■ Configuration: RCP2 —

CP2-BA7/BA7U

Top-Mounted Motor / Bottom-Mounted Motor

BA7 : Belt type BA7 : Belt type
Top-mounted moto
BA7U: Belt type
Bottom-mounted

I: Incremental
* The Simple
absolute encode models are labeled as "I". * See page Pre-35 for explanation of each code that makes up the configuration name.

Encoder

42P: Pulse motor 54:54mm 42 🗌 size

54

42P

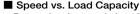
600: 600mm 1200:1200mm (50mm pitch increments)

P1: PCON RPCON PSEL N : None P : 1m S : 3m P3: PMEC PSEP

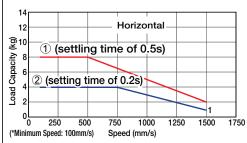
M:5m
X : Custom Length
R : Robot cable

NM: Reversed-home

Cable Length



Due to the characteristics of the pulse motor, the RCP2 series' load capacity decreases at high speeds. In the table below, check if your desired speed and load capacity are supported.



Graph ${\scriptsize \textcircled{\scriptsize 1}}$ is for standard specifications, with settling time of 0.5s for calculating the positioning time.

Graph 2 reflects some changes in the controller settings. The load capacity is lower, however the settling time is decreased to 0.2s.

If the load capacity is lower than graph $\ensuremath{@\circ}$, and you want to shorten the positioning time, change the controller settings. (See the manual for details.)

(Vertical operation is not possible.)



Technical References (1) Operating the belt type actuator at low speeds may cause vibration and/or resonance. Therefore, please set the speed at 100mm/s or faster.

(2) Since the RCP2 series use a pulse motor, the load capacity decreases at high speeds. Check in the Speed vs. Load Capacity graph to see if your desired speed and load capacity are supported.

(3) The load capacity is based on operation at an acceleration of 0.5G. 0.5G is the upper limit for the acceleration.

	Actuator Specifications						
■ Lead and Load Capacity (Note 1) Please note that the maximum load capacity decreases as the spec						speed increases.	■ S
	Model	Motor Mounting	Lead	Max. Load Capacity (Note 1) Stroke			
	Model	Direction	(mm)	Horizontal (kg)	Vertical (kg)	(mm)	Lead
	RCP2-BA7-I-42P-54-1 - 2 - 3 - 4	Тор	·54 equivalent	- 0	Not Allowed	600 ∼ 1200	
RCP2-BA7	RCP2-BA7U-I-42P-54-①-②-③-④	Bottom	54 equivalent	~ 8	Not Allowed	(50mm increments)	e
	Legend Stroke Compatible controller Cable length	(4) Options					

Stroke and	Stroke and Maximum Speed						
Stroke	600 ~ 1200						
Lead	(50mm increments)						
54 equivalent	1500						
	(Unit: mm/s)						

① Stroke List						
Stroke (mm)	Standard Price					
600	-					
650	-					
700	-					
750	-					
800	-					
850	-					
900	-					
950	-					
1000	-					
1050	-					
1100	-					
1150	-					
1200	-					

Option List			
Name	Option Code	See Page	Standard Price
Reversed-home	NM	→ A-33	_

③ Cable Lis	t	
Туре	Cable Symbol	Standard Price
Standard	P (1m)	_
	S (3m)	_
	M (5m)	_
	X06 (6m) ~ X10 (10m)	-
Special Lengths	X11 (11m) ~ X15 (15m)	_
	X16 (16m) ~ X20 (20m)	_
	R01 (1m) ~ R03 (3m)	_
	R04 (4m) ~ R05 (5m)	-
Robot Cable	R06 (6m) ~ R10 (10m)	_
	R11 (11m) ~ R15 (15m)	_
	R16 (16m) ~ R20 (20m)	_
* O A 00 f		

^{*} See page A-39 for cables for maintenance.

Actuator Specifications					
Item	Description				
Drive System	Timing Belt				
Positioning Repeatability	±0.1mm				
Lost Motion	0.1mm or less				
Allowable Dynamic Moment (*)	Ma: 13.8 N·m Mb: 19.7 N·m Mc: 29.0 N·m				
Overhang Load Length	Ma direction: 150mm or less; Mb·Mc direction: 150mm or less				
Ambient Operating Temp./Humidity	umidity 0~40°C, 85% RH or less (Non-condensing)				
(*) Based on 5.000km travel life.					

Directions of Allowable Load Moments







For Special Orders



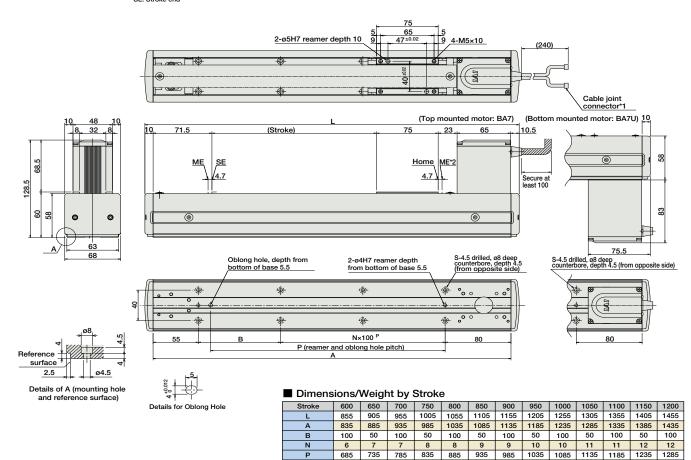




- *1 The motor-encoder cable is connected here.
- See page A-39 for details on cables.

 *2 When homing, the slider moves to the ME; therefore, please watch for any interference with the surrounding objects. ME: Mechanical end

SE: Stroke end



② Compatible Controllers

The RCP2 series actuators can operate with the controllers below. Select the controller according to your usage

Name	External View	Model	Description	Max. Positioning Points	Input Voltage	Power Supply Capacity	Standard Price	See Page		
Solenoid Valve Type	110	PMEC-C-42PI-NP-2-①	Easy-to-use controller, even for beginners	AC200V oerable with same signal as solenoid valve. ports both single and double solenoid types.	See P481	-	→ P477			
Soleriold valve Type	1	PSEP-C-42PI-NP-2-0	Operable with same signal as solenoid valve.				_	→ P487		
Splash-Proof Solenoid Valve Type	U	PSEP-CW-42PI-NP-2-0	Supports both single and double solenoid types. No homing necessary with simple absolute type.				_			
Positioner Type	· ·	PCON-C-42PI-NP-2-0	Positioning is possible for up to 512 points	512 points			_			
Safety-Compliant Positioner Type		PCON-CG-42PI-NP-2-0	Positioning is possible for up to 512 points	312 points			-			
Pulse Train Input Type (Differential Line Driver)		PCON-PL-42PI-NP-2-0	Pulse train input type with differential line driver support	(-)	DC24V	2A max.	_	→ P525		
Pulse Train Input Type (Open Collector)		PCON-PO-42PI-NP-2-0	Pulse train input type with open collector support	(-)	64 points		_			
Serial Communication Type		PCON-SE-42PI-N-0-0	Dedicated to serial communication	64 points						-
Field Network Type		RPCON-42P	Dedicated to field network	768 points				→ P503		
Program Control Type		PSEL-C-1-42PI-NP-2-0	Programmed operation is possible Can operate up to 2 axes	1500 points			-	→ P557		

16 18

3.6 3.7 18 20 20 22 22 24

3.9

4.0

4.2 4.3 4.4

4.6 4.7

* This is for the single-axis PSEL. * \odot is a placeholder for the power supply voltage (1: 100V / 2: 100 \sim 240V).

24

26

4.9

26

5.0 5.2

28

28

5.3

пср2-ват/вати 54