Battery-Body Width Motor **24**_v 70 mm Side-mo Steppe Absolute Type Moto Body width does not include the width of the side ■ Model RA7R -WA **56P** Specification mounted motor Applicable Controller/I/O Type Encoder Type — Motor Type Stroke Cable Length Options Items [RCP6] P3: PCON N : None P : 1m Please refer to the options table below. RCP6: Separate Controller WA: Battery-less 56P: Stepper 24: 24mm 50: 50mm RCP6S: Built-in Controller Absolute Motor 16: 16mm 8: 8mm MCON MSEL [RCP6S] S : 3m M: 5m 56□ Size 300: 300mm S:3m M:5m X□□: Specified Length When ordering the side 4: 4mm (50mm increments) * RCP6 does not include a controller. RCP6S includes a built-in controller.



*Depending on the model, there may be some limitations to using the vertical, side, and ceiling mount positions Please contact IAI for more information regarding mounting positions.



(1) The maximum acceleration/deceleration is 1G for horizontal, and 0.5G for vertical use.

- (2) The actuator specification displays the payload's maximum value, but it will vary depending on the acceleration and speed. Please refer to the "Selection Guidelines" (RCP6 Tables of Payload by Speed/Acceleration) on P.115 for more details.
- (3) The value of the horizontal payload assumes that there is an external guide. Please be aware that the anti-rotation stopper can be damaged when an external force is applied to the rod from any direction other than the moving direction.
- 4) When performing push-motion operation, please confirm the push force of each model by checking the "Correlation diagram of push force and current limit" on P.113.
- (5) Depending on the ambient operational temperature, duty control is necessary for the RCP6S (built-in controller type) with lead 4/8/16. Please refer to P.130 for more information.

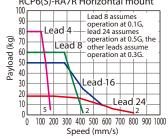
Correlation Diagrams of Speed and Payload

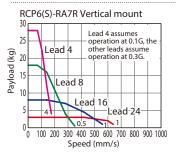
mounted motor typ

High-output enabled with PCON/MCON/MSEL connected. RCP6(S)-RA7R Horizontal mount

R□□: Robot Cable

SE: SIO Type





Actuator Specifications

■ Lead and Payload

Model Number	Lead (mm)	Connected Controller		ayload Vertical (kg)	Stroke (mm)
RCP6(S)-RA7R-WA-56P-24-①-②-③-④	24	High-output Enabled	20	3	
RCP6(S)-RA7R-WA-56P-16-①-②-③-④	16	High-output Enabled	50	8	50~300 (The increment
RCP6(S)-RA7R-WA-56P-8-①-②-③-④	8	High-output Enabled	60	18	of stroke is 50mm)
RCP6(S)-RA7R-WA-56P-4-①-②-③-④	4	High-output Enabled	80	28	

Legend: ① Stroke ② Applicable controller/I/O type ③ Cable length ④ Options

		■ Str	oke and Ma	ıx. Speed	(Unit: mm/s)		
		Lead (mm)	Connected Controller	50~300 (Every 50mm)			
		24	High-output Enabled	800 <640>			
) ent	16	High-output Enabled					
S		8	High-output Enabled	420 <350>			
	4	High-output Enabled	175				

Values in brackets < > are for vertical use.

U Stroke					
		1	,		
Stroke (mm)	RCP6	RCP6S	Stroke (mm)	RCP6	RCP6S
50	0	0	200	0	0
100	0	0	250	0	0
150	0	0	300	0	0

Options

Name	Option Code	Reference Page
Brake	В	See P.105
Cable exit direction (Outside)	CJO	See P.105
Flange	FL	See P.106
Foot bracket	FT	See P.107
Motor side-mounted to the left	ML	See P.109
Motor side-mounted to the right	MR	See P.109
Motor side-mounted to the top	MT	See P.109
Tip adapter (Internal thread)	NFA	See P.109
Non-motor end specification	NM	See P.110
T-slot nut bar	NTB	See P.110

When selecting multiple options, please list them in alphabetical order. (e.g. B-CJB-NM)

③ Cable Length						
Cable Type	Cable Code	RCP6	RCP6S			
	P (1m)	0	0			
Standard	S (3m)	0	0			
	M (5m)	0	0			
	X06 (6m) ~X10 (10m)	0	0			
Specified Length	X11 (11m) ~X15 (15m)	0	0			
	X16 (16m) ~X20 (20m)	0	0			
	R01 (1m) ~R03 (3m)	0	0			
Robot Cable	R04 (4m) ~R05 (5m)	0	0			
	R06 (6m) ~R10 (10m)	0	0			
	R11 (11m) ~R15 (15m)	0	0			
	R16 (16m) ~R20 (20m)	Ó	Ó			

* Please refer to P.144 for more information regarding the maintenance cables.

Actuator Specifications

ltem	Description
Drive system	Ball screw \phi12mm, rolled C10
Positioning repeatability	±0.01mm
Lost motion	0.1mm or less
Rod	φ30mm Material: Aluminum with hard alumite treatment
Static allowable torque on rod tip	2.5N•m
Max. angular displacement on rod tip (*1)	±0.8 deg.
Ambient operating temp. & humidity	0~40°C, 85% RH or less (Non-condensing)

(*1) This is the displacement angle of the rod tip (initial reference value) when the rod is fully retracted and the static allowable torque is applied at the rod tip.

Dimensions *1 When the rod is returning to its home position, please be careful of interference from CAD drawings can be downloaded from our website surrounding objects, as it will travel until it reaches the M.E. www.intelligentactuator.com M.E: Mechanical end S.E: Stroke end *2 The direction of width across flats varies depending on the product. Grease nipple (ϕ 5 hole) (Top and side) Supplied hex nut Must be 100 or more The orientation of the width across flats is indeterminable (*2) 249.9 (same as the type with brake) 4-M8 depth 16 164.7 4-M8 depth 16 M.E./ S.E. Home/ M.E. **(** 452 h7 430 M3 depth 4 (For ground line) 53.5 (Motor side-mounted to the left) 22.5 (Motor side-mounted to the right), M14×1.5 9.5 Stroke Cable exit direction (Option) Detail view of P * The figure above is the motor side-mounted to the left (ML). ■RCP6S-RA7R Ð 0 Cable exit direction (Option) Must be 100 or more * The figure above is the motor side-mounted to the left (ML). 286.9 (same as the type with brake) 244.8 201.7 M3 depth 4 (For ground line) 4-M8 depth 16

Teaching port

■ Dimensions and Mass by Stroke

	Strok	e	50	100	150	200	250	300
L			230	280	330	380	430	480
A			197.5	247.5	297.5	347.5	397.5	447.5
	IP6	-19.9	30.1	80.1	130.1	180.1	230.1	
	RCP6S		-56.9	-6.9	43.1	93.1	143.1	193.1
	Mass RCP6	w/o brake	5.1	5.7	6.3	6.9	7.5	8.1
Mass		w/brake	5.2	5.8	6.4	7.0	7.6	8.2
(kg)	RCP6S	w/o brake	5.2	5.8	6.4	7.0	7.6	8.1
		w/brake	5.3	5.9	6.5	7.1	7.7	8.2

Note: * If the length for R is negative in the table below, the length of the actuator body is shorter than the motor unit.

he RCP6 series actuators ca	in be operated by	the controlle	ers indicated below	. Please select t	he type depend	ing on your inte	ended use. * Please i	refer to P.147 for mo	re information about the buil	t-in controller of RCP6S series
	External view	Max. number of controlled axes		Positioner	Pulse train	Control me		k *Option	Maximum number of positioning points	Reference page
PCON-CB/CGB	1	1		• *Option	• *Option	-	DeviceNet	Ether CAT.	512 (768 for network spec.)	Please see P.131
MCON-C/CG	1111	4	DC24V		This model is vork-compatible only.		CompoNet Note: - The type of compatible networks		256	Please see the MCON catalog.
MSEL-PC/PG	1	4	Single-phase 100~230VAC	_	-	•	will vary depen controller.	ding on the reference page for	30,000	Please see the MSEL PC/PG catalog.

53.5 (Motor side-mounted to the left) 22.5 (Motor side-mounted to the right)