RCA2-TFA3NA

Robo Cylinder, Mini Table Type, Short-Length Flat Type, Actuator Width 61mm, 24V Servo Motor, Ball Screw Specification/Lead Screw Specification

Model Specification Items

RCA2 — **TFA3NA** — **I** — **10** — □ — □ — □ — □ — □ — □

Series	Type	Encoder type	Motor type	Lead	Stroke	Applicable controller	Cable length	Options
		I: Incremental * The Simple absolute encoder is also considered type "I".	10: 10W Servo motor	4: Ball screw 4mm 2: Ball screw 2mm 1: Ball screw 1mm 4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	30: 30mm 50: 50mm	A1: ACON ASEL A3: AMEC ASEP MSEP	N: None P: 1m S: 3m M: 5m X□□: Custom Length	See options below.

* See page Pre-47 for details on the model descriptions.

CE RoHS

Power-saving

Technical References → Appendix P.5

POINT Notes on selection

(1) The payload is the value when the actuator is operated at an acceleration of 0.3 G (0.2G for 1mm-lead, if used vertically and for lead screw specification). The acceleration limit is the value indicated above.
(2) If the actuator is used vertically, pay attention to rod contact because the rod will come down when the power is turned off.
(3) See page A-71 for details on push motion.

Actuator Specifications

■ Leads and Payloads

Model number	Motor output (W)	Feed screw	Lead (mm)	Max. Load Capacity Horizontal (kg)	Max. Load Capacity Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-TFA3NA-I-10-4-①-②-③-④	10	Ball screw	4	0.75	0.25	42.7	±0.02	30 50
RCA2-TFA3NA-I-10-2-①-②-③-④			2	1.5	0.5	85.5		
RCA2-TFA3NA-I-10-1-①-②-③-④			1	3	1	170.9		
RCA2-TFA3NA-I-10-4S-①-②-③-④	10	Lead screw	4	0.25	0.125	25.1	±0.05	30 50
RCA2-TFA3NA-I-10-2S-①-②-③-④			2	0.5	0.25	50.3		
RCA2-TFA3NA-I-10-1S-①-②-③-④			1	1	0.5	100.5		

■ Stroke and Maximum Speed

Lead	Stroke 30 (mm)	Stroke 50 (mm)
Ball screw 4	200	
Ball screw 2	100	
Ball screw 1	50	
Lead screw 4	200	
Lead screw 2	100	
Lead screw 1	50	

(Unit: mm/s)

Code explanation ① Stroke ② Applicable controller ③ Cable length ④ Options *See page A-71 for details on push motion.

① Stroke

Stroke (mm)	Standard price: Feed screw: Ball screw	Standard price: Feed screw: Lead screw
30	—	—
50	—	—

③ Cable Length

Type	Cable symbol	Standard price
Standard (Robot Cables)	**P** (1m)	—
	S (3m)	—
	M (5m)	—
Special length	**X06** (6m) ~ **X10** (10m)	—
	X11 (11m) ~ **X15** (15m)	—
	X16 (16m) ~ **X20** (20m)	—

* The standard cable for the RCA2 is the robot cable.
* See page A-59 for cables for maintenance.

④ Options

Name	Option code	See page	Standard price
Brake	**B**	→ A-42	—
Connector cable exits from the left	**K1**	→ A-51	—
Connector cable exits from the front	**K2**	→ A-51	—
Connector cable exits from the right	**K3**	→ A-51	—
Power-saving specification	**LA**	→ A-52	—

Actuator Specifications

Item		Description
Drive System		Ball screw/Lead screw, ø4mm, rolled C10
Lost Motion		Ball screw: 0.1mm or less Lead screw: 0.3mm or less (initial value)
Frame		Material: Aluminum, white alumite treated
Allowable dynamic moment (Note)		Ma: 9.9 N·m, Mb: 9.9 N·m, Mc: 3.3 N·m
Allowable static moment		Ma: 14.1 N·m, Mb: 14.1 N·m, Mc: 6.7 N·m
Ambient operating temperature, humidity		0 to 40°C, 85% RH or less (Non-condensing)
Service life	Lead screw specification	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles
	Ball screw specification	5,000km or 50 million cycles (*)

(Note) For cases when the guide service life has been set to 5,000km.
(*) For 1mm-lead: 3,000km or 50 million cycles.

Dimensional Drawings

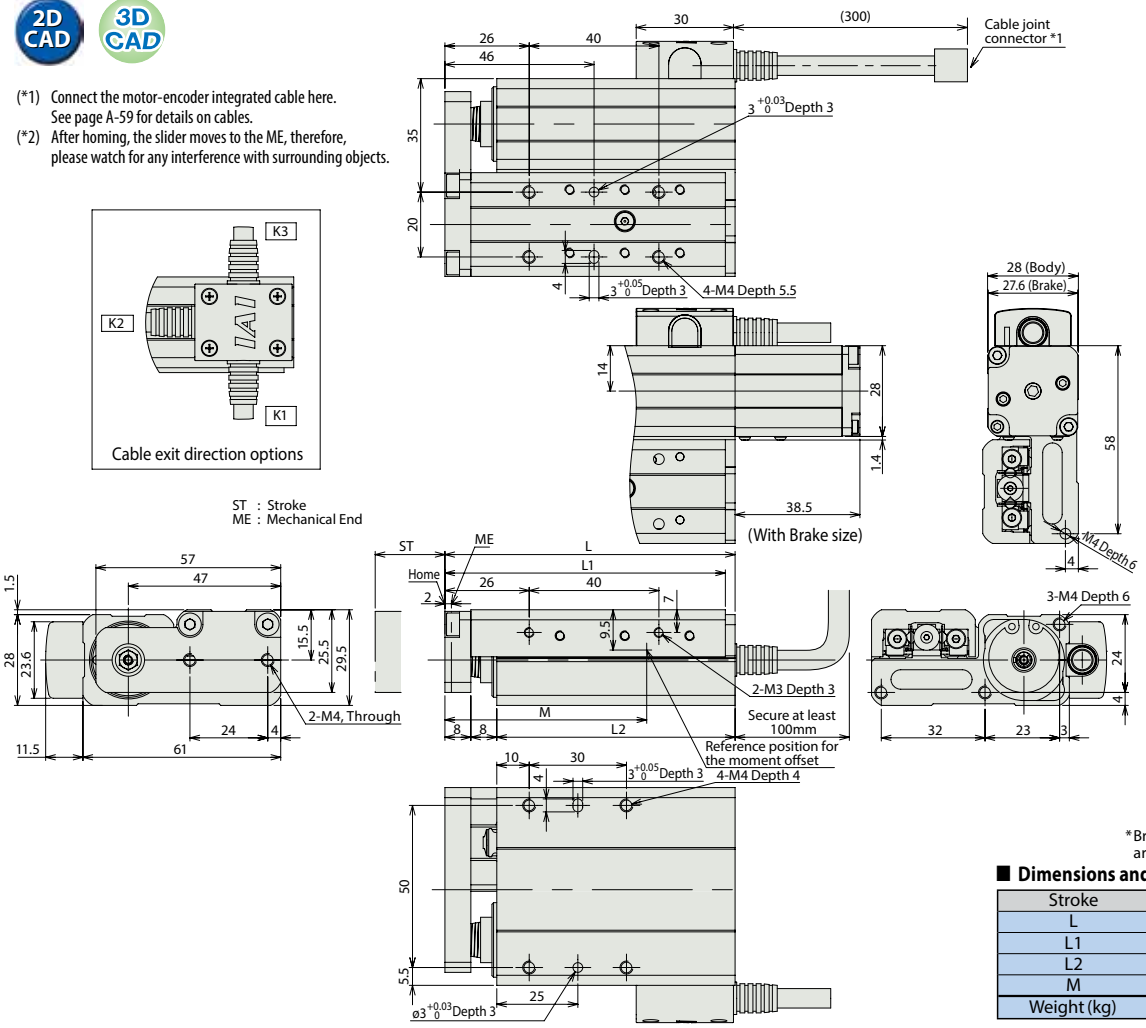
CAD drawings can be downloaded from the website. www.intelligentactuator.com

For Special Orders Appendix P.15

2D CAD 3D CAD

(*1) Connect the motor-encoder integrated cable here. See page A-59 for details on cables.
(*2) After homing, the slider moves to the ME, therefore, please watch for any interference with surrounding objects.

Cable exit direction options



*Brake-equipped models are heavier by 0.1kg.

■ Dimensions and Weight by Stroke

Stroke	30	50
L	89.5	109.5
L1	86.5	106.5
L2	73.5	93.5
M	64	84
Weight (kg)	0.4	0.48

②Applicable Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application. * ACON-CY also can be used.

Name	External view	Model number	Features	Maximum number of positioning points	Input power	Power-supply capacity	Standard price	Reference page
Solenoid Valve Type		AMEC-C-10I①-②-2-1	Easy-to-use controller, even for beginners	3 points	AC100V	2.4A rated	—	→ P537
		ASEP-C-10I①-②-2-0	Simple controller operable with the same signal as a solenoid valve		DC24V	(Standard) 1.3A rated 4.4A max. (Power-saving) 1.3A rated 2.5A max.	—	→ P547
Solenoid valve multi-axis type PIO specification		MSEP-C-③-~~-②-2-0	Positioner type based on PIO control, allowing up to 8 axes to be connected				—	→ P563
Solenoid valve multi-axis type Network specification		MSEP-C-③-~~-Ⓥ-0-0	Field network-ready positioner type, allowing up to 8 axes to be connected	256 points				
Positioner type		ACON-C-10I①-②-2-0	Positioning is possible for up to 512 points	512 points			—	→ P631
Safety-Compliant Positioner Type		ACON-CG-10I①-Ⓥ-2-0					—	
Pulse Train Input Type (Differential Line Driver)		ACON-PL-10I①-②-2-0	Pulse train input type with differential line driver support	(—)			—	
Pulse Train Input Type (Open Collector)		ACON-PO-10I①-②-2-0	Pulse train input type with open collector support				—	
Serial Communication Type		ACON-SE-10I①-N-0-0	Dedicated Serial Communication	64 points			—	
Program Control Type		ASEL-CS-1-10I①-②-2-0	Programmed operation is possible. Can operate up to 2 axes	1,500 points			—	→ P675

* This is for the single-axis ASEL. * Enter the code "LA" in ① when the power-saving specification is specified. * ② indicates I/O type (NP/PN).
* ③ indicates number of axes (1 to 8). * Ⓥ indicates field network specification symbol.