\* See page Pre-47 for details on the model descriptions.

# CA2-TCA3NA

Robo Cylinder, Mini Table Type, Short-Length Compact Type, Actuator Width 32mm, 24V Servo Motor, Ball Screw Specification/Lead Screw Specification

Model Specification Items

RCA2 — TCA3NA — Series — Type – Encoder type — Motor type —

I: Incremental

encoder is also

\* The Simple absolute

considered type "I".

10

10:10W Servo

motor

Lead

Ball screw 2mm 50: 50mm

Ball screw 1mm

4S: Lead screw 4mm

2S: Lead screw 2mm

1S: Lead screw 1mm

Stroke 4: Ball screw 4mm 30: 30mm

Applicable controller Cable length A1:ACON N: None

— Options See options below.

ASEL P: 1m A3:AMEC S: 3m ASEP M:5m

MSEP X□□:Custom Length

[C €] RoHS



**Power-saving** 

Technical References P.5

The payload is the value when the actuator is operated at an acceleration of 0.3 G (0.2G for 1mm-Lead, if used vertically and for lead screw specification). The acceleration limit is the value indicated above.

(2) If the actuator is used vertically, pay attention to rod contact because the rod will come down when the power is turned off.

(3) See page A-71 for details on push motion.

## Actuator Specifications

#### ■ Leads and Payloads

Model number	Motor output (W)	Feed screw	Lead (mm)	Max. Load Horizontal (kg)	Capacity Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-TCA3NA-I-10-4-①-②-③-④			4	0.75	0.25	42.7		
RCA2-TCA3NA-I-10-2-①-②-③-④	10	Ball screw	2	1.5	0.5	85.5	±0.02	30 50
RCA2-TCA3NA-I-10-1-①-②-③-④			1	3	1	170.9		
RCA2-TCA3NA-I-10-4S-①-②-③-④			4	0.25	0.125	25.1		
RCA2-TCA3NA-I-10-2S-①-②-③-④	10	Lead screw	2	0.5	0.25	50.3	±0.05	30 50
RCA2-TCA3NA-I-10-1S-①-②-③-④			1	1	0.5	100.5		
Code explanation ① Stroke ② Applicable controller ③ Cable length ④ Options *See page A-71 for details on push motion.								

See page Standard price

→ A-42

→ A-51

→ A-51

→ A-51

→ A-52

Stroke and Maximum Speed

Lea	Stroke	30 (mm)	50 (mm)			
>	4	200				
Ball screw	2					
Ba	1	50				
No.	4	200				
Lead screw	2	10	00			
1		5	0			

(Unit: mm/s)

①Stroke

4 Options

Brake

Stroke (mm)	Standard price			
	Feed screw			
	Ball screw	Lead screw		
30	_	_		
50	_	_		

Option code

В

K1

K2

**K**3

LA

③Cable Length

Notes or

Type	Cable symbol	Standard price
Standard (Robot Cables)	<b>P</b> (1m)	_
	<b>S</b> (3m)	_
	<b>M</b> (5m)	_
Special length	<b>X06</b> (6m) ~ <b>X10</b> (10m)	_
	X11 (11m) ~ X15 (15m)	_
	X16 (16m) ~ X20 (20m)	_

<sup>\*</sup>The standard cable for the RCA2 is the robot cable. \*See page A-59 for cables for maintenance.

### Actuator Specifications

ltem		Description		
Drive System		Ball screw/Lead screw, ø4mm, rolled C10		
Lost Motion		Ball screw: 0.1mm or less Lead screw: 0.3mm or less (initial value)		
Frame		Material: Aluminum, white alumite treated		
Allowable dynamic moment (Note)		Ma: 9.9 N·m, Mb: 9.9 N·m, Mc: 3.3 N·m		
Allowable static moment		Ma: 14.1 N·m, Mb: 14.1 N·m, Mc: 6.7 N·m		
Ambient operating temperature, humidity		0 to 40°C, 85% RH or less (Non-condensing)		
Service life	Lead screw specification	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles		
	Ball screw specification	5,000km or 50 million cycles (*)		

(Note) For cases when the guide service life has been set to 5,000km. (\*) For 1mm-lead: 3,000km or 50 million cycles.

Name

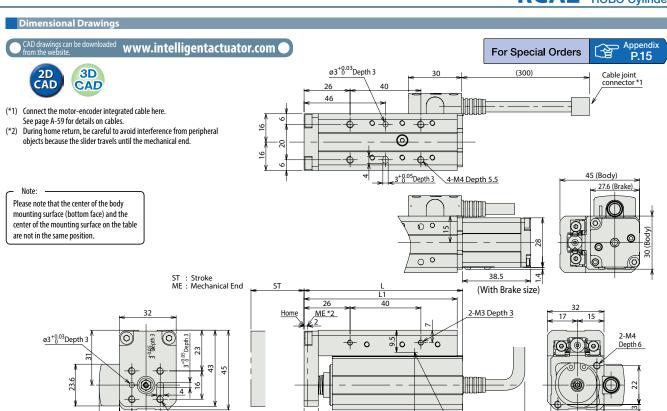
Connector cable exits from the left

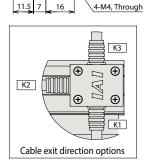
Connector cable exits from the front

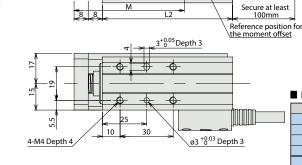
Connector cable exits from the right

Power-saving specification

30







		e heavier by	
	Stroke	30	50
√25 → 25 →	L	89.5	109.5
ri 10 30	L1	86.5	106.5
4 Depth 4 ø3 +0.03 Depth 3	L2	73.5	93.5
	M	64	84
	Weight (kg)	0.37	0.44

#### ② Applicable Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application. \* ACON-CY also can be used.

Name	External view	Model number	Features	Maximum number of positioning points	Input power	Power- supply capacity	Standard price	Reference page
Solenoid Valve Type		AMEC-C-10I①-①-2-1	Easy-to-use controller, even for beginners		AC100V	2.4A rated	_	→ P537
	1	ASEP-C-10I①-①-2-0	Simple controller operable with the same signal as a solenoid valve	3 points			_	→ P547
Solenoid valve multi-axis type PIO specification		MSEP-C	Positioner type based on PIO control, allowing up to 8 axes to be connected			(Standard) 1.3A rated 4.4A max. (Power-saving) 1.3A rated 2.5A max.		→ P563
Solenoid valve multi-axis type Network specification		MSEP-C-(  )-~-( \vec{V}-0-0	Field network-ready positioner type, allowing up to 8 axes to be connected	256 points			_	
Positioner type	I.	ACON-C-10I①-①-2-0	Positioning is possible for up to 512 points	512 points	DC24V		_	→ P631
Safety-Compliant Positioner Type		ACON-CG-10I①					_	
Pulse Train Input Type (Differential Line Driver)		ACON-PL-10I①-①-2-0	Pulse train input type with differential line driver support	( )			_	
Pulse Train Input Type (Open Collector)		ACON-PO-10I①-⑪-2-0	Pulse train input type with open collector support	(—)			_	
Serial Communication Type		ACON-SE-10I①-N-0-0	Dedicated Serial Communication	64 points			_	
Program Control Type		ASEL-CS-1-10I①-⑪-2-0	Programmed operation is possible. Can operate up to 2 axes	1,500 points				→ P675

\* This is for the single-axis ASEL. 

\* Enter the code "LA" in ⊕ when the power-savir

† ⊕ indicates number of axes (1 to 8). † ⊕ indicates field network specification symbol