# **P5-RA8R**

ROBO Cylinder, High-thrust Rod Type, Side-mounted Motor Type, Actuator Width 88mm, 24V Pulse Motor

■Model RCP5—RA8R— **60P P4** WA Applicable controller Specification Туре - Encoder type -Motor type Stroke Cable length Options Items WA: Battery-less 60P: Pulse motor, P4: PCON-CFA N: No cable 20: 20mm 50: 50mm Please refer to P: 1m S: 3m the options table below. absolute size 60□ 10: 10mm specification 700: 700mm 5: 5mm (Every 50mm) M: 5m X□□: Specified length \*Controller is not included. R□□: Robot cable

## **Radial Load Applicable**

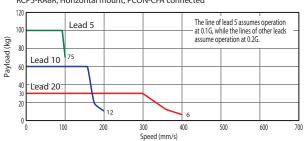


The figure above is the motor side-mounted to the left (ML).

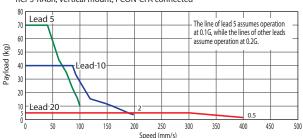
- (1) The payload assumes operation at an acceleration of 0.1G for lead 5 and operation at an acceleration of 0.2G for lead 10 and lead 20. The above values are the upper limits of acceleration/ deceleration.
- Please note that the RA8R requires a dedicated controller (high-thrust PCON-CFA).
- The radial cylinder is equipped with a built-in guide. Please refer to the graphs shown in P. 65 and after for the allowable load mass.

### ■Correlation Diagrams of Speed and Payload

RCP5-RA8R, Horizontal mount, PCON-CFA connected



#### RCP5-RA8R, Vertical mount, PCON-CFA connected



## Actuator Specifications

#### ■Lead and Payload

Model number		Connected	Maximun		Maximum	Stroke
Model Hamber	(mm)	controller	Horizontal (kg)	Vertical (kg)	push force (N)	(mm)
RCP5-RA8R-WA-60P-20-①-P4-②-③	20	PCON-CFA	30	5	500	
RCP5-RA8R-WA-60P-10-①-P4-②-③	10	PCON-CFA	60	40	1,000	50~700 (Every 50mm)
RCP5-RA8R-WA-60P-5-①-P4-②-③	5	PCON-CFA	100	70	2,000	3011111)

Legend:	1 Stroke	2 Cable length	Options	*Please refer to P. 59 for push-motio	n operation.
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#### ■Stroke and Maximum Speed

/1	In	i+-	m	m

Lead (mm)	50 (mm)	100~450 (mm)	500 (mm)	550 (mm)	600 (mm)	650 (mm)	700 (mm)
20			360	320	280	240	220
10			180	160	140	120	110
5	10	00	90	80	70	60	55

## ① Stroke

Stroke (mm)	Standard price	Stroke (mm)	Standard price
50	-	400	-
100	-	450	-
150	-	500	-
200	-	550	-
250	=	600	-
300	-	650	-
350	-	700	-

#### ② Cable Length

Type	Cable code	Standard price
	<b>P</b> (1m)	-
Standard type	<b>S</b> (3m)	-
	<b>M</b> (5m)	-
Special length	X06 (6m) ~X10 (10m)	-
	X11 (11m)~X15 (15m)	-
	X16 (16m)~X20 (20m)	-
	R01 (1m) ~R03 (3m)	-
	R04 (4m) ~R05 (5m)	-
Robot cable	R06 (6m) ~R10 (10m)	-
	R11 (11m)~R15 (15m)	-
	R16 (16m)~R20 (20m)	-
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<sup>\*</sup>Please refer to P. 89 for maintenance cables.

#### ③ Options

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Name	Option code	Reference page	Standard price
Brake	В	→P. 11	-
Cable exit direction (Top)	CJT	→P. 11	-
Cable exit direction (Outside)	CJO	→P. 11	-
Cable exit direction (Bottom)	CJB	→P. 11	-
Motor side-mounted to the left (Standard)	ML	→P. 11	-
Motor side-mounted to the right	MR	→P. 11	-
Flange	FL	→P. 12	-
Non-motor end specification	NM	→P. 11	-

#### **Actuator Specifications**

ltem	Description
Drive system	Ball screw Ø16mm, rolled C10
Positioning repeatability	±0.02mm
Lost motion	0.1mm or less
Rod	Ø40mm Aluminum
Rod non-rotation precision (*1)	0 deg.
Allowable load and torque on rod tip	Refer to table in the page on the right, refer to P. 65
Rod tip overhang distance	100mm or less
Ambient operating temperature, humidity	0 to 40°C, 85% RH or less (Non-condensing)

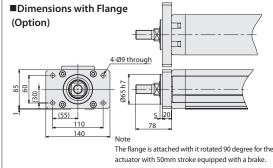
<sup>(\*1)</sup> Rod's angular displacement in rotational direction with no applied load is shown.

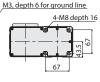




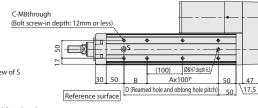
- om our website. www.intelligentactuator.com \*1 When the rod is returning to its home position, please be careful of interference
- from surrounding objects, as it will travel until it reaches the ME.
  \*2 The direction of width across flats varies depending on the product.
- \*3 If the actuator is installed using the front housing and flange, make sure the actuator will not receive any external force. ME: Mechanical end SE: Stroke end

Grease nipple M20x1.5 Supplied hex nut on rod tip 4-M8 depth 16 35 (effective thread) 12 (width across flats) st+212.5

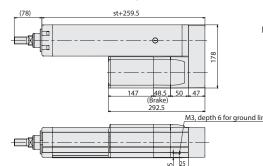




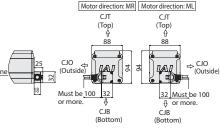




#### ■Dimensions with Brake (Option)



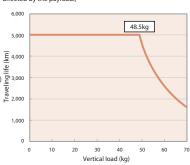
#### ■3 Cable Exit Directions (Option)



#### Note

If an actuator with lead 5 is installed vertically, the service life  $\,$ of the actuator varies significantly depending on its payload. \\ Please refer to the correlation diagram of vertical load and traveling life shown below.

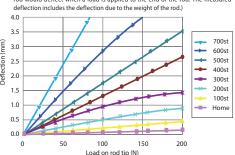
(If the actuator is installed horizontally, its service life is not affected by the payload.)



### ■Rod Deflection of RCP5-RA8R

(The graph below shows the measurements of how much a horizontally installed rod would deflect when a load is applied to the end of the rod. The measured

Dimensions and Mass by Stroke



	Stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700
	L	309.5	359.5	409.5	459.5	509.5	559.5	609.5	659.5	709.5	759.5	809.5	859.5	909.5	959.5
	A	0	1	1	2	2	3	3	4	4	5	5	6	6	7
	В	115	65	115	65	115	65	115	65	115	65	115	65	115	65
	С	4	6	6	8	8	10	10	12	12	14	14	16	16	18
	D	115	165	215	265	315	365	415	465	515	565	615	665	715	765
	atic load on rod tip (N)	180	150.3	128.9	112.7	99.9	89.7	81.3	74.3	68.3	63.1	58.6	54.6	51.1	47.9
Allowable dynamic load	Load offset 0mm	73.6	60.3	51.0	44.1	38.7	34.3	30.7	27.7	25.2	23.0	21.1	19.4	17.8	16.5
on rod tip (N)		57.0	48.6	42.5	37.8	33.8	30.5	27.6	25.2	23.1	21.2	19.5	18.1	16.7	15.5
Allowable stati	c torque on rod tip (N•m)	18.1	15.2	13.0	11.4	10.2	9.2	8.4	7.7	7.1	6.6	6.1	5.8	5.4	5.1
Allowable dynamic torque on rod tip (N+m)		5.7	4.9	4.3	3.8	3.4	3.0	2.8	2.5	2.3	2.1	2.0	1.8	1.7	1.5
Mass (kg)	Without brake	8.6	9.0	9.4	9.8	10.3	10.7	11.1	11.6	12.0	12.4	12.9	13.3	13.7	14.1
iviass (kg)	With brake	9.6	10.0	10.4	10.9	11.3	11.7	12.2	12.6	13.0	13.4	13.9	14.3	14.7	15.2

#### Applicable Controllers

The RCP5 series actuators can be operated by the controllers indicated below. Please select the type depending on your intended use

		**·				
Name	External view	Model number	Maximum number of positioning points	Input power	Standard price	Reference page
Positioner type	*	PCON-CFA-60PWAI-NP-2-0 PCON-CFA-60PWAI-PN-2-0	512 points		-	
Pulse-train type		PCON-CFA-60PWAI-PLN-2-0 PCON-CFA-60PWAI-PLP-2-0	_	DC24V	-	→P. 69
Field network type	PCON-CFA-60PWAI-①-0-0		768 points		-	

<sup>\*</sup>① Field network specification code (DV, CC, PR, CN, ML, EC, EP)