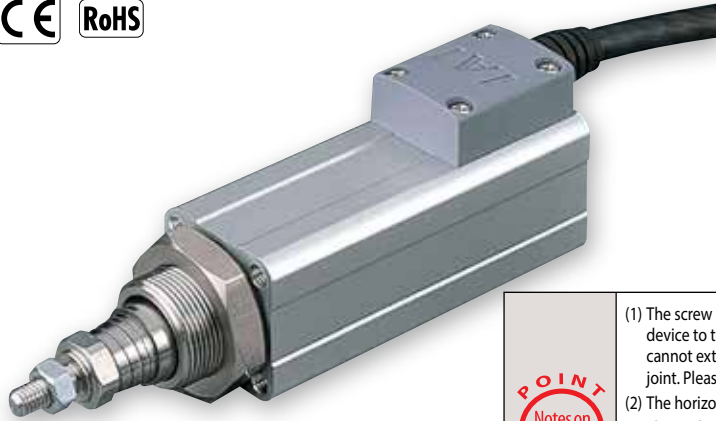


# RCA2-RN4NA

Robo Cylinder, Mini Rod Type, Short-Length Nut Mounting Type, Actuator Width 34mm, 24V Servo Motor, Ball Screw Specification/Lead Screw Specification

Model Specification Items	<b>RCA2 — RN4NA — I — 20</b>	—	—	—	—	—	—	—	—
Series	Type	Encoder type	Motor type	Lead	Stroke	Applicable controller	Cable length	Options	
I: Incremental * The Simple absolute encoder is also considered type "I".	20: 20W Servo motor	6: Ball screw 6mm 4: Ball screw 4mm 2: Ball screw 2mm 6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm	30: 30mm 50: 50mm	A1: ACON ASEL A3: AMEC ASEP MSEP	N: None P: 1m S: 3m M: 5m X□□: Custom Length	See options below.			

\* See page Pre-47 for details on the model descriptions.



Power-saving

Technical References Appendix P.5



- (1) The screw is not equipped with an anti-rotation device, so please attach a guide or similar locking device to the tip of the screw prior to use. (If there is no anti-rotation device attached, the screw cannot extend or retract.) When connecting the anti-rotation device to the rod, do not use a floating joint. Please refer to page A-11 for the instruction details.
- (2) The horizontal payload is the value when the actuator uses an external guide.
- (3) The payload is the value when the actuator is operated at an acceleration of 0.3 G (0.2G for lead 2, if used vertically and for lead screw specification). The acceleration limit is the value indicated above.
- (4) Do not apply an external force on the rod in any direction other than the direction the rod is moving in.
- (5) If the actuator is used vertically, pay attention to rod contact because the rod will come down when the power is turned off.
- (6) See page A-71 for details on push motion.

### Actuator Specifications

#### Leads and Payloads

Model number	Motor output (W)	Feed screw	Lead (mm)	Max. Load Capacity		Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
				Horizontal (kg)	Vertical (kg)			
RCA2-RN4NA-I-20-6-①-②-③-④	20	Ball screw	6	2	0.5	33.8	±0.02	30 50
RCA2-RN4NA-I-20-4-①-②-③-④			4	3	0.75	50.7		
RCA2-RN4NA-I-20-2-①-②-③-④			2	6	1.5	101.5		
RCA2-RN4NA-I-20-6S-①-②-③-④	20	Lead screw	6	0.25	0.125	19.9	±0.05	30 50
RCA2-RN4NA-I-20-4S-①-②-③-④			4	0.5	0.25	29.8		
RCA2-RN4NA-I-20-2S-①-②-③-④			2	1	0.5	59.7		

#### Stroke and Maximum Speed

Lead	Stroke	Maximum Speed	
		30 (mm)	50 (mm)
Ball screw	6	270 <220>	
	4	200	
	2	100	
Lead screw	6	220	300
	4	200	
	2	100	

Code explanation ① Stroke ② Applicable controller ③ Cable length ④ Options \* See page A-71 for details on push motion. \* The values enclosed in < > apply to vertical settings. (Unit: mm/s)

#### ① Stroke

Stroke (mm)	Standard price	
	Ball screw	Lead screw
30	—	—
50	—	—

#### ③ Cable Length

Type	Cable symbol	Standard price
Standard (Robot Cables)	P (1m)	—
	S (3m)	—
	M (5m)	—
Special length	X06 (6m) ~ X10 (10m)	—
	X11 (11m) ~ X15 (15m)	—
	X16 (16m) ~ X20 (20m)	—
		—

\* The standard cable for the RCA2 is the robot cable.  
\* See page A-59 for cables for maintenance.

#### ④ Options

Name	Option code	See page	Standard price
Brake	B	→ A-42	—
Connector cable exits from the left	K1	→ A-51	—
Connector cable exits from the front	K2	→ A-51	—
Connector cable exits from the right	K3	→ A-51	—
Power-saving specification	LA	→ A-52	—

#### Actuator Specifications

Item	Description
Drive System	Ball screw/Lead screw, ø6mm, rolled C10
Lost Motion	Ball screw: 0.1mm or less
	Lead screw: 0.3mm or less (initial value)
Frame	Material: Aluminum, white alumite treated
Ambient operating temperature, humidity	0 to 40°C, 85% RH or less (Non-condensing)
Service life	Lead screw specification
	Ball screw specification

- Slider Type
- Mini
- Standard
- Controllers Integrated
- Rod Type
- Mini
- Standard
- Controllers Integrated
- Table/ Arm/ Flat Type
- Mini
- Standard
- Gripper/ Rotary Type
- Linear Servo Type
- Clean-room Type
- Splash-Proof Type
- Pulse Motor
- Servo Motor (24V)
- Servo Motor (200V)
- Linear Servo Motor

**Dimensional Drawings**

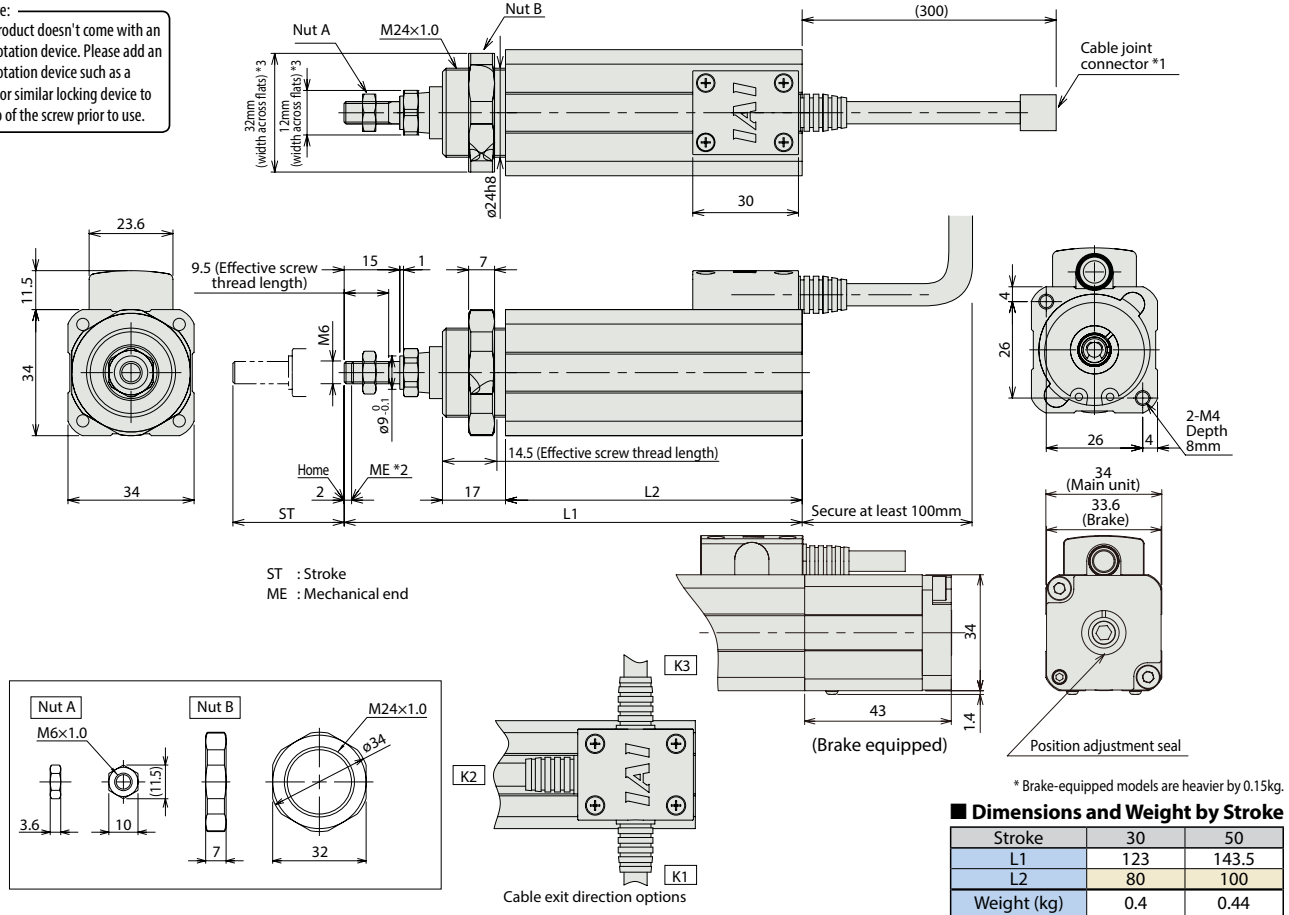
CAD drawings can be downloaded from the website. [www.intelligentactuator.com](http://www.intelligentactuator.com)

For Special Orders Appendix P.15



- (\*1) Connect the motor-encoder integrated cable here.
- (\*2) During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.
- (\*3) The orientation of the nut varies depending on the product.

**Note:**  
This product doesn't come with an anti-rotation device. Please add an anti-rotation device such as a guide or similar locking device to the tip of the screw prior to use.



**② Applicable Controllers**

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application. \* ACON-CY also can be used.

Name	External view	Model number	Features	Maximum number of positioning points	Input power	Power-supply capacity	Standard price	Reference page												
Solenoid Valve Type		AMEC-C-20I①①-2-1	Easy-to-use controller, even for beginners	3 points	AC100V	2.4A rated	—	→ P537												
		ASEP-C-20I①①-2-0	Simple controller operable with the same signal as a solenoid valve																	
Solenoid valve multi-axis type PIO specification		MSEP-C①①①①①①①①①①-2-0	Positioner type based on PIO control, allowing up to 8 axes to be connected	256 points					DC24V	(Standard) 1.3A rated 4.4A max.	—	→ P563								
Solenoid valve multi-axis type Network specification		MSEP-C①①①①①①①①①①-0-0	Field network-ready positioner type, allowing up to 8 axes to be connected																	
Positioner type		ACON-C-20I①①①①①①①①①①-2-0	Positioning is possible for up to 512 points	512 points									(Power-saving) 1.3A rated 2.5A max.	—	—	→ P631				
Safety-Compliant Positioner Type		ACON-CG-20I①①①①①①①①①①-2-0																		
Pulse Train Input Type (Differential Line Driver)		ACON-PL-20I①①①①①①①①①①-2-0	Pulse train input type with differential line driver support	(—)																
Pulse Train Input Type (Open Collector)		ACON-PO-20I①①①①①①①①①①-2-0	Pulse train input type with open collector support																	
Serial Communication Type		ACON-SE-20I①①①①①①①①①①-N-0-0	Dedicated Serial Communication	64 points																
Program Control Type		ASEL-CS-1-20I①①①①①①①①①①-2-0	Programmed operation is possible. Can operate up to 2 axes	1,500 points																

\* This is for the single-axis ASEL. \* Enter the code "LA" in ① when the power-saving specification is specified. \* ① indicates I/O type (NP/PN).  
\* ①① indicates number of axes (1 to 8). \* ①①① indicates field network specification symbol.