Body Width **24**_v Motor Table 70 mm Side-m Stepper Motor Type Type Motor Body width doe not include the width of the side ■ Model **TA7R** -WA **56P** Specification Motor Type Applicable Controller / I/O Type Encoder Type — Stroke Cable Length Options Items [RCP6] P3: PCON N : None P : 1m Please refer to the options table below. RCP6: Separate Controller WA: Battery-less 56P: Stepper 24: 24mm 25: 25mm RCP6S: Built-in Controller Absolute Motor 16: 16mm S : 3m M: 5m 56□ Size 8mm 390: 390mm MCON *Please make sure to X□□: Specified Length R□□: Robot Cable Rounted To specify either ML or MR when ordering the sidemounted To specify either ML or MR when ordering the specify eith MSEL [RCP6S] 4: 4mm * RCP6 does not include a controller. RCP6S includes a built-in controller. * Please refer to P.12 for more information about the model specification items. SE: SIO Type

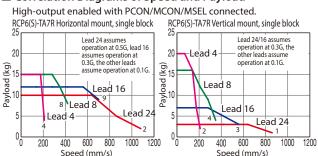


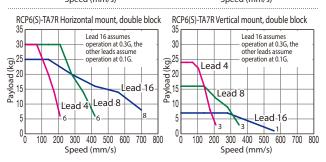
side-mounted to the left (ML).



- (1) The maximum acceleration/deceleration is 1G for horizontal, and 0.5G for vertical use.
- (2) The actuator specification displays the payload's maximum value, but it will vary depending on the acceleration and speed. Please refer to the "Selection Guidelines" (RCP6 Tables of Payload by Speed/Acceleration) on P.115 for more details.
- (3) When performing push-motion operation, please confirm the push force of each model by checking the "Correlation diagram of push force and current limit" on P.113.
- (4) Depending on the ambient operational temperature, duty control is necessary for the RCP6S (built-in controller type) with lead 4/8/16. Please refer to P.130 for more information.
- (5) High-rigidity (double-block) specification can be selected as an option.

■ Correlation Diagrams of Speed and Payload





Actuator Specifications

■ Lead and Pavload

=						
	Model Number	Lead	Connected	Max. P		Stroke
		(mm)	Controller	Horizontal (kg)	Vertical (kg)	(mm)
长	RCP6(S)-TA7R-WA-56P-24-①-②-③-④	24	High-output Enabled	10	3	
Block	RCP6(S)-TA7R-WA-56P-16-①-②-③-④	16	High-output Enabled	12	7	25~300
ngle	RCP6(S)-TA7R-WA-56P-8-①-②-③-④	8	High-output Enabled	15	16	25~300
is	RCP6(S)-TA7R-WA-56P-4-①-②-③-④	4	High-output Enabled	15	20	
Block	RCP6(S)-TA7R-WA-56P-16-①-②-③-④	16	High-output Enabled	25	7	
흥	RCP6(S)-TA7R-WA-56P-8-①-②-③-④	8	High-output Enabled	30	16	40~390
Dou	RCP6(S)-TA7R-WA-56P-4-①-②-③-④	4	High-output Enabled	30	24	

Legend: Stroke	<u></u>	Applicable controller/I/O type	(a)	Cable length	(M)	Ontions
Legena. Toke	W	Applicable controller/1/O type	1(3)	Cable length	14	Options

■ Stroke and Max. Speed

(Unit:	mm/s

RCP6S

	one and	cca	(01111:11111/3)			
Lead	Connected	Single Block	Do	ck		
(mm)	Controller	25~300	40~290	340	390	
24	High-output Enabled	1,080 <860>				
16	High-output Enabled	700 <560>	70 <50	600 <560>		
8	High-output Enabled	420 <350>	420 <350>	365 <350>	300	
4	High-output Enabled	210	210	180	150	

Values in brackets < > are for vertical use.

RCP6

① Stroke

	Single Block			Oouble Block			
Stroke (mm)	RCP6	RCP6S	Stroke (mm)	RCP6	RCP6S		
25	0	0	40	0	0		
50	0	0	65	0	0		
75	0	0	90	0	0		
100	0	0	140	0	0		
125	0	0	190	0	0		
150	0	0	240	0	0		
175	0	0	290	0	0		
200	0	0	340	0	0		
250	0	0	390	0	0		
200							

* Please refer to P. 144 for more information regarding the maintenance cables.

Cable Code

4 Options

Name	Option Code	Reference Page
Brake	В	See P.105
Cable exit direction (Outside)	CJ0	See P.105
Motor side-mounted to the left	ML	See P.109
Motor side-mounted to the right	MR	See P.109
High-rigidity (Double-block guide)	DB	See P.105
Non-motor end specification	NM	See P.110

When selecting multiple options, please list them in alphabetical order. (e.g. B-CJB-NM)

Actuator Specifications

③ Cable Length Cable Type

Standard

Specified Length

Robot Cable

P (1m) S (3m) M (5m)

X06 (6m) ~**X10** (10m) **X11** (11m) ~**X15** (15m)

X16 (16m) ~X20 (20m) R01 (1m) ~R03 (3m) R04 (4m) ~R05 (5m) R06 (6m) ~R10 (10m)

R11 (11m) ~R15 (15m) R16 (16m) ~R20 (20m)

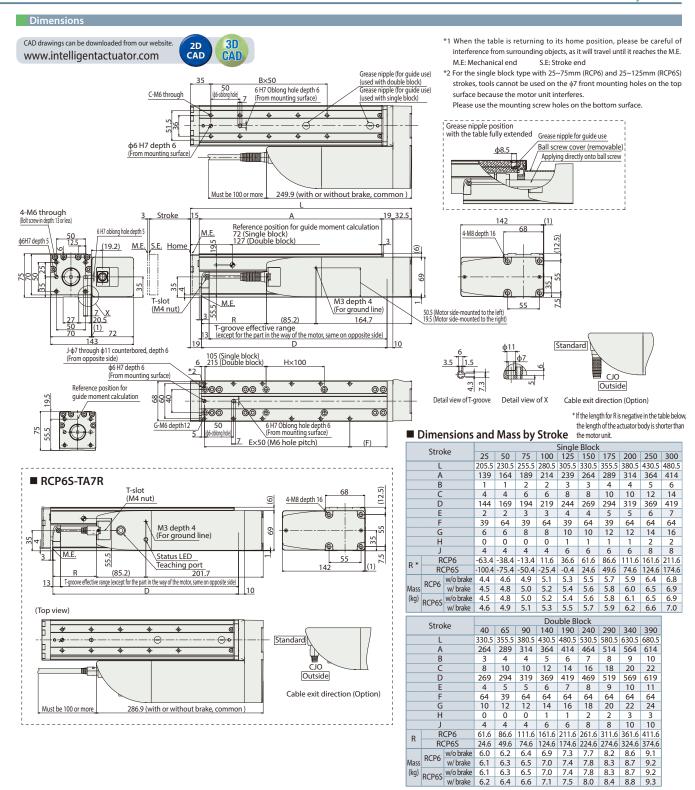
Item		Description		
Drive system		Ball screw ф12mm, rolled C10		
Positioning repeatability		±0.01mm		
Lost motion		0.1mm or less		
Base		Material: Aluminum with white alumite treatment		
Static allowable moment	Single block	Ma: 115N•m, Mb: 115N•m, Mc: 229N•m		
Static allowable moment	Double block	Ma: 620N•m, Mb: 620N•m, Mc: 458N•m		
Dimensis allowable means out (*)	Single block	Ma: 44.7N•m, Mb: 44.7N•m, Mc: 89.1N•m		
Dynamic allowable moment (*)	Double block	Ma: 196N•m, Mb: 196N•m, Mc: 145N•m		
Ambient operating temp. & humidity		0~40°C, 85% RH or less (Non-condensing)		

(*) Assumes a standard rated life of 5,000km. The service life will vary depending on operation and installation conditions.

Please refer to our website for more information regarding the directions of the allowable

moment and overhang load length.

Please refer to RCP6 instruction manual regarding the displacement of the table.



	Max. number of		r. Please select the type depending on your intended use. * Please refer to P.147 for m Control method			Maximum number				
Name	view	controlled axes	Input power	Positioner	Pulse train	Program	Networ	k *Option	of positioning points	Reference page
PCON-CB/CGB		1	DC24V	• *Option	● *Option	-	DeviceNet	Ether Net / IP	512 (768 for network spec.)	Please see P.131
MCON-C/CG	1111	4	DC24V		This model i rk-compatib		CompoNet Note: The type of compatible networks		256	Please see the MCO catalog.
MSEL-PC/PG		4	Single-phase 100~230VAC	_	-	•	will vary deper controller.	ing on the	30,000	Please see the MSE PC/PG catalog.