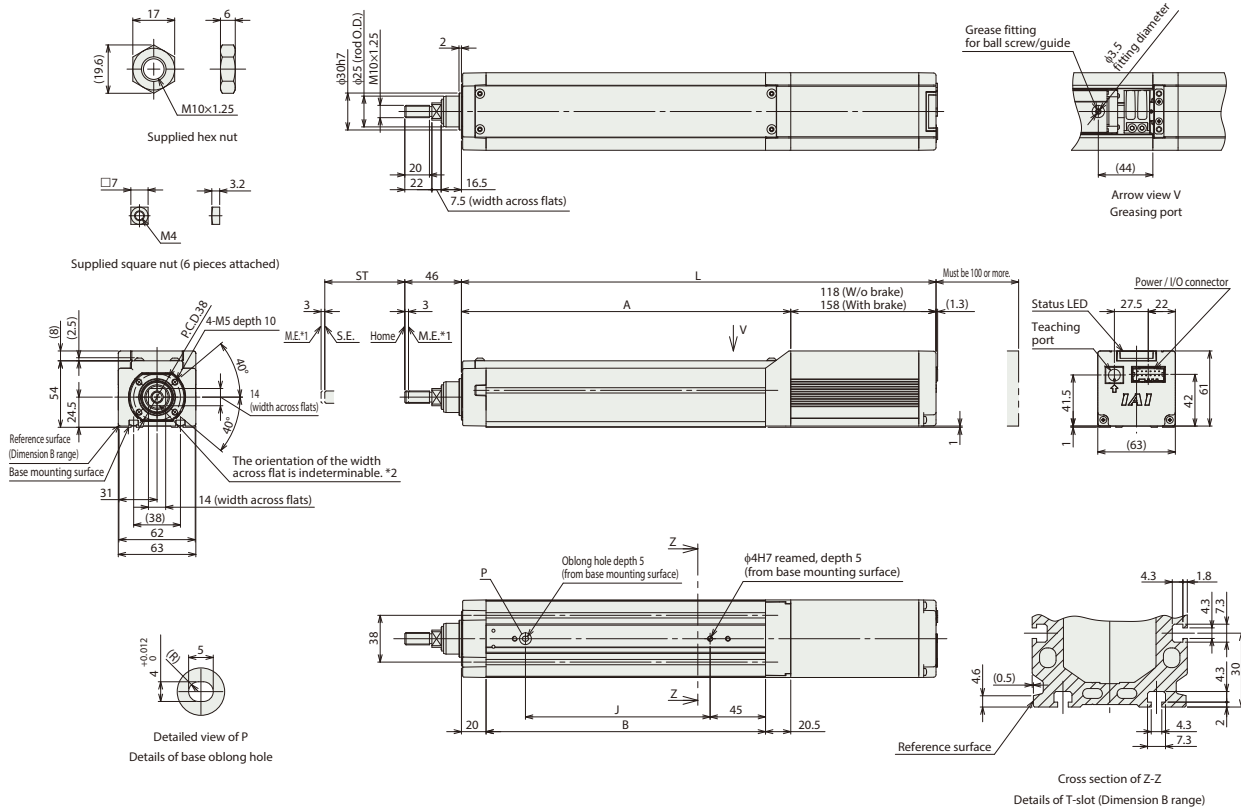


Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.com



*1 When the rod is returning to its home position, please be careful of interference from surrounding objects, as it will travel until it reaches the M.E.
M.E: Mechanical end S.E: Stroke end
*2 The direction of width across flats varies depending on the product. Those flats cannot be used for reference plane.



Dimensions and Mass by Stroke

| Stroke | 65 | 115 | 165 | 215 | 265 | 315 | |
|-------------|------------|-------|-------|-------|-------|-------|-------|
| L | W/o Brake | 335.5 | 385.5 | 435.5 | 485.5 | 535.5 | 585.5 |
| | With Brake | 375.5 | 425.5 | 475.5 | 525.5 | 575.5 | 625.5 |
| A | 217.5 | 267.5 | 317.5 | 367.5 | 417.5 | 467.5 | |
| B | 177 | 227 | 277 | 327 | 377 | 427 | |
| J | 100 | 150 | 200 | 250 | 300 | 350 | |
| Weight (kg) | W/o Brake | 1.7 | 2.0 | 2.2 | 2.5 | 2.7 | 3.0 |
| | With Brake | 1.9 | 2.2 | 2.4 | 2.7 | 3.0 | 3.2 |

Controller side Options/Accessories

| Name | Touch Panel Teaching Pendant | PC software | 24VDC power supply |
|---------------|--|---|---|
| External view | | | |
| Model | <input type="checkbox"/> TB-02 (for wired connection only) <input type="checkbox"/> TB-03 (for wired/wireless connection) | <input type="checkbox"/> RCM-101-MW (RS232 connection version) <input type="checkbox"/> RCM-101-USB (USB connection version) | <input type="checkbox"/> PS-241 (100V input) <input type="checkbox"/> PS-242 (200V input) |
| Overview | <ul style="list-style-type: none"> ● TB-02 A teaching pendant equipped with functions such as start point, end point, and AVD input, trial operation, and monitoring. ● TB-03 A data setter that supports wireless connection. The start point, end point and AVD can be input with wireless connection. | Software for start point input, end point input and AVD input, trial operation, and monitoring using a PC. Both the RS232C version and USB version are available for PC connection. | A 24VDC power supply that can instantaneously output up to 17A. Input voltage 200VAC and 100VAC specifications are available. |

* For system configurations using the above tools, refer to P.68.