

ROBO NET

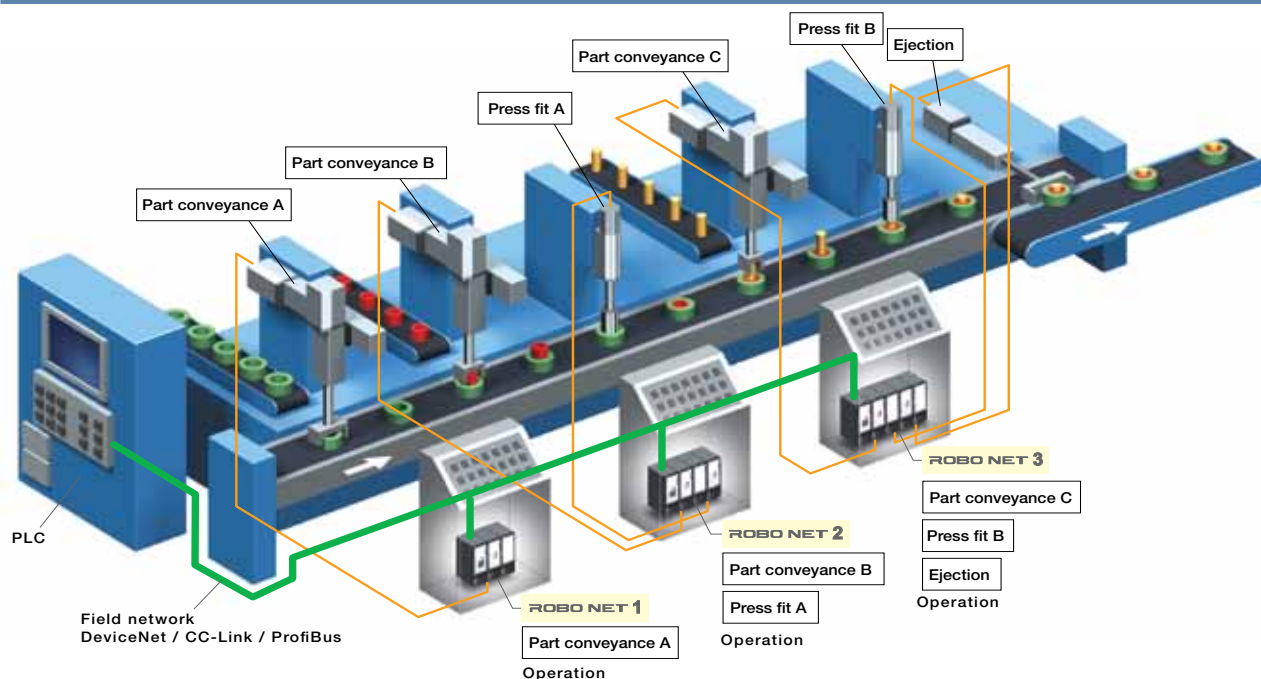
■ Model :RGW-□/RACON/RPCON/RABU/REXT

For RCA2/RCA/RCL/RCP3/RCP2
Network Controller



ROBONET is a new type of control unit that freely operates ROBO Cylinders via a field network. They have less wiring and are more compact than past controllers, and by DIN rail mounting make it possible to vastly reduce wiring and installation labor.

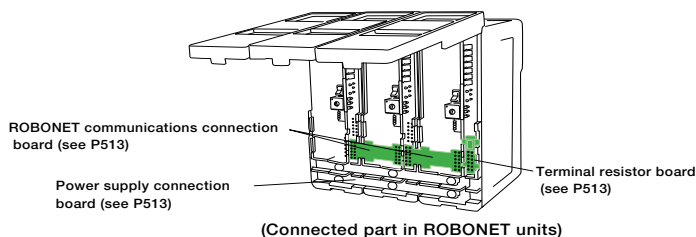
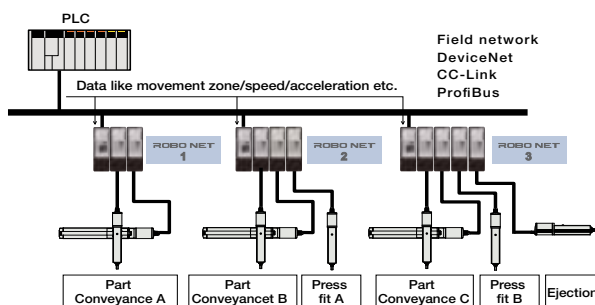
Features



1

Reduced Wiring

By connecting each line of the I/O cables to lines wired to the PLC terminals with the field network, wiring processing is completed with one dedicated cable. Also, since the unit can be coupled by just connecting with the unit connection board, the controller wiring work is greatly simplified.



2 The robot can be moved by directly specifying numeric values for the move position/velocity/acceleration and other data.

Besides the conventional method of moving the robot to pre-taught positions it is also possible to operate the robot by sending information as a string of numeric data that contains position, velocity, acceleration, etc. values. This is effective for cases such as when the move position changes with each piece or when one wants to move the robot to an arbitrary position.

	ROBONET controller	Standard controller (ACON/PCON)
Movement by specifying positions	○	○
Movement by specifying direct values	○	△
Specifying speed/acceleration	○	(Not for PIO)
Current value output	○	(Connectable with serial communication)

*ROBONET operates through a field network, and the standard controller operates with PIO.

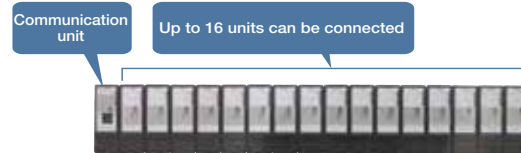
3 Ultra-compact

Each unit is an ultra-compact size of 34mm wide by 100mm high x 73mm deep. Also, since there is no base unit and the main unit is coupled with connectors, the controller takes up little space for installation even if there are many units.



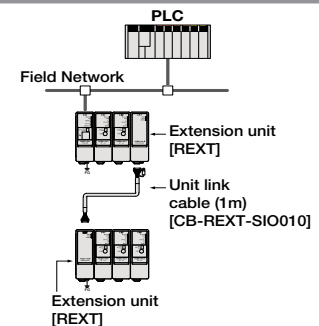
4 Can operate with a maximum of 16 axes.

Up to 16 controllers can be connected to one communication unit (Gateway R unit). RACON units (controllers for RCA) and RPCON units (controllers for RCP2) can also be used together.



5 Controllers can be multiplexed.

Controllers can be multiplexed using an optional extension unit, so many axes can be connected even if there isn't much horizontal space. Also, non-ROBONET controllers (SCON, PCON-CF, ERC2) can be connected to a ROBONET Gateway unit using the same extension unit.



6 Simple absolute unit, when home return is not required

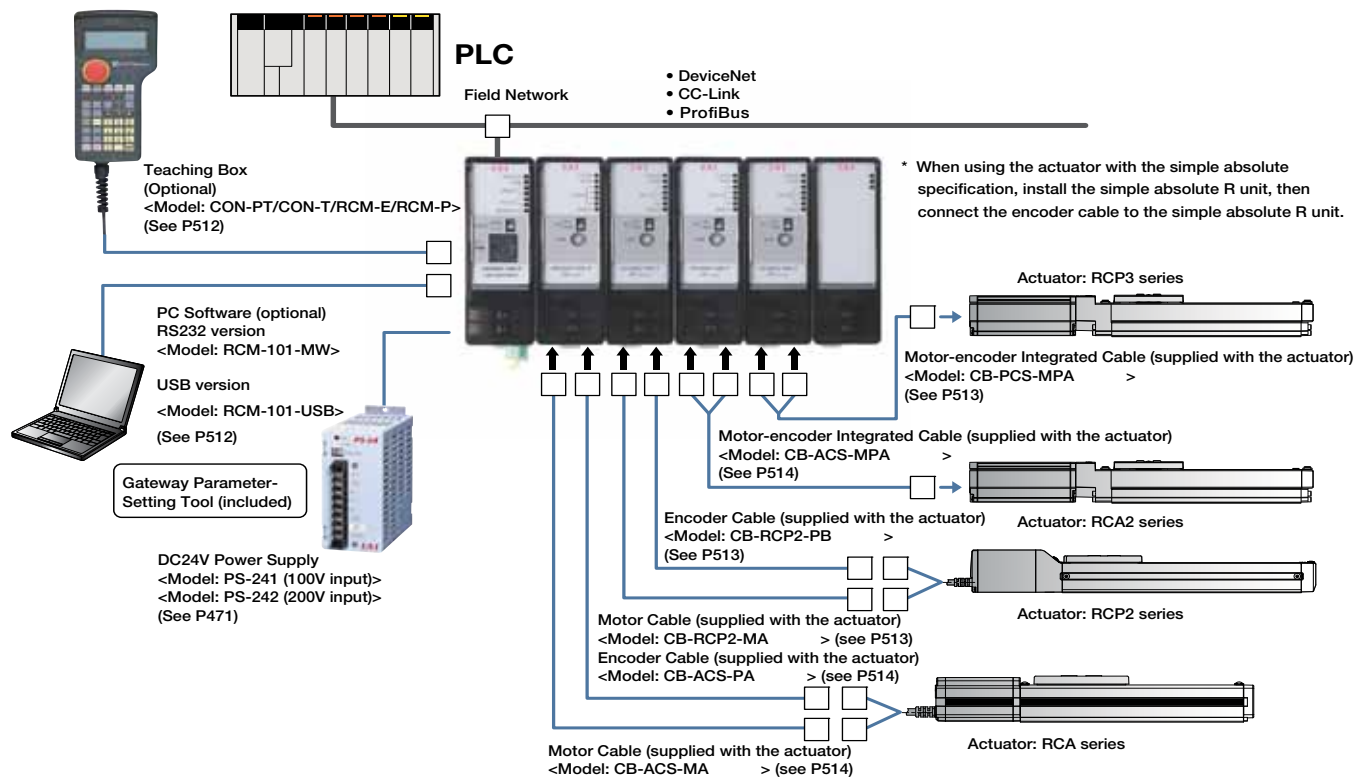
The simple absolute R unit allows operation for incremental specification axes without home return. Users can back up actuator encoder data even if the power is shut off, by installing a simple absolute R unit to a RACON unit (controller for RCA) or RPCON unit (controller for RCP2).



7 Mounting the DIN rail

The controller is installed with DIN rails, so it can be fastened and removed with one touch.

System configuration



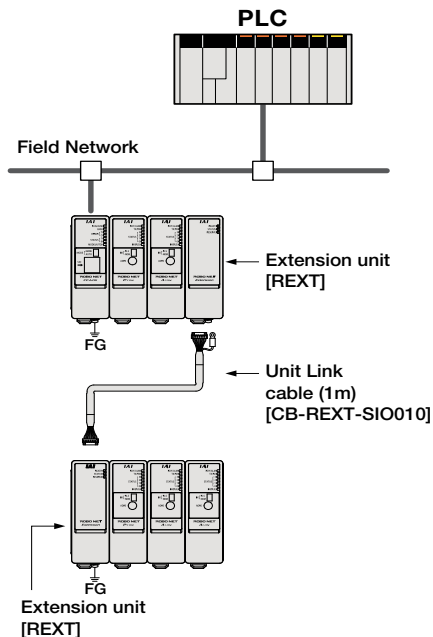
ROBONET Extension Unit

If multiple ROBONET extension units (optional) are linked together they can reduce the lateral width needed. It is also possible to connect individual controllers, such as SCON, etc. via the ROBONET.

[Unit Multiplex Set] Model: REXT-SIO

(Set Contents)

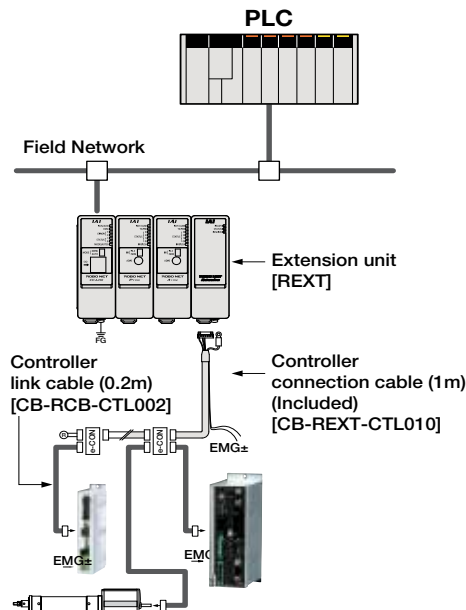
ROBONET Extension Unit (Model: REXT) 2 pc
Unit Link Cable (Model: CB-REXT-SIO010) 1 pc



[Controller Connecting Set] Model: REXT-CTL

(Set Contents)

ROBONET Extension Unit (Model: REXT) 1 pc
Controller Connection Cable (Model: CB-REXT-CTL010) 1 pc



Configuration unit

Required ROBONET units are ordered individually, and assembled as you see fit. If actuators are added later, they can be easily added simply by adding a RACON/RPCON unit.



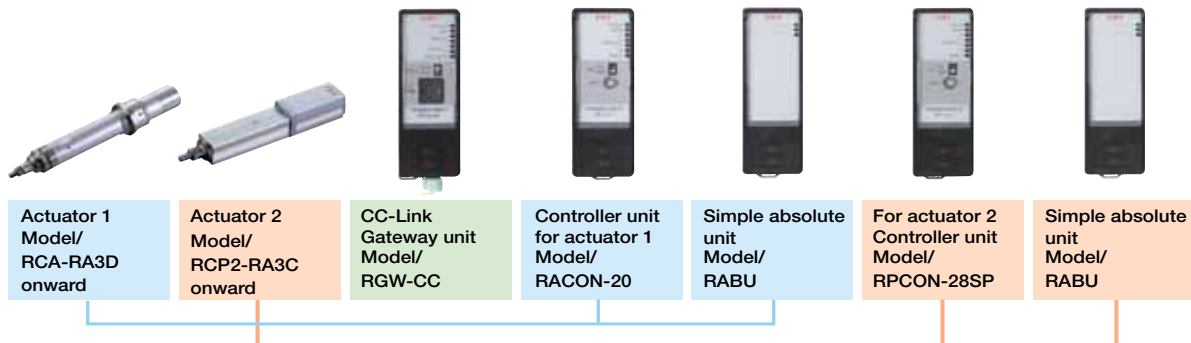
Gateway R unit RACON unit RPCON unit Simple absolute R unit Extension unit

Unit Name	Description	See Page
Gateway R unit	This unit is for connecting to a field network. Users can select from 4 types: DeviceNet, CC-Link, ProfiBus, and SIO. *This unit is required for using ROBONET.	P508 P509
RACON unit	This controller operates the RCA actuator. (One unit is necessary per actuator axis.) The incremental specification is the standard, but the simple absolute specification can also be used if the simple absolute R unit is used with it.	P510
RPCON unit	This controller operates the RCP2 actuator. (One unit is necessary per actuator axis.) The incremental specification is the standard, but the simple absolute specification can also be used if the simple absolute R unit is used with it.	P510
Simple absolute R unit	This is the back-up battery unit that retains actuator encoder data when the power is turned off.	P511
Extension unit	This unit makes it possible to reverse ROBONET connections, connect unit controllers (SCON/PCON-CF) to ROBONET, and conduct operation from a network.	P511

Ordering Method/Precautions

Required ROBONET units are ordered individually and assembled by the customer. Consequently, they can be added to or changed later.

<Ordering example> The following 2 actuator axes can be operated through CC-Link.
The models that would be best operated with the absolute specification are as follows.



■ Gateway Parameter Setting Tool

A gateway parameter setting tool is necessary to set up the network when ROBONET is connected to a field network. This tool can be acquired at no cost.

- (1) Download from the IAI website, or
- (2) Acquire PC compatible software (included on CD).

A cable (cable included with PC software, model: CB-RCA-SIO050+RCB-CV-MW) is required to connect the PC to the controller when using the gateway parameter setting tool. If you do not have the PC software, please purchase a cable.

■ PC Compatible Software Teaching Pendant

Compatible PC software or a teaching pendant is required to enter position data, etc. to a ROBONET controller unit. ROBONET compatible PC software (Model: RCM-101-MW/USB) version is Ver. 6.00.04.00 or later. Teaching pendant compatible models and versions include: RCM-T and Ver. 2.06 and later, model: RCM-E/RCM-P and Ver. 2.08 and later. Model: CON-T is compatible with all versions from the earliest version. Consult with our Sales Division if the version your equipment has needs to be updated.

Operation Mode

ROBONET operates upon receiving commands from the PLC via the field network.

The following four operating modes are available. Select the most suitable mode for the operation or the control method.

	Name	Description
1	Positioner mode (1,2)	In this mode, operation is done by specifying position numbers, whose position data, speed, and acceleration have been entered to the position table in advance. A maximum of 768 position points can be saved.
2	Simple direct input mode	The position data is specified directly using a numerical value; the other settings, such as speed, acceleration, deceleration, positioning band, and pushing current limit are specified using a predefined position number. A maximum of 768 position points can be saved.
3	Direct input mode	The position data, speed, acceleration, deceleration, positioning band, and pushing current limit are all specified directly using numerical values. Since the settings are specified by their numerical values, there is no limit to the number of points that can be set.
4	Solenoid valve mode (1,2)	The number of positioning points is limited for a simpler operation. You can operate it using the same controls as a solenoid valve, just by sending a command with the target position number (start signal not required).

List of functions for operation modes

Item	Operation mode	Positioner 1 Mode	Simple immediate data Mode	Direct number designation mode	Positioner 2 Mode	Solenoid Valve Mode 1	Solenoid Valve Mode 2
Each axis field (both input and output)		4 words		8 words	2 words	2 words	
Fixed field (both input and output)		8 words (Command field usable)		8 words (Command field not usable)	8 words (Command field usable)	8 words (Command field usable)	
Number of set positions		768 positions/axis	768 positions/axis	–	768 positions/axis	7 positions/axis	3 positions/axis
Position No. designation operation		<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	
Position data direct designation		<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	
Direct designation of speed and acceleration/deceleration speed		<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	
Direct designation of positioning band		<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	
Pushing operation		<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
Completed position No. monitor		<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	
Zone output monitor		<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
Position zone output monitor		<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	
Teaching function		<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	
Jog operation		<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	
Incremental operation		<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	
Status signal monitor (*1)		<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	
Current position monitor (*1)		<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	
Alarm code monitor (*1)		<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	
Speed and current monitor (*1)		<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	
Each axis monitoring function in in AUTO mode (*2)		<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
Command	Hand shake	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	
	Position table Reading/writing of data	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	
	Reading the current position	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	
	Broadcast	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	
Max. value for position data designation		9999.99mm (When command is used)	9999.99mm	9999.99mm	9999.99mm (When command is used)	9999.99mm (When command is used)	
Number of axes that can be connected		16	16	8	16	16	

*1: Each status signal monitor, current position monitor, alarm code monitor, and speed/current monitor can be viewed by accessing to each address of Gateway unit via PLC.

*2: Traditionally, monitoring each axis in AUTO mode is unavailable. However, monitoring each axis with Mode switch at "AUTO" is available with ROBONET by connecting the special touch panel to the TP connector.

*3: Independent acceleration and deceleration settings are not available. The setting applies to both accelerating and decelerating speeds.

Configuration unit (Gateway R unit)

Gateway R Unit for DeviceNet



A communications unit to operate ROBONET via DeviceNet.

Model **RGW-DV**

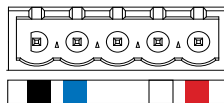
Specifications		Item		Specifications					
Power		DC24V ±10%		DeviceNet Specifications	Comm. Speed	Max. network length	Max. branch length	Total branch length	
Current consumption		600mA max.			Comm. cable length (*1)	500kbps	100m	6m	39m
DeviceNet Specifications	Comm. Standard	DeviceNet 2.0-certified interface module				250kbps	250m		78m
		Group 2 only server				125kbps	500m		156m
		Insulated node operating on network power supply				Note: When using a large cable for DeviceNet			
	Comm. Spec.	Master-slave connection	Bit strobe		Environment Requirements	No. occupied nodes	1 node		
Polling			Ambient op. temperature	0~40°C					
Cyclic			Ambient op. humidity	95% RH or below (non-condensing)					
Comm. Speed	500k/250k/125kbps (switchable by software)		Ambient op. environment	No corrosive or flammable gasses, oil mist, or dust.					
				Protection class	IP20				
				Weight	140g				
				Accessories	Terminal resistor board (model TN-1) Network connector, Emergency stop connector				

*1 If you wish to use T-junction communication, see the instructions manual for your master unit or PLC.

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Network cable

Connector on Gateway Side
MSTBA2.5/5-G-5.08 ABGY AU
(Made by: Phoenix Contact)



Connector on Cable Side
MSTB2.5/5-ST-5.08 ABGY AU
(Made by: Phoenix Contact)
= Standard accessory

Pin Color	Description
Black	Power cable negative (-) side
Blue	Comm. data Low side
-	Shield
White	Comm. data High side
Red	Power cable plus (+) side

Cable connector-compatible wiring

Item	Description
Wire diameter	Twisted wire: AWG24-12 (0.2~2.5mm ²)
Stripped wire length	7mm

Gateway R Unit for CC-Link



A communications unit to operate ROBONET via CC-Link.

Model **RGW-CC**

Specifications		Item		Specifications							
Power Supply		DC24V ±10%		Error Control Method CRC (X ¹⁶ +X ¹² +X ² +1)							
Current consumption		600mA max.		Station occupancy Remote device stations: x1, 4 st.; x4, 2 st.; x8, 2 st							
CC-Link Specifications	Comm. Standard	CC-Link Ver2.0 (*1)		CC-Link Specifications	Comm. Speed (bps)	10M	5M	2.5M	625k	156k	
	Comm. Speed	10M/5M/2.5M/625k/156kbps (switchable by software)			Total Cable Length (m)	100	160	400	900	1200	
	Comm. Method	Broadcast polling method			Comm. Cable	Dedicated CC-Link cable					
	Sync. Method	Frame synchronization method			Ambient op. temperature	0~40°C					
	Encoding Method	NRZI			Ambient op. humidity	95% RH or below (non-condensing)					
	Transf. Type	Bus format (EIA RS485 compliant)			Ambient op. environment	No corrosive or flammable gasses, oil mist, or dust.					
	Transf. Format	HDLC compliant		Protection class	IP20						
					Weight	140g					
				Accessories	Terminal resistor board (model TN-1) Network connector, Emergency stop connector Terminal resistor cable (110Ω/130Ω)						

*1 Certification acquired

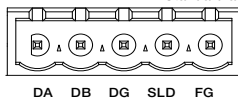
*2 If you wish to use T-junction communication, see the instruction manual for your master unit or PLC.

*1 Certification acquired

*2 If you wish to use T-junction communication, see the instruction manual for your master unit or PLC.

Network cable

Connector on Gateway Side: Connector on Cable Side:
MSTBA2.5/5-G-5.08AU MSTB2.5/5-ST-5.08 ABGY AU
(Made by Phoenix Contact) (Made by Phoenix Contact) =
Standard accessory



Signal Name	Description
DA	Communication line A
DB	Communication line B
DG	Ground
SLD	The shield and cable's shield are connected, then they are connected to "FG" and the chassis.
FG	Frame ground Connected to "SLD" and the chassis.

Cable connector-compatible wiring

Item	Description
Wire diameter	Twisted wire: AWG24-12 (0.2~2.5mm ²)
Stripped wire length	7mm

Configuration unit (Gateway R unit)

Gateway R Unit for ProfiBus



A communications unit to operate ROBONET via ProfiBus.

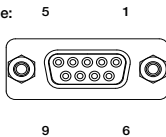
Model **RGW-PR**

Specifications

Item	Specifications		Item	Specifications
Power Supply	DC24V ±10%		Ambient op. temperature	0~40°C
Current Consumption	600mA max.		Ambient op. humidity	95% RH or below (non-condensing)
ProfiBus Specifications	Comm. Standard	DP slave	Ambient op. environment	No corrosive or flammable gases, oil mist, or dust.
	Comm. Speed	9.6kbps~12Mbps	Protection class	IP20
	Comm. Cable Length	9.6kbps	Weight	140g
		500kbps	Accessories	Terminal resistor board (model TN-1) Emergency stop connector
		1.5Mbps		
		3Mbps		
		12Mbps		

Network cable

Connector on Gateway Side:
D-Sub connector, 9-pin
socket side



Pin No.	Signal Name	Description	Pin No.	Signal Name	Description
3	B-Line	Communication line B (RS485)	6	+5V	+5V output (insulated)
4	RTS	Request send	8	A-Line	Communication line A (RS485)
5	GND	Signal ground (insulated)	Housing	Shield	Connected to the cable's shield and the chassis.

* The matching connector (D-Sub 9-pin connector) is not included. * Pins 1, 2, 7, and 9 are not connected

Gateway R Unit for SIO



A communications unit for operating ROBONET from an XSEL controller or a Modbus-compatible communications unit, via serial communication.

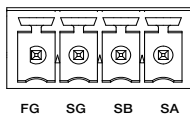
Model **RGW-SIO**

Specifications

Item	Specifications		Item	Specifications
Power Supply	DC24V ±10%		Ambient op. temperature	0~40°C
Current consumption	600mA max.		Ambient op. humidity	95% RH or below (non-condensing)
Comm. Type	RS485-compliant (Modbus protocol) 1:1 communication connection		Ambient op. environment	No corrosive or flammable gases, oil mist, or dust.
Comm. Method	Asynchronous method, half-duplex		Protection class	IP20
Comm. Speed	230.4kbps max.		Weight	140g
Cable Length	100m or less		Accessories	Terminal resistor board (model TN-1) Network connector, Emergency stop connector
Recommended cable	2 pairs of twisted pair cables (shielded)			

Network cable

Connector on Gateway Side
MC1.5/4-G-3.5
(Made by Phoenix Contact)



Connector on Cable Side:
MC1.5/4-ST-3.5
(Made by Phoenix Contact)
= Standard accessory

Signal Name	Description	
SA	Communication line A (+positive side)	Built-in RS485-compliant terminal resistor (220Ω)
SB	Communication line B (-negative side)	
SG	Signal ground	
FG	Frame ground connected to the chassis.	

Cable connector-compatible wiring

Item	Description
Wire diameter	Twisted wire: AWG28-16 (0.14~1.5mm ²)
Stripped wire length	7mm

Configuration unit (Controller unit)

RACON unit Controller for RCA2/RCA series

Controller unit that is used for RCA2/RCA actuator operation with ROBONET.

Model **RACON-①②-③**

* In Model ①, input a motor power output. (See the following table.)

② will need the code "HA" or "LA" specified when a high acceleration/deceleration or power saving actuator is to be used. (Otherwise, leave it blank.)

③ input "ABU" only when a simple absolute unit is used. (Otherwise, leave it blank.)

Model	Compatible actuators
RACON-2②-③	RCL-SA1L / SA4L / SM4L / RA1L
RACON-5②-③	RCL-SA2L / SA5L / SM5L / RA2L
RACON-10②-③	RCA2-SA3C / RN3N / RP3N / GS3N / GD3N / SD3N / TC3N / TW3N / TF3N / TA4 RCL-SA3L / SA6L / SM6L / RA3L
RACON-20②-③	RCA-SA4 / SS4 / SA5 / SS5 / RA4 -20 / RG 4 -20 / A4R / A5R RCACR-SA4C / SA5 RCAW-RA4 -20 RCA2-SA4 / SA5 / TA6
RACON-20S②-③	RCA-RA3 / RG 3 RCAW-RA3 RCA2-SA4 / TA5
RACON-30②-③	RCA-SA6 / SS6 / RA4 -30 / RG 4 -30 / A6R RCACR-SA6 RCAW-RA4 -30 RCA2-SA6C / TA7C

Specifications

Item			Specifications		
General Specifications	Power Supply	DC24V ±10%	Environment Requirements	Ambient op. temperature	0~50°C
	Power Supply Capacity	5.1A max. (depends on the actuator)		Ambient op. humidity	95% RH or below (non-condensing)
	Operable Actuators	RCA series		Ambient op. environment	No corrosive or flammable gases, oil mist, or dust.
	Positioning Points	768 points		Protection class	IP20
	Backup memory	EEPROM	Weight	200g	
	Position Detection Method	Incremental encoder	Accessories	ROBONET connection board (model JB-1), Power connection board (model PP-1)	
	Solenoid brake force-release	Brake release switch			
	Motor Cable	Model: CB-ACS-MA			
	Encoder Cable	Model: CB-ACS-PA			

RPCON unit Controller for RCP3/RCP2 series

Controller unit that is used for RCP3/RCP2 actuator operation with ROBONET.

Model **RPCON-①-②-③**

* In Model ①, input a motor type. (See the following table.)

② input "ABU" only when a simple absolute unit is used. (Otherwise, leave it blank.)

③ should have the code "H" when an RCP3-SA4, SA5, SA6, or an RCP2(RCP2CR)-SA5 or SA6 is to be connected.

Model	Compatible actuators
RPCON-20P-②	RCP2-RA2C / GRSS / GRLS / GRS RCP3-SA2A / SA2B / RA2A / RA2B
RPCON-28P-②	RCP2-GRM / GR3LS / GR3SS / RTB / RTC / RTBL / RTCL RCP3-SA3C
RPCON-28SP-②	RCP2-RA3C / RGD3C
RPCON-35P-②-③	RCP3-SA4 / TA5
RPCON-42P-②③	RCP2-SA5 / SA6 / SS7 / BA6 / BA7 / RA4C / RG 4C / GR3LM / GR3SM RCP3-SA5 / SA6 / TA6 / TA7 RCP2CR-SA5C / SA6C / SS7C RCP2W-RA4C
RPCON-56P-②	RCP2-SA7 / SS8 / RA6C / RG 6C / RCP2CR-SA7C / SS8C RCP2W-RA6C

Specifications

Item			Specifications		Item			Specifications	
General Specifications	Power Supply		DC24V ±10%		Environment Requirements	Ambient op. temperature		0~50°C	
	Power Supply Capacity		2A max.			Ambient op. humidity		95% RH or below (non-condensing)	
	Operable Actuators		RCP2 series			Ambient op. environment		No corrosive or flammable gases, oil mist, or dust.	
	Positioning Points		768 points			Protection class		IP20	
	Backup memory		EEPROM		Weight		200g		
	Position Detection Method		Incremental encoder		Accessories		ROBONET connection board (model JB-1), Power connection board (model PP-1)		
	Solenoid brake force-release		Brake release switch						
	Motor Cable		Model: CB-RCP2-MA						
	Encoder Cable		Model: CB-RCP2-PB						

Simple absolute R unit



A data backup battery unit that can be attached to an RACON or RPCON controller to use an incremental actuator as an absolute type.

*1 One unit of the simple absolute R unit is required per RACON/RPCON unit.

Model **RABU** (for RACON and RPCON)

* When preparing a simple absolute R unit together with a controller unit (RACON/RPCON), write down “-ABU” to the end of the controller model, of which the simple absolute unit is installed.

Specifications	Item		Specifications				Item		Specifications	
General Specifications	Power Supply	DC24V ±10%				Environment Requirements	Ambient op. temperature	0~40°C		
	Current consumption	300mA max.					Ambient op. humidity	95% RH or below (non-condensing)		
	Battery used	Ni-MH battery, nickel-hydrogen cell battery					Ambient op. environment	No corrosive or flammable gases, oil mist, or dust.		
	Charging time	Approx. 78 hours					Protection class	IP20		
	Battery life	3 yrs					Weight	330g		
	Maximum rpm for absolute data retention	800	400	200	100	Accessories	ROBONET connection board (model JB-1)			
	Absolute Data Retention Duration (h)	120	240	360	480		simple absolute connection board (model JB-1)			
							power connection board (model PP-1)			

Extension Unit



When too many ROBONET units are connected horizontally to fit into the controller board, use this unit to split them in the middle with a cable to create another row.

In addition, by attaching the extension unit to the end of the linked ROBONET units and using an external controller cable, you can operate a standalone controller SCON like any other ROBONET controller, over the network.

Model **REXT** (for RPCON and RACON)

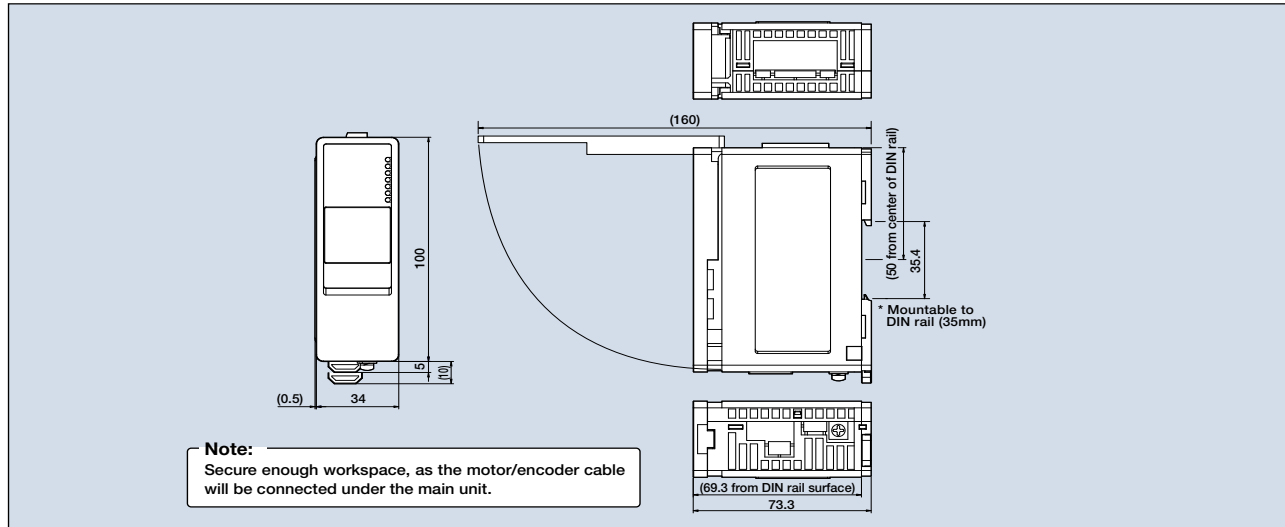
Specifications	Item		Specifications
	General Specifications	Power Supply	DC24V ±10%
		Current consumption	100mA max.
	Environment Requirements	Ambient op. temperature	0~40°C
		Ambient op. humidity	95% RH or below (non-condensing)
		Ambient op. environment	No corrosive or flammable gases, oil mist, or dust.
		Protection class	IP20
		Weight	140g
		Accessories	ROBONET connection board (model JB-1), Power connection board (model PP-1)

(Note) The cable used is different depending on whether you are creating a new row of linked units, or connecting a standalone controller.

For more information, see the ROBONET extension unit on P505.

External dimensional drawing

External dimensions of Gateway R unit, RACON unit, RPCON unit, Simple Absolute R unit, and Extension unit are same.



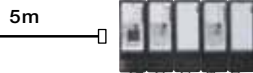
Option

Teaching Pendant

- Features** A teaching device with functions for inputting positions, performing test runs, and monitoring.
- Model**
 - CON-PT-M** (Touch panel teaching pendant)
 - CON-T** (Standard type)
 - RCM-E** (Simple teaching pendant)
- Configuration**

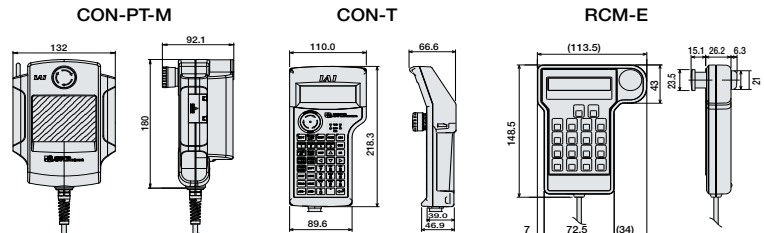
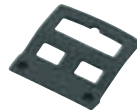


Note:
The version of RCM-E that can be used with ROBONET is 2.08 or later.



CON-T Options

- Wall-mounting hook Model **HK-1**
- Strap Model **STR-1**



Specifications

Item	CON-PT-M	CON-T	RCM-E
Data Input	○	○	○
Actuator motion	○	○	○
Ambient Operating Temp./Humidity	Temp: 0~40°C; Humidity: 85% RH or below		
Ambient Operating Atmosphere	No corrosive gases. Especially no dust.		
Protection class	IP40	IP54	—
Weight	Approx. 750g	Approx. 400g	Approx. 400g
Cable Length		5m	
Display	3-color LED touch panel with backlight	20 char. x 4 lines LCD display	16 char. x 2 lines LCD display
Standard Price	—	—	—

PC Software (Windows Only)

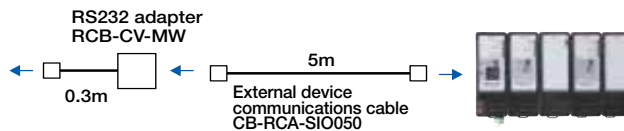
- Features** A startup support software for inputting positions, performing test runs, and monitoring. With enhancements for adjustment functions, the startup time is shortened.

- Model** **RCM-101-MW** (with external device communications cable + RS232 conversion unit)

Configuration



PC Software (CD)



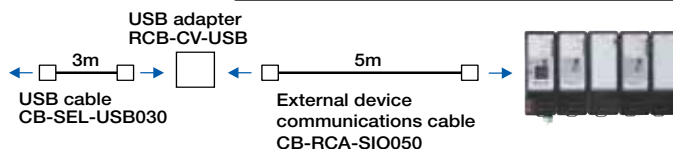
Note:
Only version 6.00.04.00 or later can be used with ROBONET.

- Model** **RCM-101-USB** (with external device communications cable + USB adapter + USB cable)

Configuration



PC Software (CD)



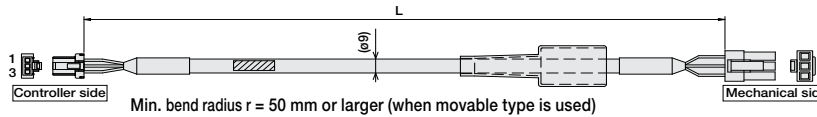
Note:
Only version 6.00.04.00 or later can be used with ROBONET.



Spare parts

Motor Cable for RCA

Model **CB-ACS-MA**

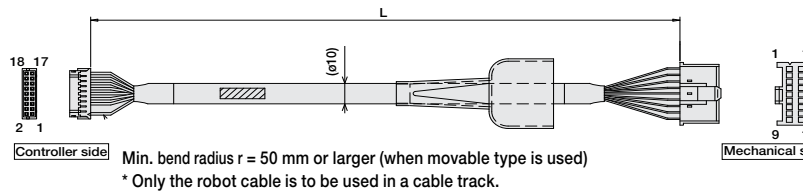
* Enter the cable length (L) into . Compatible to a maximum of 20 meters.
Ex.: 080 = 8 m


Wire	Color	Signal No.
AWG22 (crimped)	Blue	U 1
	Red	V 2
	White	W 3
	Black	

No.	Signal	Color	Wire
1	U	Blue	AWG22 (crimped)
2	V	Red	
3	W	White	

Encoder Cable/Encoder Robot Cable for RCA

Model **CB-ACS-PA** / **CB-ACS-PA**-RB

* The standard encoder cable is the normal cable. The robot cable is selectable as an option.
* Enter the cable length (L) into . Compatible to maximum of 20 meters. Ex.: 080 = 8 m


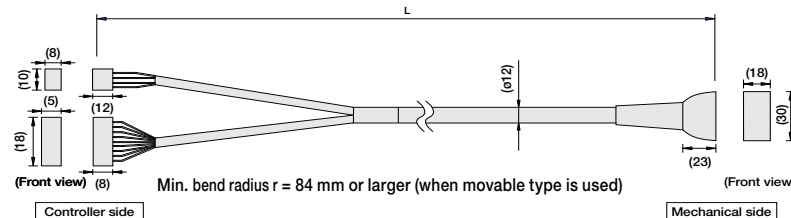
Cable color	Signal	Pin No.
White/Purple	LS+	18
White/Gray	LS-	17
Yellow	Green	16
Blue	BK+	15
White/Blue	Gray	14
White/Yellow	Red	13
White/Red	Black	12
White/Black	Yellow	11
Orange	Pink	10
Green	Purple	9
Purple	White	8
Gray	Blue/Red	7
Red	Orange/White	6
Black	Green/White	5
Ground	Ground	2
Ground	Ground	1

Housing : PHDR-18V1 (JST)
Contact : SPHD-001T-P0.5 (JST)

Plug housing : XMP-18V (JST)
Socket contact : BXA-001T-P0.5 (JST)
Retainer : XMS-00V (JST)

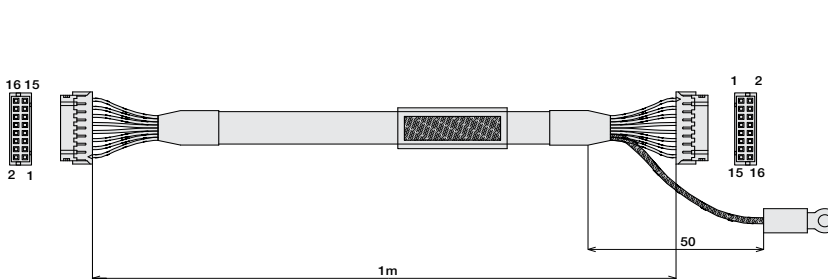
Motor-Encoder Integrated Cable for RCA2

Model **CB-ACS-MPA**

* Enter the cable length (L) into . Compatible to a maximum of 20 meters.
Ex.: 080 = 8 m


Signal	Pin No.	Wire color	Pin No.	Signal
U	1	Red	A1	U
V	2	Yellow	B1	V
W	3	Black	A2	W
			B2	NC
			A3	NC
			B3	NC
			A4	BK+
			B4	BK-
			A5	LS+
			B5	LS-
			A6	A+
			B6	A-
			A7	B+
			B7	B-
			A8	Z+
			B8	Z-
			A9	Z
			B9	Z
			A10	VCC
			B10	GND
			A11	NC
			B11	FG

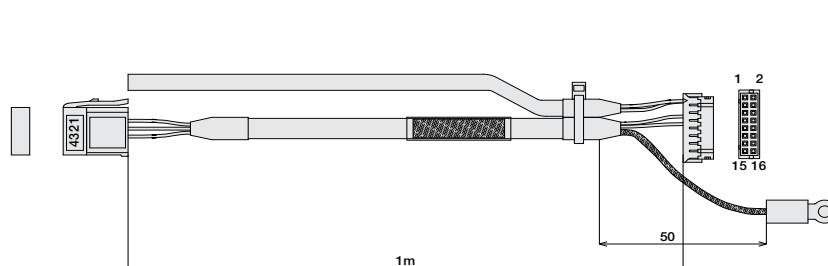
Unit Link Cable for Extension Unit

Model **CB-REXT-SIO010**


Signal	Pin No.	Wire color	Pin No.	Signal
RSV1	16	Black 2/White	16	RSV1
RSV1	15	Red 2/White	15	RSV1
ROUT	14	Black 2/Gray	14	ROUT
ROUT	13	Red 2/Orange	13	ROUT
RSV0	12	Black 2/Orange	12	RSV0
ENA	11	Black 1/Pink	11	ENA
COM2	8	Red 1/Yellow	8	COM2
COM1	7	Black 1/White	7	COM1
SD+	6	Red 1/White	6	SD+
SD+	5	Black 1/Gray	5	SD+
RD+	4	Red 1/Gray	4	RD+
RD+	3	Black 1/Orange	3	RD+
EMG+	2	Red 1/Orange	2	EMG+
EMG+	1		1	EMG+

Wire color legend: <Color of dot> <Number> <Color of insulation>

Controller Connection Cable for Extension Unit

Model **CB-REXT-CTL010**


Pin No.	Signal	Wire color	Pin No.	Signal
4	N.C.	White	10	ENA
3	GND	Gray	9	COM2
2	SD+	Orange	8	COM1
1	SD+		7	SD+
			6	SD+
			5	RD+
			4	RD+
			3	EMG+
			2	EMG+
			1	EMG+