**INTRODUCTION TO ROBO CYLINDER**

**Ball Screw Lubrication:**
The AQ Seal is engineered to provide precise lubrication to critical points and will ensure optimal maintenance-free operation.

**Slider Type Actuators:**
Speeds of up to 1500mm/s and stroke lengths of 1200mm, the slider type actuator performs flawlessly in many applications.

**Coupling Motor Specification:**
Optimized for fast and easy motor change-outs. Reduce downtime and maximize your return.

**Rod Type Actuators:**
Mounts like an air cylinder and operates at speeds of up to 800 mm/s at strokes of 300 mm offering smooth transitions unseen with air cylinders. With up to 1500 positioning points, you can produce a variety of products on the same automation line.

**Stainless Steel Dust Strip:**
Keeps contaminants out of the system, prolonging actuator performance and efficiency.

**Easy Programming:**
Acceleration and deceleration can be set independent of each other, providing excellent control of work. Dramatically reduce work damage and error.

**Slider Type Actuators:**
Speeds of up to 1500mm/s and stroke lengths of 1500mm, the slider type actuator performs flawlessly in many applications.
Established in 1976, IAI has grown globally to serve over 12 countries. IAI has 24 regional offices in Japan and is proud to announce a newly constructed headquarters, with an adjacent state of the art manufacturing facility to produce the highest quality automation robots. IAI is constantly striving in the pursuit of ‘Quality and Innovation.’ Our focus is always on our customers and their needs to offer high quality and innovative solutions tailored for specific customer applications. IAI America Inc. was established in 1989 to better serve the needs of factory automation. With 3 main offices in the United States, support from IAI’s experienced engineers is always just a phone call away.

From our easy to use software, to complete automation solutions, we provide you with the tools necessary to scale your business. When you demand innovative and high quality robots, excellent service and support for your unique needs, demand IAI!

ISO 9001:2000
IAI has been certified for ISO 9001:2000 and JIS Q9001:2000 by an independent auditor to be in conformance with ISO 9001:2000 and JIS Q9001:2000. We at IAI are continually improving our methods to produce quality products and services that surpass customer expectations.

RoHS Compliant
IAI is RoHS compliant and recognizes the responsibility in reducing hazardous substances to better serve our customers and our environment.
Higher Quality, Lower Running Costs, Sustainability

How much money is leaking out of your system?

The United States Department of Energy, Office of Industrial Technologies has reported that “many facilities have no idea how much their compressed air systems cost on an annual basis, or how much money they could be saving by improving the performance of these systems.” Do you know how much money is leaking out of your system?

The excessive cost of leaks

An example of how expensive one small leak can cost, consider the figure below:

<table>
<thead>
<tr>
<th>Size</th>
<th>Cost per Year</th>
</tr>
</thead>
<tbody>
<tr>
<td>1/16&quot;</td>
<td>$1,004.16</td>
</tr>
<tr>
<td>1/8&quot;</td>
<td>$4,022.40</td>
</tr>
<tr>
<td>1/4&quot;</td>
<td>$16,093.44</td>
</tr>
</tbody>
</table>

Costs calculated using electricity rate of $0.096 per kWh*, assuming constant operation and an efficient compressor. *Cost adjusted for average commercial retail price of electricity (Nov. 2007)

Just one small ¼" hole can cost you $16,093.44 per year! Even without a visible hole, pinhole leaks are very common and add up to a costly energy bill. Energy costs are skyrocketing and so will the cost of air leaks that plague most systems. DOE also states "leaks can be a significant source of wasted energy in an industrial compressed air system, sometimes wasting 20-30% of a compressor’s output.” Leaks will drop system pressure and make “air tools function less efficiently, adversely affecting production.”

Eliminate your problems with ROBO Cylinder

You can eliminate costly losses with IAI’s ROBO Cylinder electric actuator today! ROBO Cylinder offers you easy to use software and all of the benefits of a high-quality electric actuator. Did you know that the effective energy efficiency of IAI’s ROBO Cylinder line is 80-90%, while “a typical overall efficiency is around 10%” for a compressed air system? (U.S. DOE, OIT Sourcebook CAC F2-1)

Power Consumption Test: ROBO Cylinder vs Air Cylinder

IAI devised a precision power consumption test procedure to measure energy efficiency. Both the air cylinder and ROBO Cylinder were tested with identical variables. Variables included dwell time, cost of electricity, cost of compressed air, speed, payload, stroke, ambient temp and operating time.

ROBO Cylinder
Running Costs only 1/3 to 1/10 of an Air Cylinder

As the operation frequency increases, the energy requirements of air cylinders increase exponentially, while the power consumption rate remains constant with the energy efficient ROBO Cylinder. Therefore, the differentials in power consumption between the two actuators increase as the number of cycles per minute increases. Based on IAI’s calculations, when the two actuators are operating at 10 cycles per minute, the ROBO Cylinder only requires 1/3 the power of the air cylinder. When the actuators are operating at 30 cycles per minute, the difference is even more profound, with the ROBO Cylinder only requiring 1/10 the power of the air cylinder! Keep in mind that no industrial plant uses just one actuator; the more actuators your plant requires, the more savings and ROI with energy efficient ROBO Cylinders.

Source:
2. Department of Energy, Office of Industrial Technologies, Compressed Air Challenge “Improper Use of Compressed Air” Fact Sheet #2
3. Department of Energy, Office of Industrial Technologies, Compressed Air Challenge “Compressed Air System Efficiencies” Fact Sheet #1
4. Department of Energy, Office of Industrial Technologies, Compressed Air Challenge “Compressed Air System Efficiencies” Fact Sheet #9
5. IAI Japan Internal R&D Testing Reports
6. Pneumatic Energy Evaluation Report by Tokyo Institute of Technology

Higher Quality, Lower Running Costs, Sustainability

Green Automation

Green Automation
 ERC2 electric actuators are low-cost, controller-integrated actuators with a built-in controller. You do not need extra space for a separate controller minimizing the control area. These electric actuators are available at affordable prices similar to those of air cylinders, and thus are great economical, high-quality candidates for replacing air cylinders.

**Features**
- Use of multiple actuators in one system.
- Transfer, raising/lowering, push-out, push-motion.

**Applications**
- Example: Positioning of automobile rear panels

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The slider on the actuator moves forward and backward to perform positioning operations. The built-in linear guide helps achieve excellent linearity and also enables handling of an uneven load. Slide-type actuators are available in one of three motor-installation specifications including the coupling type, built-in (direct connection) type and reversing type.

**Features**
- Transfer and positioning along a straight line
- Product picking & placement systems consisting of multiple axes

**Applications**
- Example: Picking & placement of products

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The rod extends and contracts from/into the actuator to perform positioning and push-motion operations. You can select one of three guide options including “no guide,” “single guide” and “double guides.” Rod-type actuators are available in one of three motor-installation specifications including the coupling type, built-in (direct connection) type and reversing type.

**Features**
- Raising/lowering of loads and stackers
- Pushing-out of products (pushers)
- Press-fitting of loads, crimping

**Applications**
- Example: Press-fitting and assembly of resin parts

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The table or arm on the actuator slides to perform positioning and push-motion operations. The built-in linear guide helps achieve excellent linearity and also enables handling of an uneven load. Compared to rod-type actuators, these actuators allow for easy installation of devices.

**Features**
- Raising/lowering of loads and stackers
  (Effective for devices and loads having many overhangs)
- Pushing-out of products (pushers)

**Applications**
- Example: Raising/lowering of inkjet heads
<table>
<thead>
<tr>
<th><strong>Model Categories</strong></th>
<th><strong>Features</strong></th>
<th><strong>Applications</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>ROBO CYLINDER</td>
<td>Gripper-type actuators allow for adjustment of gripping force to hold even fragile loads with soft gripping action. Rotary-type actuators offer versatility, functioning both as an index station to perform 360-degree positioning operations, and as a conveyor that rotates infinitely in the same direction.</td>
<td>Gripper - Gripping and centering of loads Rotary - Indexing and rotation/movement of loads</td>
</tr>
<tr>
<td>Cleanroom specification</td>
<td>These actuators are designed for the cleanroom environment and achieve cleanliness of class 10 (0.1 mm). The stainless sheet prevents dust from being raised inside the actuator, which helps achieve high cleanliness with a light vacuum.</td>
<td>Transfer and positioning inside a clean room</td>
</tr>
<tr>
<td>Dust-proof/Splash-proof specification</td>
<td>These actuators have an IP65 protective structure to withstand use in a harsh environment where the actuator comes in contact with powder dust, water splashes, etc.</td>
<td>Transfer &amp; positioning structure in machine tools, food processing machines and cleaning systems</td>
</tr>
<tr>
<td>Controller</td>
<td>Our controllers support various control methods including positioner control, solenoid-valve control, pulse-train control, serial communication, field network (DeviceNet/CC-Link/ProfiBus), and program operation.</td>
<td>Simple positioning - Positioner control, solenoid-valve control At-will control - Pulse-train control, serial communication Simultaneous control with peripherals - Field network Independent control - Program control</td>
</tr>
</tbody>
</table>

Example: Palletizing of loads using a SCARA robot

Example: Stacking of discs

Example: Feeding of water jets
ROBO Cylinder Series

Pulse Motor Actuators

**ERC2 series**

The ERC2 series actuators are the affordable SOLUTION and benefit from a built-in controller improving usability

Features

1. The built-in controller offers simple wiring.
2. No need for extra installation space for controllers.
3. Exceptional value; actuator price includes the controller.

<table>
<thead>
<tr>
<th>Controller</th>
<th>Input Power</th>
</tr>
</thead>
<tbody>
<tr>
<td>(Built-in)</td>
<td>DC24V</td>
</tr>
</tbody>
</table>

**RCP3 series**

Through improvement of production TECHNOLOGY, the new RCP3 series actuators have become even more affordable and easier to use.

Features

1. The table type is constructed with a high-rigidity slide mechanism for greater moment loads.
2. An ultra-slim model with a width of 32 mm/1.26” (SA3 type) is the solution for applications requiring small actuators.
3. Motor change-outs are as easy as unscrewing one bolt.

<table>
<thead>
<tr>
<th>Controller</th>
<th>Input Power</th>
</tr>
</thead>
<tbody>
<tr>
<td>PCON PSEL</td>
<td>DC24V</td>
</tr>
</tbody>
</table>

**RCP2 series**

The RCP2 series actuators are high-value and driven by a pulse motor capable of generating high FORCE at low speed.

Features

1. Vast variety of unique electric actuators.
2. The characteristics of a pulse motor are utilized to generate strong push force.
3. Various control methods are possible with controller support.

<table>
<thead>
<tr>
<th>Controller</th>
<th>Input Power</th>
</tr>
</thead>
<tbody>
<tr>
<td>PCON PSEL</td>
<td>DC24V</td>
</tr>
</tbody>
</table>
**ROBO Cylinder Series**

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### Servo Motor Actuators

#### RCA2 series

**The RCA2 series continues on the path of the RCA series delivering a low cost and UNPARALLELED serviceability**

**Features**

1. The table type is constructed with a high-rigidity slide mechanism for greater moment loads.
2. An ultra-slim model with a width of 32 mm/1.26" (SA3 type) is the solution for applications requiring small actuators.
3. Easy motor change-outs.

<table>
<thead>
<tr>
<th>Controller</th>
<th>ACON</th>
<th>ASEL</th>
<th>Input Power</th>
<th>DC24V</th>
</tr>
</thead>
</table>

#### RCA series

**The RCA series is powered by a 24V servo motor that can be installed in the same manner as air cylinders**

**Features**

1. Various mounting brackets similar to what you normally use with air cylinders are supported.
2. Available in one of three motor-installation specifications including the coupling type, built-in (direct connection) type and reversing type.
3. Home check sensor (optional)
4. Optional high acceleration/deceleration function that enables operations at 1G. A power-saving option that lowers power consumption is also offered.

<table>
<thead>
<tr>
<th>Controller</th>
<th>ACON</th>
<th>ASEL</th>
<th>Input Power</th>
<th>DC24V</th>
</tr>
</thead>
</table>

#### RCS2 series

**Small/Medium size actuators that can be operated with a 100/200V power supply**

**Features**

1. Max speed of 1,000 mm/s, max load capacity of 60kg, and max stroke of 1,000 mm.
2. With the XSEL controller, 3 or more axes can be combined as cartesian systems.
3. Available in one of three motor-installation specifications including the coupling type, built-in (direct connection) type and reversing type.
4. Optional high acceleration/deceleration function that enables operations at 1G.

<table>
<thead>
<tr>
<th>Controller</th>
<th>SCON</th>
<th>SSL</th>
<th>XSEL</th>
<th>Input Power</th>
<th>AC100V/200V</th>
</tr>
</thead>
</table>
Actuator Type Features

Mini Slider type

The slider on the main body moves back and forth until it is positioned.

Features
- The motor can easily perform switching operations for the unit model.
- Select from Reversing type with a reduced total length and Slim Straight type (Coupling type).

Usage
Used for jig and workpiece positioning, table travel, etc.

Motor Unit Coupling type
Motor Unit Reversing type

Mini Rod type

The rod extends and retracts from the main body, gets into position and presses.

Features
- Select from Slim Motor Unit types and Short Length types having greatly reduced overall length.
- Select from Guide types with highly rigid/linear built-in guides and Non-Guide types having drastically miniaturized main body sizes.

Usage
Used for raising/lowering products and jigs, pushing, clamping, etc.

Motor Unit Coupling type
Motor Unit Reversing type
Short Length, Double-Guide Slide Unit type
Short Length, Single-Guide Free Mount type
Short Length, Fixed Nut type
Short Length, Tapped Hole type
**Mini Table type**

The table on the main body slides until it is positioned.

<table>
<thead>
<tr>
<th>Features</th>
<th>Usage</th>
</tr>
</thead>
<tbody>
<tr>
<td>· Comes equipped with an integrated guide that keeps overhung loads balanced.</td>
<td>Used for raising/lowering products and jigs, horizontal moving, and pushing (handles overhung loads from the main unit).</td>
</tr>
</tbody>
</table>

**Mini Linear Servo type**

High speed, lightweight parts transfer.

<table>
<thead>
<tr>
<th>Features</th>
<th>Usage</th>
</tr>
</thead>
<tbody>
<tr>
<td>· Equipped with a high acceleration/deceleration linear motor capable of operation at up to 2G.</td>
<td>Used for transfers requiring short cycle times, etc.</td>
</tr>
</tbody>
</table>

- Available in Slider type and Rod type.
  - Slider type comes in six different models for each size and stroke.
  - The Multi-slider type comes with two sliders on one axis that can be independently operated.

- Equipped with a high acceleration/deceleration linear motor capable of operation at up to 2G.
  - Available in Slider type and Rod type.
  - Slider type comes in six different models for each size and stroke.
  - The Multi-slider type comes with two sliders on one axis that can be independently operated.
Unlike conventional controllers, the PSEP/ASEP require only a few movement positions. These “Simple, Easy Positioner” controllers are for applications where the actuator travels only between two or three points, which is usually the case with air cylinders.

If you have been using air cylinders and are unhappy with the long time needed to change movement positions or want to stop actuator movement between two points, you can use the ROBO Cylinder with PSEP/ASEP controllers. We also have an IP53 rated dustproof type that can be placed near the actuator for operation as is done with solenoid valves.

PSEP/ASEP controllers are not just for the new Mini ROBO Cylinder lineup. They can also be used with existing ROBO Cylinders. Existing controllers can also be used with the new Robo Mini Cylinders. Please use them according to the application.
Operates using the same signals used for air cylinder solenoid valves.

**PSEP/ASEP operating methods**

PSEP/ASEP controllers can be operated with the same signals used for air cylinder solenoid valves. Solenoid valves come in two types: Single solenoids and Double solenoids. The PSEP/ASEP supports signals for both.

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### When using an air cylinder solenoid valve:

**<Single solenoid>**

(Air cylinder)  

Solenoid 1  

(Solenoid valve)

<table>
<thead>
<tr>
<th>Signal to solenoid 1</th>
<th>Rod movement</th>
</tr>
</thead>
<tbody>
<tr>
<td>ON</td>
<td>Front end</td>
</tr>
<tr>
<td>OFF</td>
<td>Rear end</td>
</tr>
</tbody>
</table>

---

**<Double solenoid>**

(Air cylinder)  

Solenoid 1  

Solenoid 2  

(Solenoid valve)

<table>
<thead>
<tr>
<th>Signal to solenoid 1</th>
<th>Signal to solenoid 2</th>
<th>Rod movement</th>
</tr>
</thead>
<tbody>
<tr>
<td>ON</td>
<td>OFF</td>
<td>Front end</td>
</tr>
<tr>
<td>OFF</td>
<td>ON</td>
<td>Rear end</td>
</tr>
</tbody>
</table>

---

**<Replacement of single solenoid>**

(ROBO Cylinder)  

(PSEP / ASEP)

*Desired positions for front end and rear end can be freely set.*

<table>
<thead>
<tr>
<th>Signal to controller Input 0</th>
<th>Rod movement</th>
</tr>
</thead>
<tbody>
<tr>
<td>ON</td>
<td>Front end</td>
</tr>
<tr>
<td>OFF</td>
<td>Rear end</td>
</tr>
</tbody>
</table>

---

**<Replacement of double solenoid>**

(ROBO Cylinder)  

(PSEP / ASEP)

<table>
<thead>
<tr>
<th>Signal to controller Input 1</th>
<th>Signal to controller Input 0</th>
<th>Rod movement</th>
</tr>
</thead>
<tbody>
<tr>
<td>ON</td>
<td>OFF</td>
<td>Front end</td>
</tr>
<tr>
<td>OFF</td>
<td>ON</td>
<td>Rear end</td>
</tr>
</tbody>
</table>

*The main body moves between the same two points listed above, but it can also travel between three points by switching the parameters.*
ROBO Cylinder IK Series
Your Multi-Axes Solution!

Easy Assembly
The complete kit includes everything needed for fast and easy assembly.

Low Cost
With the IK Series, your ROI is realized faster than you can imagine, making IAI the perfect complete solution for any application!

Motor Options
The IK Series is offered in both pulse and servo motors. Choose the pulse motor for applications requiring high thrust at low speeds. Choose the servo motor for applications requiring constant thrust regardless of the operating speed.

High Functionality
Combined with the PCON/PSEL/SCON/SSEL/XSEL controllers, complex programming is made easy.
The IK Series offers the easy cost effective SOLUTION tailored to your needs. The kit comprises the following components needed to assemble a cartesian robot:

- X-axis ROBO Cylinder
- Y-axis ROBO Cylinder
- XY Bracket
- X Guide Rail
- Frame Cover
- Y Guide Rail
- X Plate (single)
- X Plate (double)
- Cable Track
- Bearer Mounting Bracket (SS8)
- Bearer Mounting Bracket (SS7)
- Mounting Screws

Note: The above images are provided for reference purposes only. The actual components may vary depending on the combination type, direction, etc.

*Specifications without cable tracks are also available.*
New ROBO Cylinder Lineup

ROBO Cylinder  
RCP3/RCA2 Series

The New ROBO Cylinders have become more affordable and easier to use

Our Advancement for Your Benefit
We have taken the time to completely re-engineer the guide, ball screws and servo motor to reduce manufacturing costs. We are proud to make IAI’s high-quality electric actuators even more affordable!

New Table Type Actuators
Perfect for applications that require the handling of high moment loads, the new Table Type actuators have a built-in guide to handle loads with ease.

New Ultra-slim Slider Type (32mm in width)
The ideal for applications with space constraints, the new ultra-slim type SA3 (32mm wide) actuator is the ideal choice when only the best will do.

No-Cover Option
You can choose to have your actuator supplied without the exterior covers and stainless steel dust cover for even more cost savings.

Pulse-Motor RCP3 Series & Servo-Motor RCA2 Series
The RCP3 series is driven by a pulse motor and is affordably priced offering excellent push-motion performance, etc. The RCA2 series is driven by a servo motor and achieves high-speed movement while also ensuring quiet operation.

High-Speed Type  
RCA/RCS2 Series

Achieve 1G with the High-Acceleration/Deceleration ROBO Cylinders

Shorten your Cycle Time with Increased Acceleration/Deceleration
Since the acceleration can be increased to a max of 1G, the high-speed actuators will allow shorter cycle times speeding up production.

Keep your Load Capacity even when the Acceleration/Deceleration is increased
Even with 1G acceleration/deceleration, the RCA/RCS2 series can operate at the same load capacity as lower acceleration.

*The maximum load capacity will not increase when the acceleration/deceleration is decreased.
Ultra-High Thrust Type

RCS2-RA13R Series

Ultra-High Thrust Actuators Capable of 2t Press Force

With the high-output servo motor, these motorized actuators can perform push-motion operation with a maximum push force of 2 tons and also achieve high-precision position control. The RCS2-RA13R series lets you adjust the push force and control positions, which are difficult to do with hydraulic actuators.

Application Examples

- **Press-Fitting of Pins**
  - Press-fit position (height) can be adjusted

- **Press-Fitting of Bearings**
  - Push speed can be adjusted

- **Riveting**
  - Push force can be adjusted

- **Raising/Lowering of Heavy Objects**
  - Weights up to 300kg can be raised/lowered

Rotary Type

RCP2-RTBL/RTCL Series

Multiple Rotation Actuators Capable of Rotating Continuously in the Same Direction

Application Example

- **Positioning Operations Involving Rotations of 360 Degrees or More**
  - Since there are no stoppers, positioning operations involving rotations of 360 degrees or more are supported

- **Multiple Rotation Operations**
  - Since the RCP2-RTBL/RTCL series can be operated in the same rotating direction, the series is ideal for applications where loads are fed continuously in the same direction.
  - *The multiple rotation operation mode, each travel is limited to a range within +/-360 degrees.*
New ROBO Cylinder Lineup

**ROBO Cylinder**
**Long-Stroke Gripper**
RCP2-GRST

Ultra-Small High Speed Linear Servo Actuator with Up to 2G Acceleration
- Strokes of up to 100mm (50mm each side)
- High-Speed Specification with Higher Opening/Closing Speeds
- High Gripping Forces up to 40N
- Selectable Cable Exit Direction

**RCP2-GRSS/GRLS**
Small Electric Gripper
The new motorized grippers achieve high grip force and long stroke in a compact body.

**Teach Pendant**
CON-T/SEL-T (TD)

A New Teach Pendant Series Offering Improved Environmental Resistance and Safety Specifications

**IP54 Protection**
The excellent dust-proof/splash-proof performance makes the teach pendants usable in an undesirable environment where the teach pendant comes in contact with fine particles and moisture.

**Compliance with the CE Mark Standard (ANSI standard)**
All models comply with the CE Mark standard. The SEL-TD type is also UL and ANSI-compliant.

**High-Output Actuator Controller**
PCON-CF

The PCON-CF Controller is Designed Exclusively for use with RCP2 Series High-Output Motors
- RCP2-RA10C
- RCP2-HSB/HSB
- RCP2W-SA10C
A New Concept: Network Controller that Significantly Reduces the Hassle of Wiring and Installation

**Connection to Field Networks**
The RoboNet supports many major network protocols such as DeviceNet, CC-Link and Profinet.

**Reduced Man-Hours Through Wire-Saving Design**
Since the I/O signals can be wired using a single dedicated network cable, wiring man-hours can be reduced significantly.

**Easy Serial Communication Using Function Blocks**
Function blocks that eliminate the need for communication programs are available as options (provided free of charge).

**Operation by Numerical Specification of Moving Position, Speed, Etc.**
Instead of registering positions beforehand, you can operate your system by sending desired positions and speeds as data.

All you Need is to Connect your Incremental Actuator to a PCON/ACON Controller, and the Actuator can be Used as a Simple Absolute Actuator. (The simple absolute unit is also set in RoboNet)

**No Need for Home Return**
The built-in rechargeable battery in the simple absolute unit retains the encoder data even after the controller power is cut off. Accordingly, the actuator will not require home return the next time the power is turned on.

**Retention of Encoder Data for up to 20 Days**
Encoder data can be retained for up to 20 consecutive days.
## Controllers

### Supported Controllers

<table>
<thead>
<tr>
<th>Controllers</th>
<th>RCP2 RCP3 series</th>
<th>RCL RCA2 series</th>
<th>RCS2 series</th>
</tr>
</thead>
<tbody>
<tr>
<td>Position controller</td>
<td>24 VDC pulse motor type</td>
<td>24 VDC servo motor type</td>
<td>200 VAC servo motor type</td>
</tr>
<tr>
<td><strong>Positioner Type</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>These controllers support a maximum of 512 positioning points. You can also use it as a solenoid valve controller or serial communications controller, simply by changing the mode setting.</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Solenoid Valve Type</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Controls are made easy with effortless 3-point positioning. You can use the same solenoid-valve control operations you are already familiar with on your air cylinders.</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Pulse-Train Input Type</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>These controllers eliminate the need to input positions in advance. They are ideal in applications require many or complex operation patterns, or where flexibility is required in changing speed and other settings.</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Serial Communication Type</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>These controllers are used to connect to DeviceNet, CC-Link and FieldBus via a gateway unit. Their compact, low-cost construction is perfect for multi-axis operations.</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>RoboNet</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Reduce wiring and installation headaches with RoboNet. Operate via field network and connect up to 16 axes and register up to 768 points in Positioner mode and Simple Direct Value Mode. There is no limit on the number of positioning points when in Direct Numeric Value Mode. DIN-rail installation means that the controller can be fastened and removed with ease.</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Program controller

<table>
<thead>
<tr>
<th>Program controller</th>
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</tr>
</thead>
<tbody>
<tr>
<td>Program Type</td>
<td>Program controllers can operate 1, 2 and up to 6 axes. Since interpolation operation is possible, they are ideal for coating and palletizing operations requiring synchronized movements of 2 axes. You can set a maximum of 1,500 positions and 20,000 positions on the newly improved XSEL controller. The XSEL controller was further improved with the new ROBO Cylinder gateway function, which added the capacity to control a total of 22 axes.</td>
<td></td>
</tr>
</tbody>
</table>

* Refer to ROBO Cylinder General Catalog for more info
Mounting

Various Mounting Methods

ENERGY EFFICIENT ROBO Cylinder RCA/RCS2 actuators are available with optional MOUNTING BRACKETS similar to those normally used with air cylinders, such as the foot, TRUNNION and clevis. The rod tip accepts a knuckle joint, floating joint or other mounting brackets, so you can quickly and COST-EFFECTIVELY convert your existing air cylinder to a ROBO Cylinder to maximize ROI.

![Mounting Methods Examples]

Application Examples

Want to replace an existing air cylinder without hassle

Solenoid valve type

The PCON-CY and ACON-CY are recommended. [You can also use the SCON-C in the PIO mode.] Your ROBO Cylinder can be controlled just like an air cylinder.

Want to connect to CC-Link and DeviceNet

Serial communication type

You can connect the PCON-SE or ACON-SE to a gateway unit. The SCON connects directly to field networks.

Number of connectable units: DeviceNet – 16 units, CC-Link – 14 units

Want to operate it using a PLC based on pulse trains

Pulse-train input type

You can use the PCON-PL/PO, ACON-PL/PO or SCON-C.

Want to operate two axes

The PSEL, ASEL and SSEL have two-axis types. They can perform synchronized operation and interpolation operation.

Want to install it based on clevis/trunnion mount

Select either the rod-type RA3 or RA4 in the RCA/RCS2 series.