

RCA2-GD3NA

Robo Cylinder, Mini Rod Type, Short-Length Double-Guide Type, Actuator Width 28mm, 24V Servo Motor, Ball Screw Specification/Lead Screw Specification

Model Specification Items	RCA2 — GD3NA — I — 10	—	—	—	—	—	—	—	—
Series	Type	Encoder type	Motor type	Lead	Stroke	Applicable controller	Cable length	Options	
I: Incremental * The Simple absolute encoder is also considered type "I".	10: 10W Servo motor	4: Ball screw 4mm 2: Ball screw 2mm 1: Ball screw 1mm 4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	30: 30mm 50: 50mm	A1: ACON ASEL A3: AMEC ASEP MSEP	N: None P: 1m S: 3m M: 5m X□□: Custom Length	See options below.			

* See page Pre-47 for details on the model descriptions.



Power-saving



Technical References Appendix P.5

- POINT**
Notes on selection
- (1) The horizontal payload is the value when used in combination with a guide so that a radial load and moment load are not applied to the rod. Please refer to page A-111 for correlation diagrams of the end load and service life when a guide is not installed.
 - (2) The payload is the value when the actuator is operated at an acceleration of 0.3 G (0.2G for lead 1, if used vertically and for lead screw specification). The acceleration limit is the value indicated above.
 - (3) If the actuator is used vertically, pay attention to rod contact because the rod will come down when the power is turned off.
 - (4) See page A-71 for details on push motion.

Actuator Specifications

Leads and Payloads

Model number	Motor output (W)	Feed screw	Lead (mm)	Max. Load Capacity		Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
				Horizontal (kg)	Vertical (kg)			
RCA2-GD3NA-I-10-4-①-②-③-④	10	Ball screw	4	0.75	0.25	42.7	±0.02	30 50
RCA2-GD3NA-I-10-2-①-②-③-④			2	1.5	0.5	85.5		
RCA2-GD3NA-I-10-1-①-②-③-④			1	3	1	170.9		
RCA2-GD3NA-I-10-4S-①-②-③-④	10	Lead screw	4	0.25	0.125	25.1	±0.05	30 50
RCA2-GD3NA-I-10-2S-①-②-③-④			2	0.5	0.25	50.3		
RCA2-GD3NA-I-10-1S-①-②-③-④			1	1	0.5	100.5		

Stroke and Maximum Speed

Lead	Stroke	30 (mm)		50 (mm)	
		Ball screw	Lead screw	Ball screw	Lead screw
Ball screw	4	—	200	—	—
	2	—	100	—	—
	1	—	50	—	—
Lead screw	4	—	200	—	—
	2	—	100	—	—
	1	—	50	—	—

Code explanation ① Stroke ② Applicable controller ③ Cable length ④ Options *See page A-71 for details on push motion.

(Unit: mm/s)

① Stroke

Stroke (mm)	Standard price	
	Ball screw	Lead screw
30	—	—
50	—	—

③ Cable Length

Type	Cable symbol	Standard price
Standard (Robot Cables)	P (1m)	—
	S (3m)	—
	M (5m)	—
Special length	X06 (6m) ~ X10 (10m)	—
	X11 (11m) ~ X15 (15m)	—
	X16 (16m) ~ X20 (20m)	—

* The standard cable for the RCA2 is the robot cable.
* See page A-59 for cables for maintenance.

④ Options

Name	Option code	See page	Standard price
Brake	B	→ A-42	—
Connector cable exits from the left	K1	→ A-51	—
Connector cable exits from the front	K2	→ A-51	—
Connector cable exits from the right	K3	→ A-51	—
Power-saving specification	LA	→ A-52	—

Actuator Specifications

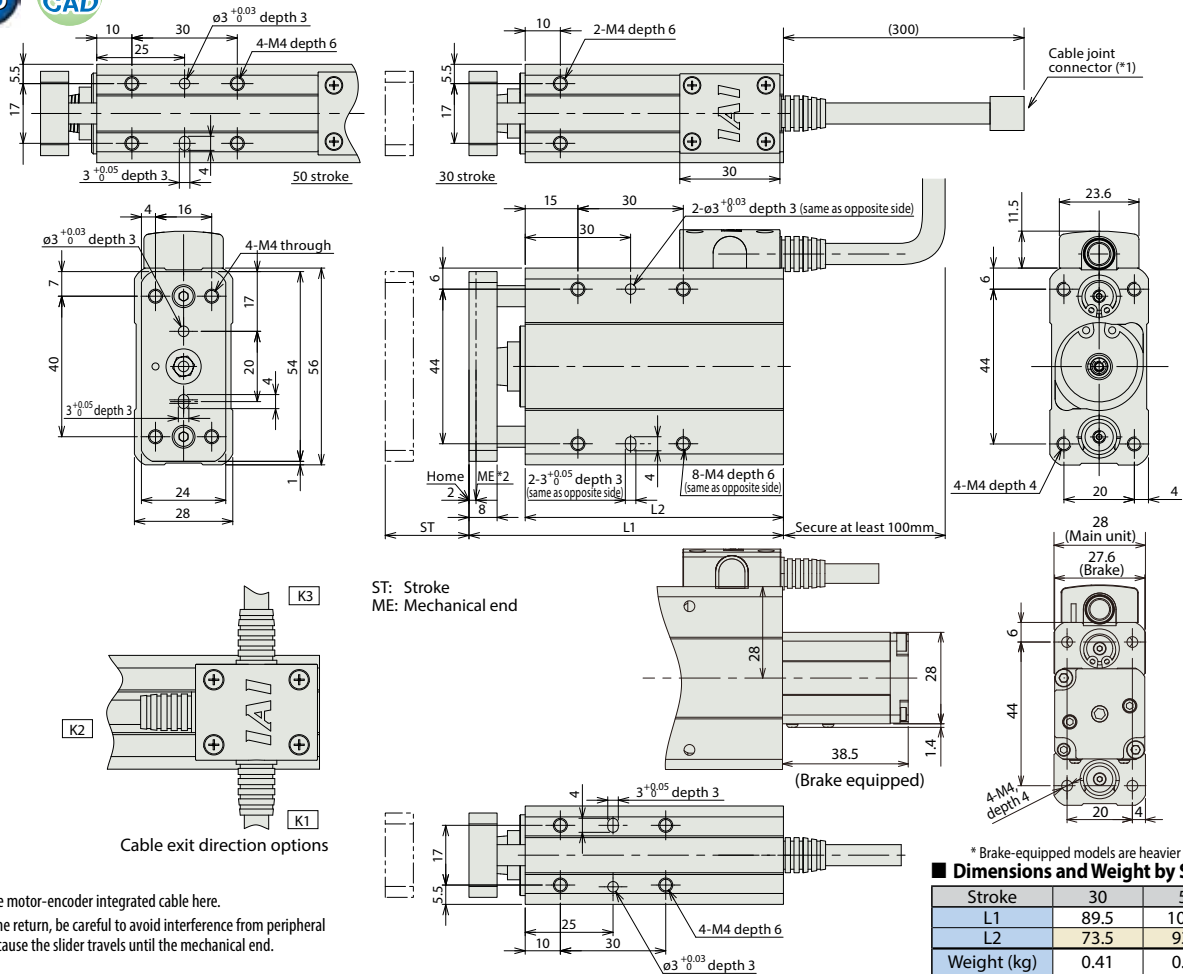
Item	Description
Drive System	Ball screw/Lead screw, ø4mm, rolled C10
Lost Motion	Ball screw: 0.1mm or less
	Lead screw: 0.3mm or less (initial value)
Frame	Material: Aluminum, white alumite treated
Ambient operating temperature, humidity	0 to 40°C, 85% RH or less (Non-condensing)
Service life	Lead screw specification
	Ball screw specification

- Slider Type
- Mini
- Standard
- Controllers Integrated
- Rod Type
- Mini
- Standard
- Controllers Integrated
- Table/Arm/Flat Type
- Mini
- Standard
- Gripper/Rotary Type
- Linear Servo Type
- Clean-room Type
- Splash-Proof Type
- Pulse Motor
- Servo Motor (24V)
- Servo Motor (200V)
- Linear Servo Motor

Dimensional Drawings

CAD drawings can be downloaded from the website. www.intelligentactuator.com

For Special Orders Appendix P.15



■ Dimensions and Weight by Stroke

Stroke	30	50
L1	89.5	109.5
L2	73.5	93.5
Weight (kg)	0.41	0.48

(*1) Connect the motor-encoder integrated cable here.
(*2) During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.

② Applicable Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application. * ACON-CY also can be used.

Name	External view	Model number	Features	Maximum number of positioning points	Input power	Power-supply capacity	Standard price	Reference page
Solenoid Valve Type		AMEC-C-10I①①-2-1	Easy-to-use controller, even for beginners	3 points	AC100V	2.4A rated	—	→ P537
		ASEP-C-10I①①-2-0	Simple controller operable with the same signal as a solenoid valve					→ P547
Solenoid valve multi-axis type PIO specification		MSEP-C-③④⑤⑥⑦⑧⑨⑩-2-0	Positioner type based on PIO control, allowing up to 8 axes to be connected	256 points	DC24V	(Standard) 1.3A rated 4.4A max.	—	→ P563
Solenoid valve multi-axis type Network specification		MSEP-C-③④⑤⑥⑦⑧⑨⑩-0-0	Field network-ready positioner type, allowing up to 8 axes to be connected					
Positioner type		ACON-C-10I①①-2-0	Positioning is possible for up to 512 points	512 points	DC24V	(Power-saving) 1.3A rated 2.5A max.	—	→ P631
Safety-Compliant Positioner Type		ACON-CG-10I①①-2-0						
Pulse Train Input Type (Differential Line Driver)		ACON-PL-10I①①-2-0	Pulse train input type with differential line driver support	(—)	DC24V	(Power-saving) 1.3A rated 2.5A max.	—	→ P631
Pulse Train Input Type (Open Collector)		ACON-PO-10I①①-2-0	Pulse train input type with open collector support					
Serial Communication Type		ACON-SE-10I①①-N-0-0	Dedicated Serial Communication	64 points	DC24V	(Power-saving) 1.3A rated 2.5A max.	—	→ P675
Program Control Type		ASEL-CS-1-10I①①-2-0	Programmed operation is possible. Can operate up to 2 axes	1,500 points	DC24V	(Power-saving) 1.3A rated 2.5A max.	—	→ P675

* This is for the single-axis ASEL. * Enter the code "LA" in ① when the power-saving specification is specified. * ①① indicates I/O type (NP/PN).
* ③④⑤⑥⑦⑧⑨⑩ indicates number of axes (1 to 8). * ④⑤⑥⑦⑧⑨⑩ indicates field network specification symbol.