RCA2-TCA4N

ROBO Cylinder Mini Table Type Short-Length Compact Model 36mm Width 24V Servo Motor Ball Screw/Lead Screw Models

30: 30mm

■ Configuration:

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* See page Pre-35 for an explanation of the naming convention.

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20: 20W Servo

motor

I: Incremental * The simple

absolute encoder

is also considered type "I".

30

6 : 6mm ball screw 4 : 4mm ball screw 2 : 2mm ball screw

6S: 6mm lead screw 4S: 4mm lead screw 2S: 2mm lead screw

A1: ACON

RACON

K2: Connector cable

ASEL S : 3m A3: AMEC M : 5m

exit direction LA: Power-saving

ASEP X □□: Custom

N: None

P:1m

Power-saving



Technical References



(1) The load capacity is based on operation at an acceleration of 0.3G (0.2G $\,$ for the 2mm-lead model, or when used vertically). This is the upper limit of the acceleration.

When using the Lead screw model, please ensure that your usage is appropriate for its characteristics. (See page Pre-42 for more

Actuator Specifications

■ Lead and Load Capacity

Model		Feed	Lead	Max. Load Capacity		Rated Thrust (N)	Positioning Repeatability	Stroke
	Output (W)	Screw	(mm)	Horizontal (kg)	Vertical (kg)	Inrust (N)	(mm)	(mm)
RCA2-TCA4N-I-20-6-30-①-②-③			6	2	0.5	33.8		
RCA2-TCA4N-I-20-4-30-1-2-3	20	Ball screw	4	3	0.75	50.7	±0.02	30 (Fixed)
RCA2-TCA4N-I-20-2-30-10-20-3			2	6	1.5	101.5		
RCA2-TCA4N-I-20-6S-30-1 -2 -3			6	0.25	0.125	19.9		
RCA2-TCA4N-I-20-4S-30-①-②-③	20	20 Lead screw		0.5	0.25	29.8	±0.05	30 (Fixed)
RCA2-TCA4N-I-20-2S-30-1 -2 -3			2	1	0.5	59.7		
Legend ① Compatible controller ② Cable length	3 Optio	ns						

■ Stroke and Maximum Speed

Lead	Stroke	(mm)	
×	6	270 <220>	
Ball screw	4	200	
8 2		100	
Me Me	6	220	
Lead screw	4	200	
Fe	2	100	
* The v	alues enclosed i	n "< >" apply to vertical usage.	(Unit: mm/s)

Stroke (mm)	Standa	rd Price	
Stroke (mm)	Feed Screw		
	Ball Screw Model	Lead Screw Model	
30	-	_	

② Cable List

Туре	Cable Symbol	Standard Price
Standard	P (1m)	-
(Robot Cables)	S (3m)	-
	M (5m)	-
	X06 (6m) ~ X10 (10m)	-
Special Lengths	X11 (11m) ~ X15 (15m)	-
	X16 (16m) ~ X20 (20m)	_

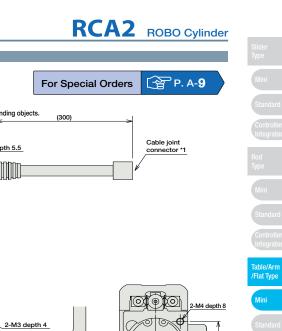
- * The RCA2 comes standard with a robot cable.
- * See page A-39 for cables for maintenance.

Name	Option Code	See Page	Standard Price
Connector cable exit direction	K2	→ A-32	-
Power-saving	LA	→ A-32	-

Actuator Specifications

Item	Description		
Drive System	Ball screw/Lead screw ø6mm C10 grade		
Lost Motion	Ball screw: 0.1mm or less/Lead screw: 0.3mm or less (initial value)		
Frame	Material: Aluminum (white alumite treated)		
Allowable Dynamic Moment (Note)	Ma: 9.9 N·m Mb: 9.9 N·m Mc: 3.3 N·m		
Ambient Operating Temp./Humidity	0~40°C, 85% RH or less (non-condensing)		
Service Life Lead Screw Model	Horizontal: 10 million cycles Vertical: 5 million cycles		

(Note) Based on a 5,000 km service life set for the guide.



2D CAD *2 When homing, the table moves to the mechanical end; therefore, please watch for any interference with the surrounding objects. CAD ME: Mechanical end ø3^{+0.03}depth 3 SE: Stroke end 4-M4 depth 5.5 00 0 0 (O) ន 3 0 depth 3 10.5 30 95 2 28 \bigoplus **(** 22.6 Secure at least 100 ø3^{+0.03}depth 3 4-M4 through 3 0 depth 3 **(** \oplus

10

ø3 ^{+0.03} depth 3

4-M4 depth 5

Dimensions

CAD drawings can be downloaded from IAI website. www.intelligentactuator.com

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Connector cable exit direction (Model: K2) * Rotates 180° with respect to the standard model.

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3D

*1 The motor-encoder cable is connected here. See page A-39 for details on cables.

■ Dimensions/Weight by Stroke

Stroke	30
Weight (kg)	0.48

Name	External View	Model	Description	Max. Positioning Points	Input Voltage	Power Supply Capacity	Standard Price	See Page	
		AMEC-C-20I①-NP-2-1	Easy-to-use controller, even for beginners		AC100V	2.4A rated	-	→ P477	
Solenoid Valve Type	1	ASEP-C-201①-NP-2-0 Operable with same signal as solenoid valve. 3 points	3 points			-			
Splash-Proof Solenoid Valve Type		ASEP-CW-20I①-NP-2-0	Supports both single and double solenoid types. No homing necessary with simple absolute type.			(Standard) 1.3A rated	-	→ P487	
Positioner Type		ACON-C-20I①-NP-2-0	Positioning is possible for up to 512 points	512 points			-		
Safety-Compliant Positioner Type		ACON-CG-20I①-NP-2-0	Positioning is possible for up to 312 points	512 points			-		
Pulse Train Input Type Differential Line Driver)			ACON-PL-20I①-NP-2-0	Pulse train input type with differential line driver support	()	DC24V	4.4A max. (Power-saving)	-	→ P535
Pulse Train Input Type (Open Collector)			ACON-PO-20I①-NP-2-0	Pulse train input type with open collector support	(-)		1.3A rated 2.5A max.	-	
Serial Communication Type	ĺ	ACON-SE-20I①-N-0-0	Dedicated to serial communication	64 points		-	-		
Field Network Type		RACON-20①	Dedicated to field network	768 points			-	→ P503	
Program Control Type		ASEL-C-1-20I①-NP-2-0	Programmed operation is possible Operation is possible on up to 2 axes	1500 points			-	→ P567	

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